## 550 Series Positioning Tables


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## Single or Multiple Axis

LINTECH's 550 series positioning tables offer precision performance and design flexibility for use in a wide variety of Motion Control applications.

\author{

- Welding <br> - Gluing <br> - Test Stands <br> - Part Insertion <br> - Laser Positioning <br> - Liquid Dispensing <br> - Pick \& Place <br> - Part Scanning <br> - Inspection Stations <br> - General Automation <br> - Semiconductor Processing
}


## Quality Construction

LINTECH's 550 series tables are designed to handle large loads at very high speeds. These tables use a low friction, preloaded, recirculating linear ball bearing system, which rides on a single precision ground linear rail. The single linear rail is mounted to a precision machined aluminum base, which offers a rigid support over the entire travel of the table's carriage. The load is mounted to a precision machined aluminum carriage, which has slots machined into it. These slots, along with the base mounting brackets, are used for the mounting of the user load. The drive system uses two pulleys, along with a high strength, steel reinforced polyurethane belt, which provides 8.071 inches ( 205 mm ) of linear movement per revolution of the input shaft. The simple belt tensioning system allows for easy adjustment of belt tension by the user. The belt also acts as a cover, preventing debris from getting into the linear bearings \& rail.

The 553 carriage uses 2 high load capacity linear bearings on one precision ground square rail. Both bearings are connected to an internal lubrication network. Any of the 4 lube ports, located on the carriage surface, can be used to supply lubrication to the 2 linear bearings.

The 554 carriage uses 2 high load capacity linear bearings on one precision ground square rail. Both bearings are out-fitted with a self-lubricating material which eliminates the need for regular lubrication. No lube ports are provided on the carriage surface.

The 555 carriage uses 2 high load capacity linear bearings on one precision ground square rail. A unique ball retainer design for the recirculating linear bearings provides a smoother operating system with less audible noise. Both bearings are connected to an internal lubrication network. Any of the 4 lube ports, located on the carriage surface, can be used to supply lubrication to the 2 linear bearings.

## Available Options

## Carriage Adapter Plates \& Vertical Angle Brackets

Optional carriage adapter plates and vertical angle brackets can be mounted directly to the top of various LINTECH positioning tables, thus providing for easy multiple axis configurations.

## End of Travel and Home Switches

The 550 series tables can be provided with end of travel (EOT) and home switches mounted and wired for each axis. Most position controllers can utilize the EOT switches to stop carriage motion when the extreme table travel has been reached in either direction. The home switch provides a known mechanical location on the table.

## Motor Adapter Brackets

NEMA 34, NEMA 42, or any metric mount motor can be mounted to a 550 series positioning table with the use of adapter brackets.

## Rotary Encoders

Incremental rotary encoders can be mounted to the table in order to provide positional data back to either a motion controller, or a digital display.

## Planetary Gearheads

LINTECH provides planetary gearheads which can be used with a 550 series. These gearheads are provided in either an in-line or right angle version, with standard gear ratios of 1:1, 3:1, 5:1 or 10:1. Gearheads may be required for applications which have a large mismatch of load to motor inertias. They also help reduce the torque required from the motor for a particular application.

## Other

The 550 series tables can accommodate chrome plated linear bearings \& rails for corrosive environment applications and power-off electric brakes for load locking applications.

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|  | Standard Features - 550 Series |
| :--- | :--- |
| $\square$ | 10.236 inches $(260 \mathrm{~mm})$ long carriage with two M5 slots for load mounting |
| $\square$ | Compact 3.15 inches $(80 \mathrm{~mm})$ wide by 3.937 inches $(100 \mathrm{~mm})$ tall |
| $\square$ | Travel lengths from 12 inches $(300 \mathrm{~mm})$ to 30 feet $(9,1$ meters $)$ |
| $\square$ | Rigid belt driven design with fully enclosed aluminum housing |
| $\square$ | $0^{\circ} \mathrm{F}$ to $+176^{\circ} \mathrm{F}\left(-18^{\circ} \mathrm{C}\right.$ to $\left.+80^{\circ} \mathrm{C}\right)$ operating temperature |
| $\square$ | Two screw belt tensioning with self locking threads |
| $\square$ | Dynamic Load Capacity to 10,500 lbs ( 4763 kg$)$ |
| $\square$ | Recirculating linear ball bearing system |
| $\square$ | Precision ground square rail design |
| $\square$ | 1 rail with 2 bearing carriages |



## Options - 550 Series

I Angle brackets for multiple axis configurations
$\square$ End of travel (EOT) and home switches wired

- CAD drawings available via the internet
- Chrome plated linear bearings and rails
- Motor mounts for non-NEMA motors
- NEMA 34 \& 42 motor mounts
- Rotary incremental encoders
- Power-off electric brakes
- Base mounting brackets
- Carriage adapter plates
- Planetary gearheads
- Motor couplings

