

POSITAL FRABA

POSITION AND MOTION SENSORS







GLOBAL PRESENCE





COMPANY



FRABA Group

FRABA is a group of enterprises focused on providing advanced products for the motion control and industrial automation markets. POSITAL has been a leading manufacturer of absolute rotary encoders for over 50 years and recently has expanded its business to inclination and linear sensors. Other FRABA Group subsidiaries include VITECTOR which focuses on protection sensors to guard doors and production machine covers.

History

FRABA was founded by Franz Baumgartner in 1918. Until the 1960s, FRABA's main product was mechanical relays. In 1963 FRABA started selling "brush" absolute encoders and in 1973 one the first non-contact, optical absolute rotary encoders was manufactured in the offices of FRABA in Cologne. Today, FRABA companies specialize in innovative products that use advanced technologies to deliver exceptional performance and value.





Service

Absolute rotary encoders are sophisticated devices that can help solve a wide range of technical problems. However, realizing the full potential of these products may require specialized knowledge when selecting the device configuration and programming the operating parameters. To ensure that customers get what they need, POSITAL's development engineers in Germany, the US and Asia have direct responsibility for customer support. In addition, a growing global network of sales partners is providing expert guidance with knowledge about the local requirements.

Production

POSITAL products are manufactured in advanced production facilities. The computer-guided semiautomated production system tracks each device from order, through assembly and testing, to final delivery. Even with thousands of unique configurations available, standard products are ready to ship within five working days of receiving an order.





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PRODUCTS





IXARC Rotary Encoders

Motion control applications – ranging from factory automation to mobile machinery – require accurate, realtime information about the location of mechanical equipment. The IXARC line of absolute rotary encoders provide precise and reliable measurement of the angular positions of joints, drive shafts, pulleys, etc... Available electronic connections range from simple analog outputs to sophisticated fieldbus and Industrial Ethernet interfaces.

TILTIX Inclinometers

Accurate measurement of tilt or inclination is very important for motion control and safety systems. Inclinometers provide single or dual-axis angle measurement in an economical package. Relying on gravity for their measurement, these sensors have no exposed moving parts, resulting in easy mounting and high environmental protection.

LINARIX Linear Sensors

Many applications require linear motion to be monitored for system control or to ensure safety. With lengths ranging from 1 m to 10 m (3' to 33'), LINARIX draw wire sensors are available in many configurations to meet an application's requirements. Options include a wide variety of outputs (including analog, fieldbus and Ethernet variants), heavy duty housings and compact designs.

Accessories

POSITAL offers a wide variety of accessories that simplify sensor installation. Mating connectors of different styles and lengths ensure proper electrical connections. Using appropriate mounting accessories minimize wear and tear on encoders and help to ensure a long and reliable life cycle. Interface modules and displays are also available to provide users with immediate access to measurements.







Mining

The convergence of industrial automation with mining machinery has resulted in greatly increased efficiency and safety. Drill rigs, excavators and mobile hammering systems are complicated machines which must perform flawlessly under the harshest conditions. System failures are not only costly, but potentially harmful for operators. For these applications POSITAL IXARC rotary encoders can be used to provide precise positioning of drill heads and masts. Single and dual axis POSITAL TILTIX inclinometers further equip operators with essential information for platform leveling and arm positioning. Combined in CANopen and SAE J1939 networks, these devices can help automate and monitor highly complex tasks.

Cranes

Cranes and other material handling equipment are required to be safe, efficient and reliable. Positioning is of prime importance, and redundant systems are often used to eliminate errors. To address this requirement the IXARC SIL-2 encoders are an excellent fit, combining redundant measurement with an easy-to-integrate interface. For boom extensions and height measurements, LINARIX linear sensors are economical, compact and highly tolerant of condensation, shock and vibration.

Concrete Pumps

Concrete trucks have to feed fresh concrete to highrise construction sites, often over large obstacles. These pathways have many joints and axes of rotation, making the task only more daunting. IXARC rotary encoders mounted directly on rotational joints provide data for active damping systems. The position of boom arms can also be monitored using TILTIX single-axis inclinometers, while dual-axis models are useful for base leveling. With IP69K ratings, IXARC encoders and TILITX inclinometers are built to withstand the high temperature, high pressure washdowns that are necessary to maintain these trucks.













Wind Energy

IXARC heavy duty absolute encoders provide precise angle measurements for pitch control systems that dynamically adjust the angle of the rotor blades. High resolution encoders are a great choice for positioning the nacelle with respect to wind direction.

Solar Energy

For both photovoltaic systems and solar thermal power plants (parabolic), solar tracking systems increase energy efficiency by optimizing the orientation of the solar collectors. Single-axis solar tracking systems typically follow the sun as it travels east to west across the sky, while two axis systems also adjust the elevation of the collectors. Compact and accurate IXARC encoders and TILTIX inclinometers are ideal for these tracking systems.

Dams and Canals

In hydroelectric dams, the precise positioning of flowgates is required to control the volume and speed of water. Simple analog control systems are often used for this task and IXARC encoders with analog interfaces provide the right mix of accuracy and compatibility.

Canal gates used in irrigation systems and lift-locks need to be precisely positioned in order to control the flow of water in the canals. Moreover, since thethese canals often extend over vast, remote areas, solar energy is sometimes used to power these control structures. IXARC absolute multiturn encoders are ideal for this application since they will retain a 'memory of their position, even when powered down. IXARC rotary encoders and TILTIX inclinometers are available with IP68 and IP69K environmental ratings for use in harsh environments. Neither type of sensor requires batteries, minimizing maintenance and increasing reliability.











Packaging

Absolute rotary encoders are essential in packaging machines. High precision is needed in processes like form filling, sealing, palletizing, pick and place, cartoning and cardboard folding. In larger lines, IXARC rotary encoders with field bus interfaces simplify wiring and keep costs down.

Stainless steel IXARC rotary encoders not only provide precise positioning, but are also able to withstand the high temperature and pressure washdowns. Since these devices retain knowledge of absolute postion during power outages, there is no need to re-home systems after power is restored.

Textile and Plastic

Textile and Plastic Manufacturing is highly processdriven with multiple stages. The material being manufactured can be changed periodically and constant adjustments need to be made in roll and nozzle positioning. IXARC absolute encoders and LINARIX linear sensors can help make these changes quickly, reducing downtime and increasing efficiency.

Food and Beverage

Bottling plants are becoming faster in response to growing global demands. Each bottle must be filled to the right level and labeled correctly. Manufactures have to comply with strict laws and hence need to pack and process these goods quickly under tight controls. IXARC encoders and LINARIX linear sensors help achieve this efficiency.









Scissor Lifts and Aerial Work Platforms

Scissor lifts needs constant tilt monitoring to prevent tip-overs. The height of the lift also needs to be known. TILTIX inclinometers and LINARIX linear sensors are perfect for such applications.

Forklifts and Automated Guided Vehicles

For forklifts and AGV's that carry loads from one point to another, safety is of utmost importance. Monitoring tilt and the height of the forks is important; TILTIX inclinometers and LINARIX linear sensors help achieve this.

Automated Storage Retrieval Systems

Increasing warehouse and labor costs make the use of automatic storage and retrieval systems economically attractive. IXARC absolute encoders and LINARIX linear sensors are used in these systems to give the position of the trays with respect to the vertical racks where goods are placed.

Overhead Conveyors

Assembly lines for automotive production have dedicated work stations for different processes. Typically the vehicle chassis is moved through a series of such work stations using overhead conveyors. IXARC absolute encoders help achieve this movement in a safe and controlled manner.

Baggage Handling

Due to stringent security requirements, all airline baggage needs to be screened and distributed in a secure manner. A labyrinth of conveyors helps sort these in a correct fashion. IXARC field bus encoders help track the position of multiple baggage conveyors. Simplified wiring, programmability and diagnostic LEDs reduce system installation time and cost.









Healthcare

Modern devices used in the healthcare industry demand advanced technology for precise positioning. TILTIX compact inclinometers provide accurate measurements and are built to last the life of the equipment. LINARIX linear sensors offer a solution for tracking the position of patient tables. For more complex applications, such as fluoroscopy or radiography tables or surgical C-arms, that require coordinated positioning of several components, IXARC absolute rotary encoders are an excellent option.

Elevators

Elevator cars need to be accurately positioned with respect to each floor they visit. IXARC absolute encoders help provide this information without the need of a ground reference. With IXARC absolute encoders, knowledge of the position of the elevator car is alwoays retained, even during power failures. IXARC encoders supporting the CANopen Lift protocol help meet the high safety standards of this industry. Cost efficient LINARIX linear sensors provide door positioning.



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ABSOLUTE VS INCREMENTAL ENCODERS





Encoder Fundamentals

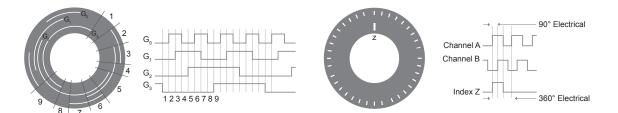
Positioning tasks require precise position values to monitor or control motion activity. In many applications position sensing is done using rotary encoders, also called shaft encoders or simply encoders. These sensors transform a mechanical angular position of a shaft or axle into an electronic signal that can be processed by a control system.

Absolute Rotary Encoders

Absolute rotary encoders are capable of providing unique position values from the moment they are switched on. This is accomplished by scanning the position of a coded element. All positions in these systems correspond to a unique code. Even movements that occur while the system is without power are translated into accurate position values once the encoder is powered up again.

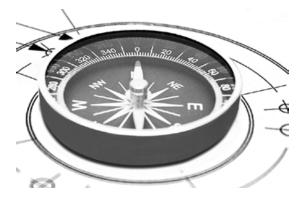
Incremental Rotary Encoders

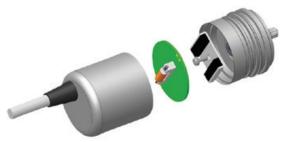
Incremental encoders generate an output signal each time the shaft rotates a certain amount. (The number of signals per turn defines the resolution of the device.) Each time the encoder is powered on it begins counting from zero, regardless of where the shaft is. Initial homing to a reference point is therefore inevitable in all positioning tasks, both upon start up of the control system and whenever power to the encoder has been interrupted.





TECHNOLOGY IXARC ENCODERS





Magnetic Measurement Principles

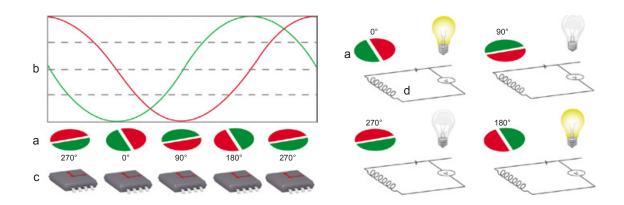
Magnetic rotary encoders determine angular position using magnetic field sensor technology. A permanent magnet (a) fixed to the encoder's shaft creates a magnetic field (b) that is sampled by a sensor (c) that generates a unique absolute position reading.

Multiturn Innovation

POSITAL's IXARC multiturn magnetic rotary encoders use an innovative technology to keep track of the number of rotations that the encoder has experienced, even if the rotations occur when there is no system power. To accomplish this, the encoders generate electrical energy from the rotation of the encoder shaft. The technology is based on the 'Wiegand effect': when a permanent magnet (a) on the encoder shaft rotates through a certain angle, the magnetic polarity in a 'Wiegand wire' suddenly changes, inducing a brief voltage spike in a coil (d) surrounding the wire. This pulse both marks a rotation of the shaft and powers the electronic circuitry that records the event. The Wiegand effect occurs reliably even with very slow rotations and eliminates the need for backup batteries.

Advantages of Magnetic Encoders

Magnetic encoders are robust, durable and compact. Their battery and gearless construction makes them mechanically simple and economical as compared to optical encoders. Their compact dimensions mean that they can be used in applications with very limited installation space.





TECHNOLOGY IXARC ENCODERS



Optical Measuring Principles

A key component of optical rotary encoders is a code disk (a) mounted on the encoder shaft (b). This disk is made of a transparent material that has a concentric pattern of transparent and opaque areas. Infrared light from an LED (c) shines through the code disk, onto an array of photoreceptors (d). As the shaft turns, a unique combination of photoreceptors are illuminated or blocked from light by the pattern on the disk. For multiturn models, there is an additional set of code discs arranged in a gear train (e). As the main encoder shaft rotates, these discs are geared together to turn like the wheels of an odometer. The rotational position of each disc is monitored optically and the output is a count of the net number of rotations of the encoder shaft.

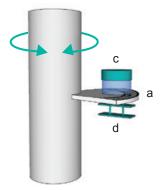


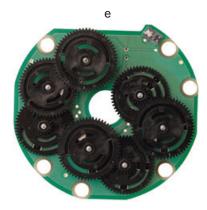
Functionality

POSITAL's IXARC optical absolute rotary encoders use highly integrated Opto-ASICs, providing a resolution up to 16 bits (65,536 steps) per turn. For multiturn models, the measuring range is extended by the mechanically geared code disks to as many as 16,384 (2¹⁴) revolutions.

Advantages of Optical Encoders

Optical encoders provide very high resolution and accuracy along with excellent dynamic response and are suitable for use in areas with high magnetic fields. Since the rotation of the code discs is an entirely mechanical process, there is no risk of these devices losing track of their absolute position due to a temporary loss of instrument power. No backup batteries are required!







IP68 – IP69K Encoders with Analog and SSI Interfaces



Highlights	Magnetic	Magnetic	Magnetic	Magnetic
	SSI, Ø 42 mm	SSI, Ø 36 mm	Analog, Ø 42 mm	Analog, Ø 36 mm
	300 N Shaft Load	IP69K	300 N Shaft Load	IP69K
Protection Class	IP69K	IP69K	IP69K	IP69K
Communication	SSI	SSI	Analog Voltage,	Analog Voltage,
Interface			Current	Current
Technology	Magnetic	Magnetic	Magnetic	Magnetic
Revolutions (Turns)	Up to 65536	Up to 65536	Up to 32768	Up to 32768
Resolution	Up to 14 bit (0.022°)	Up to 14 bit (0.022°)	Total 12 bit (0.088°)	Total 12 bit (0.088°)
Accuracy /	±0.35°	±0.35°	±0.35° /	±0.35° /
Linearity			0.05 %	0.05 %
Flange Size	Ø 42 [1.65]	Ø 36 [1.42]	Ø 42 [1.65]	Ø 36 [1.42]
in mm [in]				
Flange Design	Synchro	Synchro	Synchro	Synchro
Shaft Diameters	Ø 10 [0.39]	Ø 10 [0.39]	Ø 10 [0.39]	Ø 10 [0.39]
in mm [in]				
Material Flange /	Stainless Steel (V2A) /	Aluminum /	Stainless Steel (V2A) /	Aluminum /
Housing	Stainless Steel (V2A)	Steel	Stainless Steel (V2A)	Steel
RPM /	Max. 6000 /	Max. 6000 /	Max. 6000 /	Max. 6000 /
Radial Shaft Load	300	180	300	180
in N				
Shock /	300 g /	300 g /	300 g /	300 g /
Vibration ¹⁾	30 g	30 g	30 g	30 g
Temperature	-40 to +85	-40 to +85	-40 to +85	-40 to +85
in°C [°F] /	[-40 to +185]/	[-40 to +185] /	[-40 to +185] /	[-40 to +185] /
Humidity	98 %	98 %	98 %	98 %
Connection Type	Connector /	Connector /	Connector /	Connector /
	Cable Gland	Cable Gland	Cable Gland	Cable Gland
Supply Voltage	4.5 to 30 V	4.5 to 30 V	12 to 30 V	12 to 30 V
Certificate	UL, CE	UL, CE	UL, CE	UL, CE
Туре Кеу	MCD-SG10G	MCD-SD10D	MCD-AG10G	MCD-AD10D

1) Based on (EN 60068-2-27) / (EN 60068-2-6)