(E) - English Interface
(M) - Metric Interface


## Specifications

| Load Capacities | 553 \& 554 Carriages |  | 555 Carriage |  |
| :---: | :---: | :---: | :---: | :---: |
| Dynamic Horizontal 2 million inches $(50 \mathrm{~km})$ of travel <br> Dynamic Horizontal 50 million inches $(1270 \mathrm{~km})$ of travel <br> Static Horizontal  | 10,500 lbs <br> 3,590 lbs <br> 15,400 lbs | $(4763$ $\left(\begin{array}{cc}1628 & \mathrm{~kg}\end{array}\right)$ $(6985$ $\mathrm{kg})$ | 9,120 lbs <br> 3,119 lbs <br> 14,700 lbs | $\begin{aligned} & \left(\begin{array}{ll} (4136 & \mathrm{kg}){ }^{(1)} \\ (1414 & \mathrm{kg}){ }^{(1)} \\ \left(\begin{array}{ll} (1) \end{array}\right. \end{array}, \begin{array}{l}  \\ (\mathrm{kg})^{(1)} \end{array}\right. \end{aligned}$ |
| Dynamic Roll Moment 2 million inches ( 50 km ) of travel <br> Dynamic Roll Moment 50 million inches $(1270 \mathrm{~km})$ of travel <br> Static Roll Moment  | $\begin{array}{ll} 410 & \mathrm{ft}-\mathrm{lbs} \\ 140 & \mathrm{ft}-\mathrm{lbs} \\ 650 & \mathrm{ft}-\mathrm{lbs} \end{array}$ | $\begin{aligned} & (556 \mathrm{~N}-\mathrm{m}) \\ & (\quad 190 \mathrm{~N}-\mathrm{m}) \\ & (\quad 881 \mathrm{~N}-\mathrm{m}) \end{aligned}$ | $172 \mathrm{ft}-\mathrm{lbs}$ <br> $59 \mathrm{ft}-\mathrm{lbs}$ <br> 285 ft-lbs | $\begin{aligned} & \left(\begin{array}{r} 233 \\ \mathrm{~N}-\mathrm{m}) \\ ( \\ (\quad 80 \mathrm{~N}-\mathrm{m}) \\ (\quad 386 \mathrm{~N}-\mathrm{m}) \end{array}\right. \end{aligned}$ |
| Dyn. Pitch \& Yaw Moment 2 million inches ( 50 km ) of travel <br> Dyn. Pitch \& Yaw Moment 50 million inches ( 1270 km ) of travel <br> Static Pitch \& Yaw Moment | $\begin{array}{rl} 1,215 & \mathrm{ft}-\mathrm{lbs} \\ 414 & \mathrm{ft}-\mathrm{lbs} \\ 1,775 & \mathrm{ft}-\mathrm{lbs} \end{array}$ | $\begin{aligned} & (1647 \mathrm{~N}-\mathrm{m}) \\ & (561 \mathrm{~N}-\mathrm{m}) \\ & (2406 \mathrm{~N}-\mathrm{m}) \end{aligned}$ | $510 \mathrm{ft}-\mathrm{Ibs}$ <br> $174 \mathrm{ft}-\mathrm{lbs}$ <br> $845 \mathrm{ft}-\mathrm{lbs}$ | $\begin{aligned} & (690 \mathrm{~N}-\mathrm{m}) \\ & \left(\begin{array}{rl}  & \mathrm{N}-\mathrm{m}) \end{array}\right. \\ & (1145 \mathrm{~N}-\mathrm{m}) \end{aligned}$ |
| Each Bearing Dyn. Capacity 2 million inches ( 50 km ) of travel <br> Each Bearing Dyn. Capacity 50 million inches ( 1270 km ) of travel <br> Each Bearing Static Load Capacity <br> Maximum Belt Tensile Force <br> Maximum Carriage Thrust Force <br> Maximum Speed <br> Maximum Acceleration | 5,250 lbs <br> 1,795 lbs <br> 7,700 lbs <br> 675 lbs <br> 475 lbs <br> 118 $\mathrm{in} / \mathrm{sec}^{2}$ <br> 1,930 $\mathrm{in} / \mathrm{sec}^{2}$ | $(2381$ $\mathrm{kg})$ $\left(\begin{array}{rr}814 & \mathrm{~kg}) \\ (3493 & \mathrm{kg})\end{array}\right.$ $\left(\begin{array}{cc}306 & \mathrm{~kg}) \\ \left(\begin{array}{cc}215 & \mathrm{~kg})\end{array}\right. \\ \left(\begin{array}{cc}3 & \mathrm{~m} / \mathrm{sec})\end{array}\right. \\ \left(49,0 \mathrm{~m} / \mathrm{sec}^{2}\right)\end{array}\right.$ | 4,560 lbs <br> 1,559 lbs <br> 7,350 lbs <br> 675 lbs <br> 475 lbs <br> 197 $\mathrm{in} / \mathrm{sec}$ <br> 1,930 $\mathrm{in} / \mathrm{sec}^{2}$ | $(2068 \mathrm{~kg})^{(1)}$ $\left(\begin{array}{rl}707 & \mathrm{~kg})^{(1)} \\ (3334 & \mathrm{kg})^{(1)} \\ \left(\begin{array}{cc}306 & \mathrm{~kg})\end{array}\right. \\ (215 \mathrm{~kg}) \\ (5 \mathrm{~m} / \mathrm{sec})\end{array}\right.$ $\left(49,0 \mathrm{~m} / \mathrm{sec}^{2}\right)$ |
| $\mathbf{d}_{2} \quad$ Center to center distance (spacing) of each bearing on a single rail <br> $d_{r} \quad$ Center distance of the bearing to top of carriage plate surface | $\begin{aligned} & 3.876 \text { in } \\ & 1.508 \text { in } \end{aligned}$ | $\begin{array}{ll} (98,4 & \mathrm{mm}) \\ (38,3 & \mathrm{mm}) \end{array}$ | $\begin{aligned} & 3.876 \text { in } \\ & 1.626 \text { in } \end{aligned}$ | $\left.\begin{array}{ll} (98,4 & \mathrm{mm} \end{array}\right)$ |


| Other | 553, 554 \& 555 Carriages |
| :---: | :---: |
| Table Material <br> Linear Rail Material <br> Belt Properties | Base Extrusion, Carriage, \& End Plates - 6061 anodized aluminum Case Hardened Steel <br> Black, 50 mm wide, Polyurethane, Steel reinforced belt |
| Drive Pulley Weight <br> Drive Pulley Diameter <br> Drive Lead | 1.500 lbs $\left(\begin{array}{rl}0,68 & \mathrm{~kg}) \\ 2.569 & \text { in } \\ 8.071 & \text { in } \\ (205,00 & \mathrm{mm})\end{array} ~\right.$ |
| Belt Stretch - x Load (lbs or N) <br> Unidirectional Repeatability <br> Bidirectional Repeatability <br> Position Accuracy (Belt) ${ }^{(2)}$ <br> Orthogonality (multi-axis systems) | 0.00006 in/ft per lbs $($ $0,00114 \mathrm{~mm} / \mathrm{m}$ per N$)$  <br> $+/-$ 0.001 in $(+/-0,0254$ $\mathrm{mm})$ <br> $+/-$ 0.004 in $(+/-0,1016$ $\mathrm{mm})$ <br> $<$ 0.010 in/ft $(<0,254$ $\mathrm{mm} / 300 \mathrm{~mm})$ <br>  $<60$ arc-seconds   |
| Friction Coefficient Breakaway Torque (3) Motor Mount Coupling | $\begin{array}{ll} < & 0.01 \\ <16 \mathrm{lb}-\mathrm{in} \quad(1,808 \mathrm{~N}-\mathrm{m}) \end{array}$ <br> NEMA 34 \& 42 Mounts, Metric Mounts, and Gearheads Two (2) different styles available |

## Footnotes:

(1) Derate value by $50 \%$ when load is applied to the open end of the bearing (inverted configuration).