IP68 – IP69K Encoders with Bus Interfaces







Highlights	Magnetic	Optical	Magnetic
	Bus Interfaces, Ø 36 mm	Bus Interfaces	Bus Interfaces, Ø 42 mm
	IP69K	Up to 16 bit	300 N Shaft Load
Protection Class	IP69K	IP68	IP69K
Communication Interface	DeviceNet, CANopen,	DeviceNet, CANopen,	DeviceNet, CANopen,
	CANopen Lift, SAE J1939	CANopen Lift, SAE J1939	CANopen Lift, SAE J1939
Technology	Magnetic	Optical	Magnetic
Revolutions (Turns)	Up to 65536	Up to 16384	Up to 65536
Resolution	Up to 14 bit (0.022°)	Up to 16 bit (0.005°)	Up to 14 bit (0.022°)
Accuracy	±0.35°	±0.022°	±0.35°
Flange Size in mm [in]	Ø 36 [1.42]	Ø 58 [2.28]	Ø 42 [1.65]
Flange Design	Synchro	Synchro, Clamp,	Synchro
		Blind Hollow	
Shaft Diameters in mm [in]	Ø 10 [0.39]	Shaft Ø 10 [0.39]	Ø 10 [0.39]
		Hub Ø 6 to 15 [0.24 to 0.59]	
Material Flange /	Aluminum /	Aluminum /	Stainless Steel (V2A) /
Housing	Steel	Aluminum	Stainless Steel (V2A)
RPM /	Max. 6000 /	Max. 6000 /	Max. 6000 /
Radial Shaft Load in N	180	110	300
Shock /	300 g /	100 g /	300 g /
Vibration ¹⁾	30 g	10 g	30 g
Temperature	-40 to +85	-40 to +85	-40 to +85
in °C [°F] /	[-40 to +185] /	[-40 to +185] /	[-40 to +185] /
Humidity	98 %	98 %	98 %
Connection Type	Connector /	Connector /	Connector /
	Cable Gland	Cable Gland	Cable Gland
Supply Voltage	4.5 to 30 V	4.5 to 30 V	4.5 to 30 V
Certificate	UL, CE	UL, CE	UL, CE
Туре Кеу	MCD-C/DD10D	OCD-C/D	MCD-C/DH

1) Based on (EN 60068-2-27) / (EN 60068-2-6)



Encoders with Analog, SSI, Bit Parallel and Incremental Interfaces



Highlights	Optical SSI	Optical SSI + Incremental	Magnetic SSI	Optical Parallel Output	Magnetic Programmable
	Up to 16 bit	Up to 16 bit	Ø 36 mm	Up to 16 bit	Analog
Protection Class	Up to IP67	Up to IP67	Up to IP65	Up to IP67	Up to IP65
Communication Interface	SSI	SSI + Incremental	SSI	Parallel	Analog Voltage, Current
Technology	Optical	Optical	Magnetic	Optical	Magnetic
Revolutions (Turns)	Up to 16384	Up to 16384	Up to 65536	Up to 16384	Up to 32768
Resolution	Up to 16 bit (0.005°)	Up to 16 bit (0.005°)	Up to 14 bit (0.022°)	Up to 16 bit (0.005°)	Total 12 bits (0.088°)
Accuracy / Linearity	±0.022°	±0.022°	±0.35°	±0.022°	±0.35° / 0.05 %
Flange Size in mm [in]	Ø 58 [2.28]	Ø 58 [2.28]	Ø 36 [1.42] Ø 58 [2.28]	Ø 58 [2.28]	Ø 36 [1.42] Ø 58 [2.28]
Flange Design	All	All	All	All	All
Shaft Diameters	Ø 6 to 15	Ø 6 to 15	Ø 6 to 15	Ø 6 to 15	Ø 6 to 15
in mm [in]	[0.24 to 0.59]	[0.24 to 0.59]	[0.24 to 0.59]	[0.24 to 0.59]	[0.24 to 0.59]
Material Flange /	Aluminum or	Aluminum or	Aluminum /	Aluminum or	Aluminum /
Housing	Stainless Steel / Steel	Stainless Steel / Steel	Steel	Stainless Steel / Steel	Steel
RPM /	Max. 12000 /	Max. 12000 /	Max. 12000 /	Max. 12000 /	Max. 12000 /
Radial Shaft Load in N	110	110	110	110	110
Shock /	100 g /	100 g /	100 g /	100 g /	100 g /
Vibration ¹⁾	10 g	10 g	10 g	10 g	10 g
Temperature	-40 to +85	-40 to +85	-40 to +85	-40 to +85	-40 to +85
in °C [°F] /	[-40 to +185] /	[-40 to +185] /	[-40 to +185] /	[-40 to +185] /	[-40 to +185] /
Humidity	98 %	98 %	98 %	98 %	98 %
Connection Type	Connector /	Connector /	Connector /	Connector /	Connector /
	Cable Gland	Cable Gland	Cable Gland	Cable Gland	Cable Gland
Supply Voltage	4.5 to 30 V	4.5 to 30 V	4.5 to 30 V	4.5 to 30 V	12 to 30 V
Certificate	UL, CE	UL, CE	UL, CE	UL, CE	UL, CE
Туре Кеу	OCD	OCD	MCD	OCD	MCD

1) Based on (EN 60068-2-27) / (EN 60068-2-6)



Encoders with Bus Interfaces



Highlights	Optical	Optical	Magnetic	Optical	Magnetic
	PROFIBUS	Bus Interfaces	Bus Interfaces	DeviceNet	DeviceNet
	Up to 16 bit	Up to 16 bit	Ø 58 mm	Up to 16 bit	Ø 36 mm
Protection Class	Up to IP67	Up to IP67	Up to IP65	Up to IP67	Up to IP65
Communication	PROFIBUS DPV0 /	CANopen,	CANopen,	DeviceNet	DeviceNet
Interface	DPV1 / DPV2	CANopen Lift	CANopen Lift		
Technology	Optical	Optical	Magnetic	Optical	Magnetic
Revolutions (Turns)	Up to 16384	Up to 16384	Up to 65536	Up to 16384	Up to 65536
Resolution	Up to 16 bit	Up to 16 bit	Up to 14 bit	Up to 16 bit	Up to 14 bit
	(0.005°)	(0.005°)	(0.022°)	(0.005°)	(0.022°)
Accuracy	±0.022°	±0.022°	±0.35°	±0.022°	±0.35°
Flange Size in mm [in]	Ø 58 [2.28]	Ø 58 [2.28]	Ø 58 [2.28]	Ø 58 [2.28]	Ø 36 [1.42] Ø 58 [2.28]
Flange Design	Clamp, Synchro, Blind Hollow	All	Clamp, Synchro, Blind Hollow	All	Clamp, Synchro, Blind Hollow
Shaft Diameters	Ø 6 to 15	Ø 6 to 15	Ø 6 to 15	Ø 6 to 15	Ø 6 to 15
in mm [in]	[0.24 to 0.59]	[0.24 to 0.59]	[0.24 to 0.59]	[0.24 to 0.59]	[0.24 to 0.59]
Material Flange /	Aluminum or	Aluminum or	Aluminum /	Aluminum or	Aluminum /
Housing	Stainless Steel /	Stainless Steel /	Steel	Stainless Steel /	Steel
	Steel	Steel		Steel	
RPM /	Max. 12000 /	Max. 12000 /	Max. 12000 /	Max. 12000 /	Max. 12000 /
Radial Shaft	110	110	110	110	110
Load in N					
Shock /	100 g /	100 g /	100 g /	100 g /	100 g /
Vibration ¹⁾	10 g	10 g	10 g	10 g	10 g
Temperature	-40 to +85	-40 to +85	-40 to +85	-40 to +85	-40 to +85
in °C [°F] /	[-40 to +185] /	[-40 to +185] /	[-40 to +185] /	[-40 to +185] /	[-40 to +185] /
Humidity	98 %	98 %	98 %	98 %	98 %
Connection Type	Connector /	Connector /	Connector /	Connector /	Connector /
	Connection Cap	Connection Cap	Connection Cap	Connection Cap	Connection Cap
Supply Voltage	10 to 30 V	10 to 30 V	10 to 30 V	10 to 30 V	10 to 30 V
Certificate	UL, CE	UL, CE	UL, CE	UL, CE	UL, CE
Туре Кеу	OCD	OCD	MCD	OCD	MCD

1) Based on (EN 60068-2-27) / (EN 60068-2-6)



Encoders with Ethernet Interfaces



Highlights	Optical	Optical	Optical	Optical	Optical
	Ethernet/IP	PROFINET	Modbus/TCP	POWERLINK	EtherCAT
	Up to 16 bit				
Protection Class	Up to IP67				
Communication	EtherNet/IP	PROFINET	Modbus/TCP	ETHERNET	EtherCAT
Interface				POWERLINK	
Technology	Optical	Optical	Optical	Optical	Optical
Revolutions	Up to 16384				
(Turns)					
Resolution	Up to 16 bit				
	(0.005°)	(0.005°)	(0.005°)	(0.005°)	(0.005°)
Accuracy	±0.022°	±0.022°	±0.022°	±0.022°	±0.022°
Flange Size	Ø 58 [2.28]				
in mm [in]					
Flange Design	Clamp, Synchro,				
	Blind Hollow				
Shaft Diameters	Ø 6 to 15				
in mm [in]	[0.24 to 0.59]				
Material Flange /	Aluminum or				
Housing	Stainless Steel /				
	Steel	Steel	Steel	Steel	Steel
RPM /	Max. 12000 /	Max. 12000 /	Max. 12000 /	Max. 12000 /	Max. 12000 /
Radial Shaft Load	110	110	110	110	110
in N					
Shock /	100 g /	100 g /	100 g /	100 g /	100 g /
Vibration ¹⁾	10 g				
Temperature	-40 to +85				
in °C [°F] /	[-40 to +185] /	[-40 to +185] /	[-40 to +185] /	[-40 to +185] /	[-40 to +185] /
Humidity	98 %	98 %	98 %	98 %	98 %
Connection Type	Connector	Connector	Connector	Connector	Connector
Supply Voltage	10 to 30 V				
Certificate	UL, CE				
Туре Кеу	OCD	OCD	OCD	OCD	OCD

1) Based on (EN 60068-2-27) / (EN 60068-2-6)



Explosion Proof and Safety-Certified Encoders



Highlights	ATEX Certified	ATEX Certified	ATEX Certified	SIL Certified	SIL CL 3 Certified
	Bus Encoder	SSI Encoder	Ethernet Encoder	Magnetic Encoder	Precise Encoder
Protection Class	Up to IP67	Up to IP67	Up to IP67	Up to IP67	Up to IP67
Communication	PROFIBUS,	SSI	EtherNet/IP,	CANSafe	CANSafe
Interface	CANopen,		PROFINET,	(EN50325-5)	(EN50325-5)
	DeviceNet		Modbus/TCP		
Technology	Optical	Optical	Optical	Magnetic	Optical
Revolutions	Up to 16384	Up to 16384	Up to 16384	Singleturn	Up to 16384
(Turns)					
Resolution	Up to 16 bit	Up to 16 bit	Up to 16 bit	Up to 14 bit	Up to 16 bit
	(0.005°)	(0.005°)	(0.005°)	(0.005°)	(0.005°)
Accuracy	±0.022°	±0.022°	±0.022°	±1.8° (safe)	±0.35° (safe)
Flange Size	Ø 78 [3.07]	Ø 78 [3.07]	Ø 78 [3.07]	Ø 25 [0.98]	Ø 58 [2.28]
in mm [in]				Ø 9 [0.35]	
Flange Design	Clamp, Blind	Clamp, Blind	Clamp, Blind	Synchro	Clamp, Blind
	Hollow, Synchro	Hollow, Synchro	Hollow, Synchro		Hollow, Synchro
Shaft Diameters	Shaft Ø 10 [0.39] /	Shaft Ø 10 [0.39] /	Shaft Ø 10 [0.39] /	Ø 6 [0.24]	Ø 6 to 15
in mm [in]	Hub Ø 14 [0.55]	Hub Ø 14 [0.55]	Hub Ø 14 [0.55]	Ø 10 [0.39]	[0.24 to 0.59]
Material Flange /	Aluminum or	Aluminum or	Aluminum or	Aluminum /	Aluminum /
Housing	Stainless Steel	Stainless Steel	Stainless Steel	Steel	Steel
RPM /	Max. 3000 /	Max. 3000 /	Max. 3000 /	Application	Max. 6000 /
Radial Shaft	50	50	50	Dependent	110
Load in N					
Shock /	100 g /	100 g /	100 g /	100 g /	100 g /
Vibration ¹⁾	10 g	10 g	10 g	10 g	10 g
Temperature	-40 to +75	-40 to +75	-40 to +75	-40 to +75	-30 to +70
in °C [°F] /	[-40 to +167] /	[-40 to +167] /	[-40 to +167] /	[-40 to +167] /	[-22 to +158] /
Humidity	98 %	98 %	98 %	98 %	98 %
Connection Type	Connection Cap	Connection Cap	Cable	Cable	Connector /
	with Cable Gland	with Cable Gland			Connection Cap
Supply Voltage	10 to 30 V	4.5 to 30 V	10 to 30 V	9 to 35 V	12 to 30 V
Certificate	ATEX / IECEx	ATEX / IECEx	ATEX / IECEx	SIL CL 2 and PI d	SIL CL 3 and PI e
Туре Кеу	OCE/M-	OCE/M-	OCE/M-	MCS-	OCS-

1) Based on (EN 60068-2-27) / (EN 60068-2-6)



13

14

16

Multiturn: 13 bit (8192 rev)

Multiturn: 14 bit (16384 rev)

Multiturn: 16 bit (65536 rev)

PRODUCT SELECTION GUIDE IXARC ROTARY ENCODERS

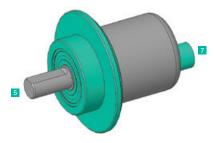
IXARC Magnetic Encoders

	0 2 8	4	6 6 7
м	c – –		
1 Certi	ficate	4 Re	esolution
D	CE/UL	10	10 bit (1024 Steps / 0.35°)
S	SIL	12	12 bit (4096 Steps / 0.088°)
2 Com	munication Interface	5 M	echanical Design
AV001	Voltage: 0 to 5 V	See r	next page for details
AVP01	Voltage: 0 to 5 V w. Pushbuttons		
AV002	Voltage: 0 to 10 V	6 Pr	otection Class
AVP02	Voltage: 0 to 10 V w. Pushbuttons	Α	IP54
AV003	Voltage: 0.5 to 4.5 V	0	IP54 to IP65
AVP03	Voltage: 0.5 to 4.5 V w. Pushbuttons	S	IP54 to IP67 (Only Clamping Flange)
AV004	Voltage: 0.5 to 9.5 V	D	IP54 to IP69K
VP04	Voltage: 0.5 to 9.5 V w. Pushbuttons	G	IP54 to IP69K (Stainless Steel)
AC005	Current: 4 to 20 mA		
ACP05	Current: 4 to 20 mA w. Pushbuttons	7 Co	onnection Type
AC006	Current: 0 to 20 mA	CAW	Cable: Axial 1 m
ACP06	Current: 0 to 20 mA w. Pushbuttons	2AW	Cable: Axial 2 m
CA00B	CANopen	5AW	Cable: Axial 5 m
CL00B	CANopen Lift	AAW	Cable: Axial 10 m
0200B	DeviceNet	CRW	Cable: Radial 1 m
C900B	J1939	2RW	Cable: Radial 2 m
S101B	SSI Binary	5RW	Cable: Radial 5 m
S101G	SSI Gray	ARW	Cable: Radial 10 m
		PAM	Connector: Axial M12 (5 pin)
Revo	plution	PAQ	Connector: Axial M12 (8 pin)
00	Singleturn	PRM	Connector: Radial M12 (5 pin)
)4	Multiturn: 4 bit (16 rev)	PRQ	Connector: Radial M12 (8 pin)
)8	Multiturn: 8 bit (256 rev)		
2	Multiturn: 12 bit (4096 rev)		



PRODUCT SELECTION GUIDE IXARC ROTARY ENCODERS

Mechanical Design 5 and Connection Type Z



5 Synchro Flange (R)

Туре R06 R10

,	
[1.44] ø36.50 d	

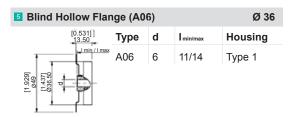
5

		Ø 36
d	I	Housing
6	10	Туре 1
10	12	Туре 1

			Ø 58
Туре	d	Ι	Housing
L06	6	10	Туре 3
L10	10	20	Туре 3
L12	12	20	Туре 3
	Type L06 L10	Type d L06 6 L10 10	Type d I L06 6 10 L10 10 20

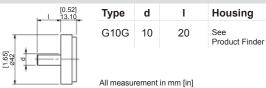
5 Clamp Flange (M)			Ø 58
[0.59]	Туре	d	I	Housing
0.228]	M06	6	10	Type 1
	M10	10	20	Type 1
	M12	12	20	Type 1

Blind Hollow Fla		Ø 36 / Ø 42		
[0.72] -18.2 -18.2 -18.2 -18.2 -18.2 -18.2 -18.2 -18.2 -18.2 -18.2 -18.2 -18.2 -18.2 -18.2 -18.2 -18.2 -18.2 -18.2 -18.2 	Туре	d	min/max	Housing
	V06	6	12/18	Type 1
	V08	8	12/18	Type 1
	V10	10	12/18	Type 1
	V12	12	12/18	Type 1



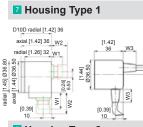
5 Synchro HD Flan	Ø 36			
[0.79] 20	Туре	d	I	Housing
	D10D	10	20	Type 2