## Dimensions \& Specifications

| Model <br> Number | Travel ${ }^{(1)}$ <br> Length <br> inches (mm) | Table Dimensions inches (mm) |  | BeltWeightlbs(kg) | Table Weight(553 \& 554 Carriages)lbs(kg) | Table Weight (555 Carriage) <br> lbs <br> (kg) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | A | B |  |  |  |
| 55x10012 | $\begin{gathered} 12 \\ (300) \end{gathered}$ | $\begin{aligned} & 24.00 \\ & (609,6) \end{aligned}$ | $\begin{aligned} & 32.275 \\ & (819,8) \end{aligned}$ | $\begin{gathered} 0.29 \\ (0,13) \end{gathered}$ | $\begin{gathered} 24.1 \\ (10,9) \end{gathered}$ | $\begin{gathered} 23.0 \\ (10,4) \end{gathered}$ |
| 55x10018 | $\begin{gathered} 18 \\ (455) \end{gathered}$ | $\begin{gathered} 30.00 \\ (762,0) \end{gathered}$ | $\begin{aligned} & 38.275 \\ & (972,2) \end{aligned}$ | $\begin{gathered} 0.40 \\ (0,18) \end{gathered}$ | $\begin{gathered} 27.3 \\ (12,4) \end{gathered}$ | $\begin{gathered} 26.0 \\ (11,8) \end{gathered}$ |
| 55x10024 | $\begin{gathered} 24 \\ (605) \end{gathered}$ | $\begin{gathered} 36.00 \\ (914,4) \end{gathered}$ | $\begin{aligned} & 44.275 \\ & (1124,6) \end{aligned}$ | $\begin{gathered} 0.51 \\ (0,23) \end{gathered}$ | $\begin{gathered} 30.6 \\ (13,9) \end{gathered}$ | $\begin{gathered} 29.2 \\ (13,2) \end{gathered}$ |
| 55x10030 | $\begin{gathered} 30 \\ (760) \end{gathered}$ | $\begin{gathered} 42.00 \\ (1066,8) \end{gathered}$ | $\begin{aligned} & 50.275 \\ & (1277,0) \end{aligned}$ | $\begin{gathered} 0.62 \\ (0,28) \end{gathered}$ | $\begin{gathered} 33.9 \\ (15,4) \end{gathered}$ | $\begin{gathered} 32.3 \\ (14,7) \end{gathered}$ |
| 55x10036 | $\begin{gathered} 36 \\ (910) \end{gathered}$ | $\begin{gathered} 48.00 \\ (1219,2) \end{gathered}$ | $\begin{aligned} & 56.275 \\ & (1429,4) \end{aligned}$ | $\begin{gathered} 0.72 \\ (0,33) \end{gathered}$ | $\begin{gathered} 37.2 \\ (16,9) \end{gathered}$ | $\begin{array}{r} 35.5 \\ (16,1) \end{array}$ |
| 55x10048 | $\begin{gathered} 48 \\ (1215) \end{gathered}$ | $\begin{gathered} 60.00 \\ (1524,0) \end{gathered}$ | $\begin{array}{r} 68.275 \\ (1734,2) \end{array}$ | $\begin{gathered} 0.94 \\ (0,43) \end{gathered}$ | $\begin{gathered} 43.8 \\ (19,9) \end{gathered}$ | $\begin{gathered} 41.8 \\ (19,0) \end{gathered}$ |
| 55x10060 | $\begin{gathered} 60 \\ (1520) \end{gathered}$ | $\begin{gathered} 72.00 \\ (1828,8) \end{gathered}$ | $\begin{aligned} & 80.275 \\ & (2039,0) \end{aligned}$ | $\begin{gathered} 1.15 \\ (0,52) \end{gathered}$ | $\begin{gathered} 50.3 \\ (22,8) \end{gathered}$ | $\begin{gathered} 48.0 \\ (21,8) \end{gathered}$ |
| 55x10072 | $\begin{gathered} 72 \\ (1825) \end{gathered}$ | $\begin{gathered} 84.00 \\ (2133,6) \end{gathered}$ | $\begin{aligned} & 92.275 \\ & (2343,8) \end{aligned}$ | $\begin{gathered} 1.37 \\ (0,62) \end{gathered}$ | $\begin{gathered} 56.9 \\ (25,8) \end{gathered}$ | $\begin{gathered} 54.3 \\ (24,6) \end{gathered}$ |
| 55x10084 | $\begin{gathered} 84 \\ (2130) \end{gathered}$ | $\begin{gathered} 96.00 \\ (2438,4) \end{gathered}$ | $\begin{aligned} & 104.275 \\ & (2648,6) \end{aligned}$ | $\begin{gathered} 1.58 \\ (0,72) \end{gathered}$ | $\begin{gathered} 63.5 \\ (28,8) \end{gathered}$ | $\begin{gathered} 60.6 \\ (27,5) \end{gathered}$ |
| 55x10096 | $\begin{gathered} 96 \\ (2435) \end{gathered}$ | $\begin{gathered} 108.00 \\ (2743,2) \end{gathered}$ | $\begin{aligned} & 116.275 \\ & (2953,4) \end{aligned}$ | $\begin{gathered} 1.80 \\ (0,82) \end{gathered}$ | $\begin{gathered} 70.1 \\ (31,8) \end{gathered}$ | $\begin{gathered} 66.9 \\ (30,3) \end{gathered}$ |
| 55x10108 | $\begin{gathered} 108 \\ (2740) \end{gathered}$ | $\begin{gathered} 120.00 \\ (3048,0) \end{gathered}$ | $\begin{aligned} & 128.275 \\ & (3258,2) \end{aligned}$ | $\begin{gathered} 2.01 \\ (0,91) \end{gathered}$ | $\begin{gathered} 76.7 \\ (34,8) \end{gathered}$ | $\begin{aligned} & 73.2 \\ & (33,2) \end{aligned}$ |
| 55x10120 | $\begin{gathered} 120 \\ (3045) \end{gathered}$ | $\begin{aligned} & 132.00 \\ & (3352,8) \end{aligned}$ | $\begin{aligned} & 140.275 \\ & (3563,0) \end{aligned}$ | $\begin{gathered} 2.23 \\ (1,01) \end{gathered}$ | $\begin{gathered} 83.2 \\ (37,8) \end{gathered}$ | $\begin{gathered} 79.4 \\ (36,0) \end{gathered}$ |
| 55x10132 | $\begin{gathered} 132 \\ (3350) \end{gathered}$ | $\begin{aligned} & 144.00 \\ & (3657,6) \end{aligned}$ | $\begin{aligned} & 152.275 \\ & (3867.8) \end{aligned}$ | $\begin{gathered} 2.44 \\ (1,11) \end{gathered}$ | $\begin{gathered} 89.8 \\ (40,8) \end{gathered}$ | $\begin{gathered} 85.7 \\ (38,9) \end{gathered}$ |
| 55x10144 | $\begin{gathered} 144 \\ (3655) \end{gathered}$ | $\begin{aligned} & 156.00 \\ & (3962,4) \end{aligned}$ | $\begin{aligned} & 164.275 \\ & (4172,6) \end{aligned}$ | $\begin{gathered} 2.66 \\ (1,21) \end{gathered}$ | $\begin{gathered} 96.4 \\ (43,7) \end{gathered}$ | $\begin{gathered} 92.0 \\ (41,7) \end{gathered}$ |
| 55x10180 | $\begin{gathered} 180 \\ (4572) \end{gathered}$ | $\begin{gathered} 192.00 \\ (4876,8) \end{gathered}$ | $\begin{aligned} & 200.275 \\ & (5087,0) \end{aligned}$ | $\begin{gathered} 3.30 \\ (1,50) \end{gathered}$ | $\begin{aligned} & 116.1 \\ & (52,7) \end{aligned}$ | $\begin{aligned} & 110.8 \\ & (50,3) \end{aligned}$ |
| 55x10240 | $\begin{gathered} 240 \\ (6096) \end{gathered}$ | $\begin{aligned} & 252.00 \\ & (6400,8) \end{aligned}$ | $\begin{aligned} & 260.275 \\ & (6611,0) \end{aligned}$ | $\begin{gathered} 4.38 \\ (1,99) \end{gathered}$ | $\begin{aligned} & 149.0 \\ & (67,6) \end{aligned}$ | $\begin{aligned} & 142.2 \\ & (64,5) \end{aligned}$ |
| 55x10300 | $\begin{gathered} 300 \\ (7620) \end{gathered}$ | $\begin{gathered} 312.00 \\ (7924,8) \end{gathered}$ | $\begin{aligned} & 320.275 \\ & (8135,0) \end{aligned}$ | $\begin{gathered} 5.45 \\ (2,47) \end{gathered}$ | $\begin{aligned} & 181.9 \\ & (82,5) \end{aligned}$ | $\begin{aligned} & 173.6 \\ & (78,7) \end{aligned}$ |
| 55x10360 | $\begin{gathered} 360 \\ (9144) \end{gathered}$ | $\begin{aligned} & 372.00 \\ & (9448,8) \end{aligned}$ | $\begin{aligned} & 380.275 \\ & (9659,0) \end{aligned}$ | $\begin{gathered} 6.52 \\ (2,96) \end{gathered}$ | $\begin{aligned} & 214.8 \\ & (97,4) \end{aligned}$ | $\begin{aligned} & 204.9 \\ & (92,9) \end{aligned}$ |

T-x $=3$; 553 Carriage; Carriage weight $=7.98 \mathrm{lbs} .(3,62 \mathrm{~kg})$

- $x=4 ; 554$ Carriage; Carriage weight $=7.98 \mathrm{lbs} .(3,62 \mathrm{~kg})$

L x $=5$; 555 Carriage; Carriage weight $=7.14 \mathrm{lbs} .(3,24 \mathrm{~kg})$
Footnotes:

[^0]Dimensions


## Footnotes:

(1) This value is center to center distance (spacing) of each bearing on a single rail ( $\mathrm{d}_{2}$ ).
(2) This value is the center distance of the bearing to top of carriage plate surface ( $\mathbf{d}_{\mathrm{r}}$ ) for the 553 \& 554 carriages. For the 555 carriage $d_{r}=1.626$ inches ( $41,3 \mathrm{~mm}$ ).
(3) Two lube ports on carriage top and lube fittings on each side of the 553 \& 555 carriages are all interconnected. Only one port is required to lubricate both linear bearings. The 554 carriage will not have any lube ports.

## Carriage Fastener Rail \& Base Mounting Brackets

LINTECH provides the user with 2 vital optional accessories. The carriage fastener rails slide into the two slots on the 550 series carriage. These fastener rails give the user the ability to mount their load to the 550 series carriage. From 1 to 3 fastener rails can be used in each carriage slot. The base mounting brackets give the user the ability to mount the 550 series table to a mounting surface. These mounting brackets attach anywhere along the bottom T-slot's on both sides of the 550 series table.


## Table Deflection - Moment of Inertia Values

The "moment of inertia" of an object is a gauge of the strength of that object to resist deflecting when used in an application or orientation where deflection might occur. The higher an I value relates to a lower amount of deflection.
$\mathbf{I}=3.10 \mathrm{in}^{4}\left(1.29 \times 10^{6} \mathrm{~mm}^{4}\right)$

$\mathbf{I}=4.44 \mathrm{in}^{4}\left(1.85 \times 10^{6} \mathrm{~mm}^{4}\right)$
$\downarrow^{W}$


## Linear Bearing Load Capacities

The following equation, and graphs, can be used to help determine the linear bearing life, and load capacity, of a 550 series positioning table.

$$
\mathbf{L}=\left[\frac{R}{F \times S}\right]^{3} \times B
$$

$\mathbf{L}=$ calculated travel life (millions of inches or Km)
$\mathbf{R}=$ rated dynamic load capacity of carriage (or each bearing) at 2 million inches of travel or 50 Km
F = user applied load
S = safety factor (1 to 8)
B $=$ either 2 (for millions of inches) or 50 (for Km)


Dynamic Moment Load $\left(\mathbf{M}_{\mathrm{R}}\right)$ Capacity
Load applied away from Carriage Center
Dynamic Moment Load $\left(\mathbf{M}_{\mathrm{R}}\right)$ Capacity
Load applied away from Carriage Center


Travel Life
millions of inches (Km)

Dynamic Horizontal Load Capacity
Load Centered on Carriage

| travel life |  | 553 \& 554 Carriage |  | 555 Carriage |  |
| :---: | :---: | ---: | :---: | :---: | :---: |
| millions of inches | $(\mathrm{Km})$ | lbs | (kg) | lbs | $(\mathrm{kg})$ |
| 2 | $(50)$ | 10,500 | $(4763)$ | 9,120 | $(4136)$ |
| 50 | $(1270)$ | 3,590 | $(1628)$ | 3,119 | $(1414)$ |
| 100 | $(2540)$ | 2,849 | $(1292)$ | 2,475 | $(1123)$ |



Dynamic Moment Load ( $\mathrm{M}_{\mathrm{P}}$ \& $\mathrm{M}_{\mathrm{y}}$ ) Capacity
Load applied away from Carriage Center

| travel life |  | 553 \& 554 |  | Carriage | 555 Carriage |  |
| :---: | :---: | ---: | :---: | :---: | :---: | :---: |
| millions of inches | $(\mathrm{Km})$ | $\mathrm{ft}-\mathrm{lbs}$ | $(\mathrm{N}-\mathrm{m})$ | ft -lbs | $(\mathrm{N}-\mathrm{m})$ |  |
| 2 | $(50)$ | 1,215 | $(1647)$ | 510 | $(690)$ |  |
| 50 | $(1270)$ | 414 | $(561)$ | 174 | $(236)$ |  |
| 100 | $(2540)$ | 330 | $(447)$ | 138 | $(187)$ |  |
| Ratings are based on $\mathrm{d}_{3}=0 \& \mathrm{~d}_{4}=12$ inches $(305 \mathrm{~mm})$ |  |  |  |  |  |  |