5 Synchro Stainloss	Stool Flange	(G10G)	Ø 42
Synchro Stainless	Steer Flange	(0100)	Ø 42



Synchro Flange (Y)Ø 58					
[0.53]	Туре	d	I	Housing	
058 058	Y06	6	10	Туре 3	
	Y10	10	20	Туре 3	
	Y12	12	20	Туре 3	
,					
5 Blind Hollow Fla	ngo (H)			Ø 58	

5 Blind Hollow Flange (H)					
-28.40 Imin/Imax	Туре	d	min/max	Housing	
	H06	6	15/30	Туре 3	
	H08	8	15/30	Туре 3	
	H12	12	15/30	Туре 3	
	H14	14	15/30	Туре 3	
	H15	15	15/30	Туре 3	



Туре	W1	W2	W3
_AW	~20	~26	~16
P	~25	~13	~16

Ø 36

7	Housing Type 2			Ø 42
	adial [2.20] 55.90 W2 axial [2.04] 51.80 W1	Туре	W1	W2
50		W	~25	~13
[1.50] Ø38.20	[0.26] Ø6.50	P	~20	~14
	[0.39] 10			

Housing Type 3			Ø 58
[1.70] 43.2 w	Туре	W	
[2.31] 958.6	W	20	
	P	13	



PRODUCT SELECTION GUIDE IXARC ROTARY ENCODERS

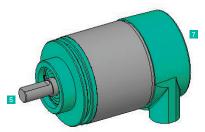
IXARC Optical Encoders

	1	2 3	G 6 6
ο	c –		
Corti	ificate	4 Resolution	5 Mechanical Design
D	CE/UL	12 12 bit (4096 Steps / 0.088°)	Saa navt naga far dataila
		· · · · · · · · · · · · · · · · · · ·	
E	Ex Oil / Gas	13 13 bit (8192 Steps / 0.044°)	Protection Class
M	Ex Mining	16 16 bit (65536 Steps / 0.005°)) 0 IP54 to IP65
S	SIL		S IP54 to IP67 (with Shaft Sealing)
			V IP54 to IP67 (Stainless Steel)
2 Com	munication In	terface	H IP54 to IP67 (Heavy Duty Design)
PPA1B	Parallel Binary	у	
PPA1G	Parallel Gray		Connection Type
P1A1B	Parallel Prese	et Binary	CAW Cable: Axial 1 m
P1A1G	Parallel Prese	et Gray	2AW Cable: Axial 2 m
S101B	SSI Binary		5AW Cable: Axial 5 m AAW Cable: Axial 10 m
S101G	SSI Gray		CRW Cable: Radial 1 m
S401B	SSI Binary w.	Pushbuttons	2RW Cable: Radial 2 m
	SSI Gray w. P		5RW Cable: Radial 5 m
S5xxB		ntal binary + A/B/Z (RS-422)	ARW Cable: Radial 10 m
			PAM Connector: Axial M12, 5 pin
S6xxB		ntal binary + A/B/Z (Push-Pull)	PAQ Connector: Axial M12, 8 pin
		ntal Gray + A/B/Z (RS-422)	PAL Connector: Axial M23, 12 pin (SSI)
		ntal Gray + A/B/Z (Push-Pull)	PAP Connector: Axial M23, 16 pin (Parallel)
DPC1B	Profibus DP		PAT Connector: Axial M27, 26 pin (Parallel)
CAA1B	CANopen		PRM Connector: Radial M12, 5 pin (CAN, Analog)
CL00B	CANopen Lift		PRQ Connector: Radial M12, 8 pin (SSI)
D2B1B	DeviceNet		PRL Connector: Radial M23, 12 pin (ssi)
IBA1B	Interbus		PRP Connector: Radial M23, 16 pin (Parallel)
EIB1B	PROFINET IC)	PRT Connector: Radial M27, 26 pin (Parallel) PRM Connector: Radial 2 x M12 (Modbus)
EEA1B	EtherNet/IP		PRM Connector: Radial 2 x M12 (Modbus) PRM Connector: Radial 3 x M12 (Ethernet/IP, Profinet, Powerlink, Ethernet/IP, Powerlink, Powerlink, Powerlink, Ethernet/IP, Powerlink, Powerlink, Ethernet/IP, Powerlink, Pow
E2A2B	POWERLINK		PRI Connector: Radial 2 x M23, 9 pin (Interbus)
EC00B	EtherCAT		H3P Connection Cap: 3 Cable Glands
EM00B	Modbus/TCP		H2M Connection Cap: 2 x M20 Cable Glands (Profibus, CAN, De
			H72 Connection Cap: 3 x M12 Connectors (Profibus, CAN, Devi
3 Revo	olution		H2B Connection Cap: 2 x M12 Connectors (CAN, DeviceNet)
	Singleturn		H1B Connection Cap: 1 x M12 Connector (CAN, DeviceNet)
08	Multiturn: 8 bit	t (256 rev)	H1C Connection Cap: 1 x M23 Connector (DeviceNet)
		. ,	HCC Connection Cap: Without
12	Multiturn: 12 b		HFZ Connection Cap: 2 x Radial Blind Plug (for OCE / OCN
13	Multiturn: 13 b	· · · ·	HFE Connection Cap: 3 x Radial Blind Plug (for OCE / OCN
14	Multiturn: 14 b	oit (16384 rev)	HFG Connection Cap: Axial Blind Plug (for OCE / OCM)



PRODUCT SELECTION GUIDE IXARC ROTARY ENCODERS

Mechanical Design 5 and Connection Type 7



5 Through Hollow F	lange (T)	Ø 58
[0.70] ~17.8	Туре	d
1 min /1 max	Т08	8
	T10	10
(2.83) 72 058.5 058.5 058.5	T12	12

7 Housing for Fieldbus and Ethernet Ø 58						
e	Туре	w	L (ST / MT) ²⁾			
	PRM	70	57.5 / 68.5			
×			67.7 / 78.7 ³⁾			
	Н	90	57.5 / 68.5			
Ψ.	H2M		60.7 / 71.7			

Ø 58

Ø 58

L (ST / MT)2)

32.2 / 43.2

32.2 / 43.2

Axial Housings (Cable or Connector)

Radial Housings (Cable or Connector)

[2.31] 58.6

Туре

_ AW

PA_

W

18

24

5 Clamp Flange (C) Ø 58 Туре d L C06 6 10 [2.28] ø58

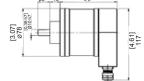
	000	0	10	
	C10	10	20 ¹⁾	
	C12	12	20	
	CA7	9.5	20	
Square Flange (9))			Ø 58

Square Flange (9)			6 9
[0.76] I 19.3	Туре	d	I	
	9A7	9.5	20	

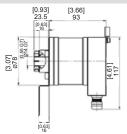
5 Synchro Flange (S)					
(0.53) 13.5 13.5 13.5 13.5 13.5 13.5 13.5 13.5	[0.53] 13.5	Туре	d	I	
		S06	6	10 ¹⁾	
		S10	10	201)	
	=	S12	12	20	
,	Щ				

Ø 58 Blind Hollow Flange (B) [1.12] ~28.40 d min/max Туре I min / I max B06 15 / 30 06 B08 08 15 / 30 [2.83] 72 2.30] B10 10 15 / 30 15 / 301) B12 12 B14 14 15 / 30 B15 15 15 / 30

2331 886	Туре	w	L (ST / MT) ²⁾
	_RW	19	43.2 / 43.2
			43.2 / 53.04)
	PR_	24	43.2 / 43.2
₩ ≥			43.2 / 53.04)
5 Clamp Flange	(F10)⁵)		Ø 78, EX-Proof
	[0.79] [0.63] 20 16 93		



5 Blind Hollow Flange (E14)5)



1) SIL Certified 2) ST Singleturn, MT Multiturn 3) Modbus/TCP

4) Parallel 5) Available for OCE/M Types

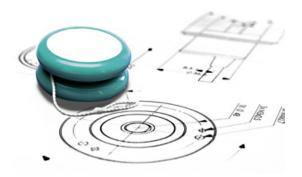
Ø 78, EX-Proof

All measurement in mm [in]

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TECHNOLOGY LINARIX LINEAR SENSORS



Repeatable Length Measurement

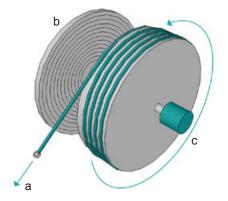
POSITAL'S LINARIX draw wire sensors measure linear motion by displacing a retractable steel wire (a) wound around a cable drum (b) that actuates the rotary encoder (c) coupled to it. The encoder in return provides a proportional output. Measurements are highly accurate, reliable and the systems have very long lifetimes. The LINARIX line offers a wide range of measurement lengths ranging from 1 m to 10 m (3' to 33') and also provides position output in almost all available industrial interfaces both analog and digital.