## Maximum Motor Input Torque, Maximum Belt Force, \& Maximum Acceleration Rate

## Maximum Motor Input Torque

The maximum safe speed/torque of a motor/drive system that can be used with the 550 series, is limited by the belt strength at a given speed. The maximum linear forces the belt can adequately handle are determined by the number of teeth on the pulley and the belt width. The chart below illustrates the relationship between motor input torque/belt force and carriage speed. Care should be taken when sizing and selecting a motor/drive system for use with a 550 series table. Exceeding the maximum input torque values at the listed speeds can cause belt "skipping" over pulley teeth. This will result in mis-positioning of the carriage.

## Maximum Acceleration

The maximum acceleration rate using a 550 series table can be determined by the simple equation $\mathbf{F}=\mathbf{M} \mathbf{x} \mathbf{A}$. Knowing the mass of the load, and the maximum safe operating force for the belt, the maximum possible acceleration rate can be determined. Note: The mechanical limitation for acceleration of the 550 series table is 5 g's.

## Maximum Acceleration Example

$\mathbf{F}=\mathbf{M} \times \mathbf{A}$
$\mathbf{F} \quad=\quad$ maximum belt force at desired speed
$\mathbf{M} \quad=\quad$ user applied load
$\mathrm{A}=$ maximum acceleration rate ( g 's)
$\operatorname{Sin} \phi=\quad$ angle of table from horizontal (degrees)
Horizontal Application
Vertical Application
$\mathbf{A}=\frac{\mathbf{F}}{\mathbf{M}}$
$A=\frac{F-M \operatorname{Sin} \phi}{M}$
Example: A 200 lb load is mounted to a 550 series carriage in a horizontal application. Determine the maximum accel rate in g's \& in/sec ${ }^{2}$ that can be used to achieve a maximum speed of 75 IPS.

Step 1: From graph below, determine the maximum belt force at $75 \mathrm{IPS}:(\mathrm{F}=235 \mathrm{lbs})$.

Step 2: Add up your total mass = load weight + carriage weight : $(M=5.4+200=205.4 \mathrm{lbs})$.

Step 3: Solve for A : (A = 235/205.4 = 1.1 g 's $)$.
Note: $1 \mathrm{~g}=386 \mathrm{in} / \mathrm{sec}^{2}$
Step 5: 1.1 g's $\times 386=442 \mathrm{in} / \mathrm{sec}^{2}$.


## Carriage Adapter Plate (550 Base to 550 Carriage)

Optional carriage adapter plates assist in the creation of simple $X-Y, X-Z$, and $X-Y-Z$ multiple axis systems. Using one of the adapter plates below, allows a 550 series table to be mounted on top of a second 550 series table in order to make an $X-Y$ axes system (see below). Also, using two of the adapter plates below, allows a 550 series table to be mounted on top of two 550 series tables in order to make an $\mathrm{X}-\mathrm{Y}$ axes gantry system (see page K-14).


## Mounting Hardware Kit

Part \# 202023
a) 4 Carriage Fastener Rails
b) 4 Base Mounting Brackets
c) $12 \mathrm{M} 5 \times 20 \mathrm{~mm}$ Bolts
d) $8 \mathrm{M} 6 \times 30 \mathrm{~mm}$ Bolts

## Mounting Hardware Kit

Part \# 202024
a) 4 Carriage Fastener Rails
b) 6 Base Mounting Brackackets ed By:
c) $12 \mathrm{M} 5 \times 20 \mathrm{~mm}$ Bolts
d) $12 \mathrm{M} 6 \times 30 \mathrm{~mm}$ Bolts SERVO2GQcom

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## Carriage Adapter Plate ( 550 Carriage to 550 Carriage)

Optional carriage adapter plates assist in the creation of simple $X-Y, X-Z$, and $X-Y-Z$ multiple axis systems. The adapter plate below allows two 550 series tables to be mounted carriage to carriage in order to make an $\mathrm{X}-\mathrm{Y}$ axes system.



Mounting Hardware Kit
Part \# 202025
a) 8 Carriage Fastener Rails
b) $24 \mathrm{M} 5 \times 20 \mathrm{~mm}$ Bolts

## Carriage Adapter Plate (550 Base to 550 Carriage)

Optional carriage adapter plates assist in the creation of simple $X-Y, X-Z$, and $X-Y-Z$ multiple axis systems. Using one of the adapter plates below, allows a 550 series table to be mounted on top of a second 550 series table in order to make an $X-Y$ axes system (see page K-12). Also, using two of the adapter plates below, allows a 550 series table to be mounted on top of two 550 series tables in order to make an $\mathrm{X}-\mathrm{Y}$ axes gantry system (see below).



## Horizontal Adapter Bracket (550 Series Base to 550 Carriage)

Optional horizontal adapter brackets assist in the creation of simple $X-Y, X-Z$, and $X-Y-Z$ multiple axis systems. Using one of the adapter plates below, allows a 550 series table to be mounted on top of a second 550 series table in order to make an $X-Y$ axes system. Also, using two of the adapter plates below, allows a 550 series table to be mounted on top of two 550 series tables in order to make an $\mathrm{X}-\mathrm{Y}$ axes gantry system (see below).


## Vertical Adapter Bracket ( 550 Base to 550 Carriage)

Optional vertical adapter brackets assist in the creation of simple $X-Y, X-Z$, and $X-Y-Z$ multiple axis systems. The vertical adapter bracket below allows a 550 series table to be mounted on top of a second 550 series table in order to make an $\mathrm{X}-\mathrm{Z}$ axes system.



Mounting Hardware Kit Part \# 202028
a) 4 Carriage Fastener Rails
b) 4 Base Mounting Brackets
c) $8 \mathrm{M} 5 \times 20 \mathrm{~mm}$ Bolts
d) $8 \mathrm{M} 6 \times 30 \mathrm{~mm}$ Bolts

Mounting Hardware Kit
Part \# 202029
a) 4 Carriage Fastener Rails
b) 6 Base Mounting Brackets
c) $8 \mathrm{M} 5 \times 20 \mathrm{~mm}$ Bolts
d) $12 \mathrm{M} 6 \times 30 \mathrm{~mm}$ Bolts

## Vertical Adapter Bracket (550 Carriage to 550 Carriage)

Optional vertical adapter brackets assist in the creation of simple $X-Y, X-Z$, and $X-Y-Z$ multiple axis systems. The vertical adapter bracket below allows two 550 series tables to be mounted carriage to carriage in order to make an $\mathrm{X}-\mathrm{Z}$ axes system.


## Multi-Axis Configurations

LINTECH can provide various adapter plates, horizontal adapter brackets, and vertical adapter brackets to facilitate the construction of $\mathrm{X}-\mathrm{Y}, \mathrm{X}-\mathrm{Z}$, and $\mathrm{X}-\mathrm{Y}-\mathrm{Z}$ multiple axis configurations using its many different standard positioning systems.
(X-Y) Configurations


150 Series to 550 series


## Multi-Axis Configurations

LINTECH can provide various adapter plates, horizontal adapter brackets, and vertical adapter brackets to facilitate the construction of $\mathrm{X}-\mathrm{Y}, \mathrm{X}-\mathrm{Z}$, and $\mathrm{X}-\mathrm{Y}-\mathrm{Z}$ multiple axis configurations using its many different standard positioning systems.


## NEMA 34 \& NEMA 42 Motor Mounts

NEMA 34 \& 42 motor mounts can be ordered with either English, or Metric threads. LINTECH can provide adapter brackets for any step motor, or servo motor, that has other mounting requirements.


## Chrome Plated Linear Bearings \& Rails

For applications in high moisture, high humidity, clean room, or highly corrossive environments, chrome plating of the linear bearings, and linear rails, will offer superior resistance to corrosion than stainless steel components, resulting in longer table life. The process uniformly deposits dense, hard, high chromium alloy on the rails, and has a Rockwell C hardness value of 67-72. This process also conforms to MIL Spec: (MIL-C-23422). The chrome plating bonds to the parent material and will not crack or peel off under the high point loading of balls on the rail. This chrome plating process differs from a normal hard enrome plate which just lays on the surface of the part plated.

## End of Travel (EOT) Switches \& Home Switch

LINTECH provides several options for EOT \& home switches. When ordered with a LINTECH 550 series table, each switch is mounted to the side of the table, while the actuating cams are mounted to the carriage assembly. The $T$-slot which runs along both sides of the 550 series, allows the switches to be located anywhere along the table. The switches are pre-wired by LINTECH for easy interfacing to the users Motion Controller.

## End of Travel (EOT) Switches

End of travel (EOT) switches can be utilized by a motion controller to stop carriage motion, thereby preventing any damage to personnel, table carriage, or user mounted load if the extreme end of travel has been reached by the carriage. There are two EOT switches mounted to the side of the table, one on each end. The CCW switch is mounted at the motor mount end, while the CW switch is located at the opposite end of the table. LINTECH provides normally closed (NC) end of travel switches. This provides for a power-off fail safe system, where the position controller can detect broken wires. It is highly recommended that any positioning table used with a position controller, should have end of travel switches installed for protection of personnel, table carriage, and user mounted load.

## Home Switch

The home switch can be utilized by a motion controller as a known fixed mechanical location on the positioning table. The switch is located between the EOT switches, near the motor mount end, and is a normally open (NO) switch.

## Switch Locations

The following diagram shows the locations of the switches when ordered from LINTECH.


Note: Each switch can be located anywhere along the T-slots, which run on both sides of the table.

| Switch Type | Cost | Repeatability <br> inches (microns) | Actuated | Power Supply Required | Activation Area <br> inches (mm) | Comments |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| reed | least expensive | $+/-\underset{(50)}{0.0020}$ | magnetic | No | $\begin{gathered} 0.30 \\ (7,62) \end{gathered}$ | for non-contact \& low repeatable applications |
| hall effect | medium priced | $\text { +/- } 0.0002$ <br> (5) | magnetic | Yes | $\begin{gathered} 0.32 \\ (8,13) \end{gathered}$ | for non-contact and wash down applications |
| proximity | most expensive | $\text { +/- } 0.0002$ <br> (5) | non-magnetic | Yes | $\begin{gathered} 1.75 \\ (44,45) \end{gathered}$ | for non-contact, high speed, \& wash down applications |

Sold \& Serviced By:


Non-Contact Reed Switches


| Repeatability | $:+/-0.0020$ inch (50 microns) |
| :--- | :--- |
| Electrical | $: 1.0 \mathrm{amps} @ 125$ VAC |
|  | $0.5 \mathrm{amps} @ 100$ VDC |
| Activation Style | $:$ magnetic |
| Activation Area | $: 0.30$ inches $(7,62 \mathrm{~mm})$ of travel |
| Temperature Range | $:-10^{\circ} \mathrm{C}$ to $+60^{\circ} \mathrm{C}$ |
| Environment | $:$ non wash down |
| Added Table Width | $: 0.45$ inch $(11,4 \mathrm{~mm})$ (EOT switches) |
|  | 0.45 inch $(11,4 \mathrm{~mm})$ (Home switch) |
| Individual Switch Wiring | $: 12$ inch $(305 \mathrm{~mm})$ leads |



Standard LINTECH Wiring (provided when switch option is ordered with any table)
: from table end plate, 10 foot ( 3 m ) shielded cable, 6 conductor, 24 AWG, unterminated leads

| Wire Color | Description |
| :---: | :---: |
| Black <br> Blue | CW EOT (black) <br> CW Common <br> (black) |
| Red White |  |
| Brown Green | HOME HOME Common (black) |
| Silver | Shield SERV |

CW - Clockwise
CCW - Counter Clockwise oll Free Fax: 877-378-0249
EOT - End of Travel
NC - Normally Closed sales@servo2go.com

NO - Normally Open

## End of Travel (EOT) Switches \& Home Switch

## Non-Contact Hall Effect Switches



| Repeatability | $:+/-0.0002$ inch (5 microns) |
| :--- | :--- |
| Electrical | $: 5-24 \mathrm{VDC}$ |
|  | $15 \mathrm{~mA}-$ power input |
|  | 25 mA max - signal |
| Actuation Style | $:$ magnetic |
| Activation Area | $: 0.32$ inches $(8,13 \mathrm{~mm})$ of travel |
| Temperature Range | $:-10^{\circ} \mathrm{C}$ to $+60^{\circ} \mathrm{C}$ |
| Environment | $:$ wash down |
| Added Table Width | $: 0.45$ inch $(11,4 \mathrm{~mm})$ (EOT switches) |
|  | 0.45 inch $(11,4 \mathrm{~mm})$ (Home switch) |
| Individual Switch Wiring | $: 12$ inch $(305 \mathrm{~mm})$ leads |