Compared to conventional linear pots and linear measurement systems using multiple gears and encoders, the LINARIX line of sensors are more



durable and can directly replace them, additionally, avoiding the common problems of slippage, wear and tear damage. The draw wire sensors from POSITAL provide extremely precise measurements because of the inherent accuracy of the encoders and the rugged construction ensures reliable performance even under extreme conditions.

The POSITAL product offering has been categorized based on robustness and length giving the customer maximum selectability based on their respective application.







PRODUCT OVERVIEW LINARIX LINEAR SENSORS

Draw Wire Encoders with Machined Metal Housing

		2 O		2
Measuring Range in m [in]	1.25 [49]	1.74 [69]	2.00 [79]	3.00 [118]
Communication	Analog, SSI,	Analog, SSI,	Analog, SSI,	Analog, SSI,
Interface ¹⁾	CANopen,	CANopen,	CANopen,	CANopen,
	DeviceNet	DeviceNet	DeviceNet	DeviceNet
Accuracy in [±FSO%]	0.04	0.02	0.02	0.04
Wire Material	Nylon Coated	Coated Polyamide	Plastic Coated	Nylon Coated
	Stainless Steel	Stainless Steel	Stainless Steel	Stainless Steel
Wire Diameter in mm	Ø 0.48	Ø 0.45	Ø 0.45	Ø 0.48
Draw Wire Housing	Machined Metal,	Machined Metal,	Machined Metal,	Machined Metal,
Material	Rectangualar Housing	Cylindrical Housing	Rectangualar Housing	Rectangualar Housing
Operating	-40 to +94	-20 to +80	-10 to +80	-40 to +94
Temperature in °C [°F]	[-40 to 201]	[-4 to 176]	[14 to 176]	[-40 to 201]
Max. Extension Force in N	2.34	5.00	2	3.90
Min. Retraction Force in N	1.26	3.50	1.2	2.10
Linear Resolution ²⁾ in µm	24	36	24	49
Drum Circumference in mm [in]	Ø 100 [3.9]	Ø 149 [5.9]	Ø 100 [3.9]	Ø 200 [7.9]
Туре Кеу	LAC	LPC	LCN	LBC

1) Other interfaces available on request

2) Based on an encoder with 12 Bit Resolution



PRODUCT OVERVIEW LINARIX LINEAR SENSORS

			A Co	
Measuring Range in m [in]	3.00 [118]	6.00 [236]	5.08 [200]	10.16 [400]
Communication	Analog, SSI,	Analog, SSI,	Analog, SSI,	Analog, SSI,
Interface ¹⁾	CANopen,	CANopen,	CANopen,	CANopen,
	DeviceNet	DeviceNet	DeviceNet	DeviceNet
Accuracy in [±FSO%]	0.01	0.01	0.02	0.02
Wire Material	Plastic Coated	Stainless Steel	Nylon Coated	Nylon Coated
	Stainless Steel		Stainless Steel	Stainless Steel
Wire Diameter in mm	Ø 0.87	Ø 0.54	Ø 0.86	Ø 0.86
Draw wire Housing	Machined Metal,	Machined Metal,	Die Cast Metal	Die Cast Metal
Material	Rectangualar Housing	Rectangualar Housing		
Temperature	-40 to +80	-20 to +80	-40 to +90	-40 to +90
in °C [°F]	[-40 to 176]	[-4 to 176]	[-40 to 194]	[-40 to 194]
Max. Extension	3	8	6.5	6.5
Force in N				
Min. Retraction	2.5	3.0	3.5	3.5
Force in N				
Linear Resolution ²⁾	49	40	78	78
Drum Circumference in mm [in]	Ø 200 [7.9]	Ø 200 [7.9]	Ø 320 [12.6]	Ø 320 [12.6]
Туре Кеу	LDN	LEN	LKH.	LLH
1) Other interfaces available or	n request			

Draw Wire Encoders with Machined Metal Housing or Die Cast Metal Housing

4

1) Other interfaces available on request

2) Based on an encoder with 12 Bit Resolution



PRODUCT OVERVIEW LINARIX LINEAR SENSORS

Measuring 3.00 [118] 5.00 [197] 10.00 [394] 1.25 [49] 2.10 [83] Range in m [in] Communication Analog, SSI, Analog, SSI, Analog, SSI, Analog, SSI, Analog, SSI, Interface¹⁾ CANopen, CANopen, CANopen, CANopen, CANopen, DeviceNet DeviceNet DeviceNet DeviceNet DeviceNet 0.02 0.02 0.05 0.05 Accuracy 0.01 in [±FSO%] Wire Material Coated Polyamide Nylon Coated Nylon Coated Coated Polyamide Coated Polyamide Stainless Steel Stainless Steel Stainless Steel Stainless Steel Stainless Steel Ø 0.80 Ø 1.00 Ø 0.45 Wire Diameter Ø 1.00 Ø 0.36 in mm Draw wire Extruded Metal Extruded Metal Extruded Metal Plastic Plastic Housing Material Temperature -20 to +80 in °C [°F] [-4 to 176] Max. Extension 21.0 1.50 5.00 9.0 16.0 Force in N Min. Retraction 4.0 8.0 1.00 3.50 5.5 Force in N Linear Reso-63 77 77 31 52 lution²⁾ in µm Drum Circumfe-Ø 260 [10.2] Ø 315 [12.4] Ø 315 [12.4] Ø 125 [4.9] Ø 215 [8.5] rence in mm [in] Туре Кеу L..-..F-.H.. L..-..G-.H. L..-..H-.H.. L..-..N-.C.. L..-..M-.C..

Draw Wire Encoders with Extruded Metal Housing or Plastic Housing

1) Other interfaces available on request

2)Based on an encoder with 12 Bit Resolution



LINARIX Linear Sensors

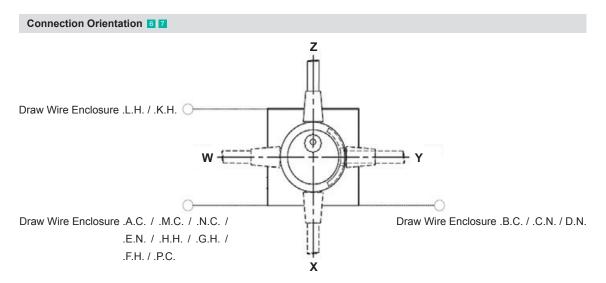
	L 0 - 2 -	4	
1 Tec	hnology	4 End	coder Resolution
w	Draw Wire Only	00	Draw Wire Only
D	Optic (Diode)	D2	12 bit
м	Magnetic	D3	13 bit
	5	D4	16 bit
2 Co	nmunication Interface		
00000	Draw Wire Only		raw Wire Enclosure
AV001	Voltage: 0 to 5 V	See ne	ext page for details
AVP01	Voltage: 0 to 5 V w. Pushbuttons		onnection Orientation and Protection Class
AV002	Voltage: 0 to 10 V		
	Voltage: 0 to 10 V w. Pushbuttons	SEE IIE	ext page for details
AC005	Current: 4 to 20 mA	9 Coi	nnection Type
ACPO	Current: 4 to 20 mA w. Pushbuttons	000	Draw Wire Only
P100E	Parallel Binary with Preset	CRW	1 m PVC Cable - Radial Exit
P100G	Parallel Gray with Preset	ARW	10 m PVC Cable - Radial Exit
S101E	SSI Binary	CAW	1 m PVC Cable - Axial Exit
S1010	i SSI Gray	AAW	10 m PVC Cable - Axial Exit
S5xxE	SSI Binary + Incremental A/B/Z (RS-422)	PRL	M23 12 pin - Radial Exit
S6xxE	SSI Binary + Incremental A/B/Z (Push-Pull)		M23 16 pin - Radial Exit
S5xxG	SSI Gray + Incremental A/B/Z (RS-422)		M26 26 pin - Radial Exit
S6xxG	SSI Gray + Incremental A/B/Z (Push-Pull)		M12 5 pin - Radial Exit
N00I	Incremental		2 x M12 5 pin - Radial Exit
DPC1	B Profibus DP		M12 8 pin - Radial Exit M23 12 pin - Axial Exit
CAA1	B CANopen		M23 16 pin - Axial Exit
CLOOE	CANopen Lift		M12 5 pin - Axial Exit
D2B1E	B DeviceNet		M12 8 pin - Axial Exit
IBA1B	Interbus		M12 Cable Glands x 3
EIB1B	PROFINET IO	H1B	M12 Connector x 1
EEAO	B EtherNet/IP	H2B	M12 Connector x 2
E2A1E	B POWERLINK	H1C	M23 Connector x 1
FMOOR	Modbus/TCP		

Measurement Range

- **1** 1 m
- **2** 2 m
- **3** 3 m
- **5** 5 m
- **6** 6 m
- **A** 10 m

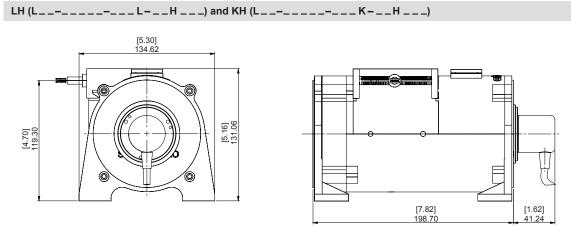


Mechanical Options LINARIX Linear Sensors



Connection Exit selected based on Draw Wire Enclosure **5**. When Connection Type is "Draw Wire Only" then Connection Orientation **6** is 0.

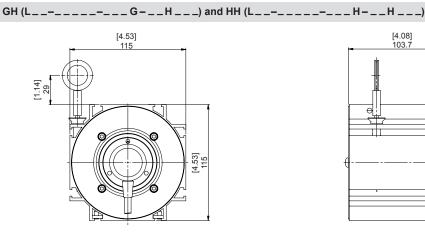
Die Cast Metal



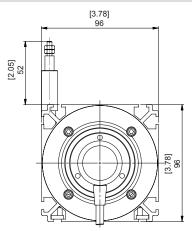
All measurement in mm

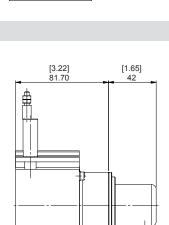


Extruded Metal



FH (L____F___F___H___)





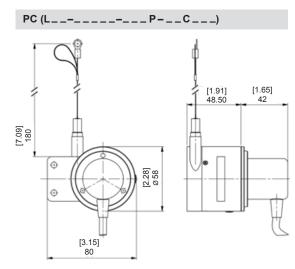
[4.08] 103.7

0

[1.65]

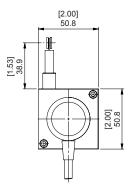
42

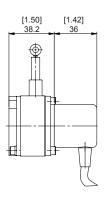
Machined Metal – Cylindrical Housing



Machined Metal – Rectangular Housing

- AC (L_____A-__C___)
- Measurement Length 1.25 m [24.2 in]







[1.43]

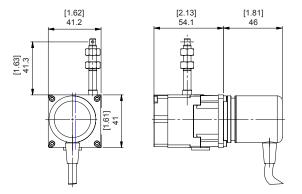
36.4

Machined Metal – Rectangular Housing

EN (L_____E___E___N___) Measurement Length 6.00 m [236 in] (3.35) (3.38) 85.8 (3.38) (3.

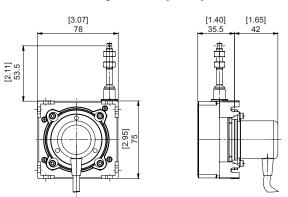
CN (L_____C___C___N___)

Measurement Length 2.00 m [78.7 in]



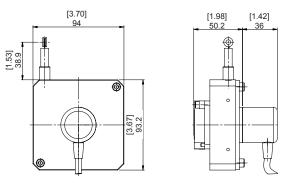
DN (L_____D____D____D____)

Measurement Length 3.00 m [118 in]



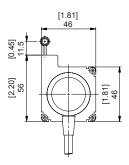
BC (L__-____B-__C___)

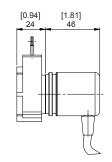
Measurement Length 3.00 m [118 in]



Plastic

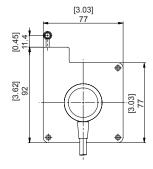
Measurement Length 1.25 m [24.2 in]

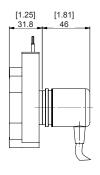




MC (L______M____M_____)

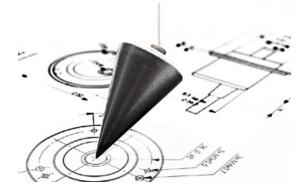
Measurement Length 2.10 m [82.7 in]







TECHNOLOGY TILTIX INCLINOMETERS



POSITAL's TILTIX Inclinometers are based on highly dynamic MEMS (Micro-Electro-Mechanical Systems) technology and on high precision Fluid Cell Technology.

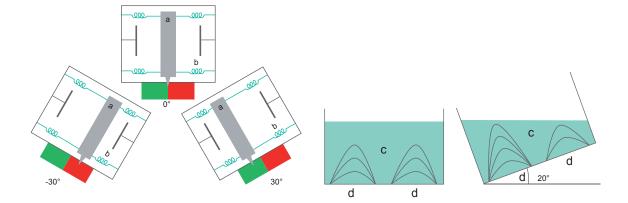
MEMS

In MEMS devices, a 'micro mass' (a) is suspended in a flexible support structure (b). Any movement will induce a displacement of the mass, which will result in a change of the capacitance between the mass and the holding structure. Changes of inclination are calculated from these measured capacitance changes. These inclinometers have a measurement range of ±80° in two axes or 360° in one axis. The devices can withstand shock and vibration loadings of up to 100 g as per EN 60068-2-27.



Fluid Cell

In fluid filled inclinometers a sensor cell is partially filled with an electrolytic liquid (c) and the walls are covered with a pair of electrodes (d). As the senor tilts, the level of fluid covering the electrodes changes. This results in an increase or decrease of conductivity between the electrodes. From this measurement tilt can be calculated. Fluid Cells are capable of measuring inclinations of up to $\pm 30^{\circ}$ with a very high level of precision. The natural damping of liquids makes these inclinometers precise as well as stable.





PRODUCT OVERVIEW TILTIX INCLINOMETERS

Inclinometers with MEMS Technology







Highlights	MEMS	MEMS	MEMS
	Programmable Analog	SSI	Bus Interfaces
Protection Class	Up to IP69K / IP68	Up to IP69K / IP68	Up to IP69K / IP68
Communication Interface	Analog,	SSI	CANopen,
	Voltage,		DeviceNet,
	Current		SAE J1939
Technology	MEMS	MEMS	MEMS
Max Measurement Range	2-axis ±80° /	1-axis 0° to 360°	2-axis ±80° /
	1-axis 0 to 360°		1-axis 0 to 360°
Resolution	0.01°	0.04°	0.01°
Accuracy	0.1°	0.1°	0.1°
Material Housing	Aluminum	Aluminum	Aluminum
Shock /	100 g /	100 g /	100 g /
Vibration ¹⁾	20 g	20 g	20 g
Temperature	-40 to +85	-40 to +85	-40 to +85
in °C [°F]	[-40 to 185]	[-40 to 185]	[-40 to 185]
Supply Voltage	10 to 30 V	5 to 30 V	10 to 30 V
Connection Type	Cable /	Cable /	Cable /
	Connector (M12)	Connector (M12)	Connector (M12)
Certificates	CE	CE	CE
Туре Кеу	ACSH2	ACSS1H2	ACSCA/D1H2

1) Based on (EN 60068-2-27) / (EN 60068-2-6)