Standard LINTECH Wiring (provided when switch option is ordered with any table)
from table end plate, 10 foot ( 3 m ) shielded cable; 9 conductor, 24 AWG, unterminated leads

| Wire Color | Description |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Brown | CW Power <br> CW EOT <br> CW Common | (brown) | switch | NC |
| Black |  | (black) |  |  |
| Blue |  | (blue) |  |  |
| Red | CCW Power | (brown) | switch | NC |
| White | CCW EOT | (black) |  |  |
| Green | CCW Common | (blue) |  |  |
| Orange | Home Power | (brown) | switch | NO |
| Yellow | Home | (black) |  |  |
| Grey | Home Common | (blue) |  |  |
| Silver | Shield |  |  |  |

## Non-Contact Proximity Switches



| Repeatability | $:+/-0.0002$ inch (5 microns) |
| :--- | :--- |
| Electrical | $: 10-28$ VDC |
|  | $15 \mathrm{~mA}-$ power input |
|  | 100 mA max - signal |
| Actuation Style | $:$ non-magnetic cam |
| Activation Area | $: 1.75$ inches $(44,45 \mathrm{~mm})$ of travel |
| Temperature Range | $:-25^{\circ} \mathrm{C}$ to $+75^{\circ} \mathrm{C}$ |
| Environment | $:$ IEC IP67 wash down |
| Added Table Width | $: 0.45$ inch $(11,4 \mathrm{~mm})$ (EOT switches) |
|  | 0.45 inch $(11,4 \mathrm{~mm})$ (Home switch) |
| Individual Switch Wiring | $: 6.5$ foot $(2 \mathrm{~m})$ cable for NPN |
|  |  |
|  |  |
|  |  |


| NPN wiring connection - both NC \& NO$\qquad$ Power - (Brown) |  |
| :---: | :---: |
| NPN Switch Sinking |  |
| NPN wiring connection - both NC \& NO$\qquad$ Power - (Brown) |  |
| PNP Switch Sourcing |  |

Standard LINTECH Wiring (provided when switch option is ordered with any table)
: from table end plate, 10 foot ( 3 m ) shielded cable; 9 conductor, 24 AWG, unterminated leads

| Wire Color | Description |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Brown | CW Power (brown) |  |  | NC |
| Black | CW EOT | (black) | switch |  |
| Blue | CW Common | (blue) |  |  |
| Red | CCW Power (brown) |  |  |  |
| White | CCW EOT | (black) | switch | NC |
| Green | CCW Common | (blue) |  |  |
|  |  |  |  |  |
| Orange | Home Power |  |  |  |
| Yellow | Home |  |  |  |  |  |
| Grey | Home Common | To(bl\|(G) ee P Phone: $8 \not 77-37$Toll Free Fax: $877-378$ |  |  |
| Silver | Shield | sales@servo2go.co |  |  |
|  |  | www.servo2go.com |  |  |

## Motor Couplings

LINTECH provides three different types of couplings that can be used to mount a motor to a positioning table. These couplings compensate for misalignment between the motor shaft \& belt drive shaft extension. This provides for trouble-free operation as long as certain precautions are taken. The connected motor output torque should never exceed the coupling maximum torque capacity. Larger capacity couplings may be required for applications having high accelerations, large back driving loads, high torque output motors, or servo motors.


| Model <br> Number |  | $\begin{gathered} \mathrm{L} \\ \substack{\text { inches } \\ (\mathrm{mm})} \\ \hline \end{gathered}$ | Table | Motor | Dia <br> Min <br> (in) |  | Maxi <br> (in) | $\begin{aligned} & \text { imum } \\ & (\mathrm{mm}) \end{aligned}$ |  | Inertia <br> oz-in ${ }^{2}$ <br> $\left(\mathrm{g}-\mathrm{cm}^{2}\right)$ | Wind-up arc-sec/oz-in (deg/N-m) | Max Torque oz-in (N-m) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| H197-018-aaa | $\begin{aligned} & 1.97 \\ & (50,0) \end{aligned}$ | $\begin{aligned} & 2.35 \\ & (59,7) \end{aligned}$ | 018 | aaa | . 375 | 10 | . 750 | 20 | $\begin{gathered} \hline 7.6 \\ (215) \end{gathered}$ | $\begin{aligned} & 3.69 \\ & (674) \end{aligned}$ | $\begin{gathered} 1.1 \\ (0,043) \end{gathered}$ | $\begin{aligned} & \hline 3,600 \\ & (25,4) \end{aligned}$ |
| H225-018-aaa | $\begin{aligned} & 2.25 \\ & (57,2) \end{aligned}$ | $\begin{gathered} 3.07 \\ (78,0) \end{gathered}$ | 018 | aaa | . 500 | 12 | 1.000 | 24 | $\begin{aligned} & 13.1 \\ & (371) \end{aligned}$ | $\begin{gathered} 8.29 \\ (1516) \end{gathered}$ | $\begin{gathered} 0.6 \\ (0,024) \end{gathered}$ | $\begin{aligned} & 5,300 \\ & (37,4) \end{aligned}$ |
| G177-018-aaa | $\begin{aligned} & 1.77 \\ & (45,0) \end{aligned}$ | $\begin{aligned} & 2.48 \\ & (63,0) \end{aligned}$ | 018 | aaa | . 375 | 10 | . 750 | 20 | $\begin{gathered} 7.1 \\ (200) \end{gathered}$ | $\begin{aligned} & 2.78 \\ & (508) \end{aligned}$ | $\begin{gathered} 0.2 \\ (0,008) \end{gathered}$ | $\begin{aligned} & 4,250 \\ & (30,0) \end{aligned}$ |
| G220-018-aaa | $\begin{aligned} & 2.20 \\ & (56,0) \end{aligned}$ | $\begin{aligned} & 2.56 \\ & (65,0) \end{aligned}$ | 018 | aaa | . 500 | 12 | 1.000 | 24 | $\begin{aligned} & 10.6 \\ & (300) \end{aligned}$ | $\begin{gathered} 6.41 \\ (1172) \end{gathered}$ | $\begin{gathered} 0.04 \\ (0,002) \end{gathered}$ | $\begin{aligned} & 7,100 \\ & (50,0) \end{aligned}$ |
| G260-018-aaa ${ }^{(1)}$ | $\begin{aligned} & 2.60 \\ & (66,0) \end{aligned}$ | $\begin{aligned} & 3.07 \\ & (78,0) \end{aligned}$ | 018 | aaa | . 625 | 16 | 1.000 | 24 | $\begin{aligned} & 21.2 \\ & (600) \end{aligned}$ | $\begin{aligned} & 17.91 \\ & (3276) \end{aligned}$ | $\begin{gathered} 0.03 \\ (0,001) \end{gathered}$ | $\begin{aligned} & 9,600 \\ & (68,0) \end{aligned}$ |
| Possible values for aaa | $375=$ $500=$ $625=$ $750=$ | 375 inch 500 inch 625 inch 750 inch |  | $=1.000$ | inch |  | $010=10$ $012=1$ $014=1$ $016=1$ | 0 mm 2 mm 4 mm 6 mm | 018 019 020 024 | $\begin{aligned} & =18 \mathrm{~m} \\ & =19 \mathrm{~m} \\ & =20 \mathrm{~m} \\ & =24 \mathrm{~m} \end{aligned}$ |  |  |