PRODUCT OVERVIEW TILTIX INCLINOMETERS

Inclinometers with MEMS and Fluid Cell Technology



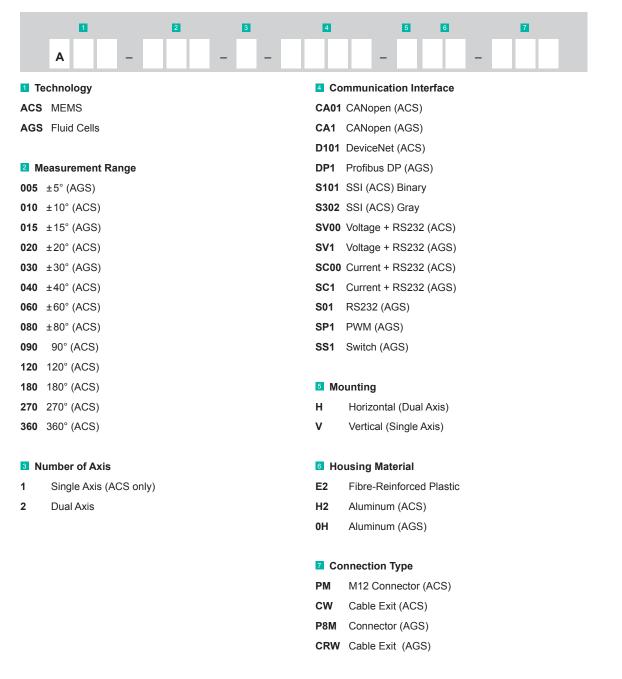
Highlights	MEMS	MEMS	MEMS	Fluid Cell	Fluid Cell
	Programmable	SSI	Bus Interfaces	Analog	CANopen
	Analog				
Protection Class	Up to IP69K / IP68	Up to IP69K / IP68	Up to IP69K / IP68	IP67	IP67
Communication	Analog Voltage	SSI	CANopen,	Analog Voltage	CANopen
Interface	or Current		DeviceNet,	or Current	
			SAE J1939		
Technology	MEMS	MEMS	MEMS	Fluid Cell	Fluid Cell
Max. Measure-	2-axis ±80° /	1-axis 0° to 360°	2-axis ±80° /	2-axis ±30°	2-axis ±30°
ment Range	1-axis 0 to 360°		1-axis 0 to 360°		
Resolution	0.01°	0.04°	0.01°	0.001°	0.001°
Accuracy	0.1°	0.1°	0.1°	0.01°	0.01°
Material Housing	Fiber Reinforced	Fiber Reinforced	Fiber Reinforced	Aluminum	Aluminum
	Plastic	Plastic	Plastic		
Shock /	100 g /	100 g /	100 g /	30 g /	30 g /
Vibration ¹⁾	20 g	20 g	20 g	5 g	5 g
Temperature	-40 to +85	-40 to +85	-40 to +85	-40 to +85	-40 to +85
in °C [°F]	[-40 to 185]	[-40 to 185]	[-40 to 185]	[-40 to 185]	[-40 to 185]
Supply Voltage	10 to 30 V	5 to 30 V	10 to 30 V	10 to 30 V	10 to 30 V
Connection Type	Cable /	Cable /	Cable /	Cable /	Cable /
	Connector (M12)	Connector (M12)	Connector (M12)	Connector (M12)	Connector (M12)
Certificates	CE	CE	CE	CE	CE
Туре Кеу	ACSE2	ACSS1E2	ACSCA/D1	AGS	AGS
			-E2		

1) Based on (EN 60068-2-27) / (EN 60068-2-6)



PRODUCT SELECTION GUIDE TILTIX INCLINOMETERS

TILTIX Inclinometer





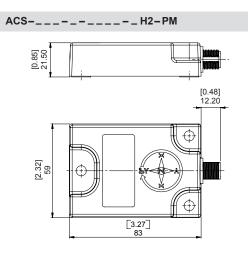
PRODUCT SELECTION GUIDE TILTIX INCLINOMETERS

Mechanical Options TILTIX Inclinometer

MEMS, Fibre-Reinforced Plastic, Connector

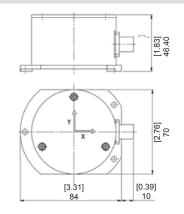
ACS-____E2-PM



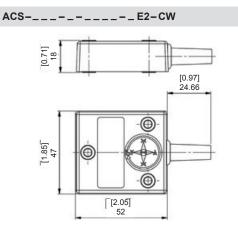


Fluid Cell, Connector

AGS-___-P8M

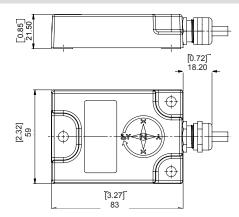


MEMS, Fibre-Reinforced Plastic, Cable

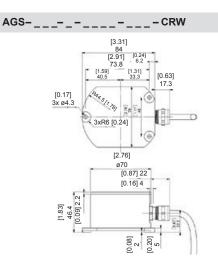


MEMS, Aluminum, Cable

ACS-____H2-CW



Fluid Cell, Cable





PRODUCT OVERVIEW ACCESSORIES

Mounting Fixtures

Material

Couplings and Reducing Adapters

Product	Reducing Adapter	Couplings	Couplings	Couplings
Diameters /	Ø 15 to 12,	Ø 6 to 6, Ø 6 to 10,	Ø 6 to 6, Ø 6 to 1	10, Ø 6 to 6, Ø 6 to 10,
Sizes in mm	Ø 15 to 10	Ø 10 to 10	Ø 10 to 10	Ø 10 to 10
Types or Material	Stainless Steel, Aluminum	Bellow	Disc	Jaw
Product	Flange Adapters	Tethers a	nd Clamp Rings	Clamp Discs
Features	MGY58 and Flar	nge Various To	orque Supports	Clamp Discs to Mount
	Adapters	and Clam	ping Discs	Encoders onto a Surface

Aluminum, Stainless Steel

Aluminum

Aluminum, Plastics



PRODUCT OVERVIEW ACCESSORIES

Electrical Connections and Interface Options

Connectors and Cables

	N		No.	Ç	
Standards	M12	M23	M27	M12 Assembly	M23 Assembly,
					M27 Assembly
Lengths	-	-	_	2, 5, 10	2, 5, 10
Pins /	4 pin D,	9, 12, 16	26	4 pin D,	9, 12, 16, 26
Cables	5 pin A,			5 pin A,	
	8 pin A			8 pin A	
Material of Cable	-	-	-	PUR / PVC	PUR / PVC
Material	Metal	Metal	Metal	PBT	Metal
of Connector				Metal	
Termination	_	_	_	Open Ends /	Open Ends
				RJ45	
Protection Type	IP67	IP67	IP67	IP69K	IP67

Configuration and Interface Modules





Product	SSI2USB Module	Voltage Panel Display
Features	 Easy interface of SSI device 	 Measures voltage from
	to USB port of PC	0 to 40 V DC
	Graphical User Interface	2.4" color TFT screen
	to view and store SSI Data	 Use PanelPilot software, to setup
	 Power Supply to SSI device 	and customize the display
	(max 12 Volts) using USB Port	 Programmable via the USB interface
	Three independent tri-state outputs	 Simple panel mounting solution
	Could be used as a Virtual Com	 Wide operating voltage
	port device	of 4 V to 30 V DC



GLOSSARY

Analog	A common standard with either a voltage or a current output
ATEX / IECEx	ATEX and IECEx norms define essential requirements for equipment and
	protective systems intended for use in potentially explosive atmospheres
CANopen	CANopen is a fieldbus protocol using CAN networks
CANopen Lift	CANopen Lift is a fieldbus protocol for elevator applications
CE	With the CE marking POSITAL declares that the product conforms with
	essential requirements of the applicable EC directives
DeviceNet	DeviceNet is a fieldbus system based on CAN networks and CIP protocol,
	managed by ODVA, widely used in factory automation and available on
	many PLCs
EtherNet/IP	EtherNet/IP is an industrial communication protocol developed by Rockwell
	Automation and managed by ODVA. It is based on CIP and TCP/IP
ETHERNET POWERLINK	Ethernet Powerlink is a real-time communication system based on Ethernet
	networks and managed by EPSG
Interbus	Interbus is a fieldbus technology developed by Phoenix Contact
IP54	Protected against dust and splash water from any direction
IP65	Dust tight and protected against water jets from any direction.
IP67	Dust tight and protected against temporary immersion up to 1 m
IP68	Dust tight and protected against long periods of immersion under pressure
IP69K	Dust tight and protected against high temperature (steam) and high pressure
	water jets from any direction
Modbus	Modbus is a serial protocol managed by the Modbus Organization
Parallel	All bits of the position output are transferred simultaneously using one line
	for each bit
PROFIBUS	Profibus is available on many PLCs and one of the most common fieldbus
	technologies in factory automation and other areas. It is based on RS485.
	There are different versions of Profibus and different device profiles
PROFINET	Profinet is an Industrial Ethernet standard from
	"Profibus&ProfiNet International" designed for automation
SAE J1939	SAE J1939 is a fieldbus standard used for communication by the car and
	heavy-duty truck industry
SIL	SIL (Safety Integrity Level) is defined as a relative level of risk-reduction
	provided by a safety function. In accordance with the requirements of IEC
	61508/EN 62061, PL e and Cat.4 according to EN ISO 13849-1
SSI	SSI is a widely used serial interface with point-to-point connection between
	PLC/Master and encoder. It is based on the RS422 standard
UL	UL (Underwriters Laboratories) is a US based consulting and certification
	company providing safety standards for electrical devices. UL marking
	confirms the compliance with applicable UL safety standards