## Footnotes:

(1) This coupling option can not be used with the optional NEMA $34 \& 42$ motor mounts because its diameter is too large. Custom motor mounts can be provided upon request. See page K-25 for maximum coupling diameter and length specifications for use with the optional NEMA $34 \& 42$ motor mounts.

## Motor Couplings

| Coupling | Cost | Torque Capacity | Wind-up | Suggested Motor | Comments |
| :---: | :---: | :---: | :---: | :---: | :--- |
| H Type | less expensive | medium | medium | stepper or servo | use for high accels \& for starting \& stopping large <br> inertia loads |
| G Type | more expensive | high | the least | servo | use for very high torque requirements \& very high <br> servo accelerations |


| Specification | 550 Series <br> NEMA 34 \& 42 bracket <br> inches <br> $(\mathrm{mm})$ |
| :--- | :---: |
| Shaft extension diameter at motor mount end | 0.709 <br> $(18,0)$ |
| Maximum coupling diameter | 2.300 <br> $(58,42)$ |
| Maximum coupling length | 3.100 <br> $(78,74)$ |
| Note: Custom brackets available upon request. |  |

## Coupling Part Numbers

| C293 | H197-018-375 | C359 | H225-018-500 | C573 | G177-018-375 | C639 | G220-018-500 | C684 | G260-018-625 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| C294 | H197-018-500 | C360 | H225-018-625 | C574 | G177-018-500 | C640 | G220-018-625 | C685 | G260-018-750 |
| C295 | H197-018-625 | C361 | H225-018-750 | C575 | G177-018-625 | C641 | G220-018-750 | C686 | G260-018-999 |
| C296 | H197-018-750 | C362 | H225-018-999 | C576 | G177-018-750 | C642 | G220-018-999 | C687 | G260-018-016 |
| C297 | H197-018-010 | C363 | H225-018-012 | C577 | G177-018-010 | C643 | G220-018-012 | C688 | G260-018-018 |
| C298 | H197-018-012 | C364 | H225-018-014 | C578 | G177-018-012 | C644 | G220-018-014 | C689 | G260-018-019 |
| C299 | H197-018-014 | C365 | H225-018-016 | C579 | G1177-018-014 | C645 | G220-018-016 | C690 | G260-018-020 |
| C300 | H197-018-016 | C366 | H225-018-018 | C580 | G177-018-016 | C646 | G220-018-018 | C691 | G260-018-024 |
| C301 | H197-018-018 | C367 | H225-018-019 | C581 | G177-018-018 | C647 | G220018-019 |  |  |
| C302 | H197-018-019 | C368 | H25-018-020 | C582 | G177-018-019 | C6488 | G220-018-020 |  |  |
| C303 | H197-018-020 | C369 | H225-018-024 | C583 | G177-018-020 | C649 | G220-018-024 |  |  |

## Power-off Electric Brakes

For vertical table applications, or for those applications requiring the load to be locked securely in place, an electric brake may be mounted to the positioning table. The 550 series will have the brake mounted to the "Thru Drive Shaft" option. With proper wiring from a control system, this power-off friction brake can ensure that the carriage is firmly held in place, when no electric power is applied to the brake. When power is applied to the brake, the brake is opened or "released".

For proper emergency braking of the 550 series table, this electric brake needs to be interfaced to a position controller or relay network. LINTECH also provides 24 \& 90 VDC power supplies which can be used to power the brakes.

## Brakes

| Model <br> Number | Holding Force <br> in-lbs <br> $(\mathrm{N}-\mathrm{m})$ | Excitation Voltage <br> volts | Current <br> amps | Weight <br> lbs <br> $(\mathrm{kg})$ |
| :---: | :---: | :---: | :---: | :---: |
| B05 | 180 <br> $(20,3)$ | 24 VDC | 1.136 | 4.8 <br> $(2,18)$ |
| B06 | 180 <br> $(20,3)$ | 90 VDC | 0.287 | 4.8 <br> $(2,18)$ |



Note: This power-off electric brake MUST NOT be engaged when the positioning table is in motion. Moving the table with the brake applied could damage the brake and the positioning table. Also, continuous use of this brake to stop a table (load) that is in motion could damage the brake and the positioning table. Dynamic braking of a positioning table should be done by the motor and not the brake.

## Power Supplies

| Model <br> Number | DC Output |  |  | AC Input |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| volts | amps | style | volts | amps | Hz |  |
| 41970 | 5 | 3.0 | regulated | $120 / 240$ | $0.8 / 0.4$ | $47-63$ |
| 37488 | 24 | 1.2 | regulated | $120 / 240$ | $0.8 / 0.4$ | $47-63$ |
| 37489 | 90 | 0.8 | unregulated | 120 | 1.0 | $50 / 60$ |
| 37490 | 90 | 0.8 | unregulated | 240 | 0.5 | $50 / 60$ |

## Rotary Incremental Encoders

Shaftless, incremental, optical rotary encoders can be mounted to the "Thru Drive Shaft" option on the 550 series positioning tables. These encoders provide positional feedback to either a motion controller, or a digital position display.


| Wire Color | Description |
| :---: | :---: |
| White Blue | Channel $\mathrm{A}^{+}$(or A) <br> Channel A- (or $\bar{A}$ ) |
| Green Orange | Channel $\mathrm{B}^{+}$(or B) <br> Channel B ${ }^{-}$(or B) |
| White/Black <br> Red/Black | Channel Z ${ }^{+}$(or Z) <br> Channel Z (or Z) |
| Black <br> Red | Common $+5 \text { vdc (+/-5\%) }$ |


| Specification | ROTARY ENCODERS |  |  |
| :---: | :---: | :---: | :---: |
|  | E01 | E02 | E03 |
| Line Count <br> Pre Quadrature Resolution <br> Post Quadrature Resolution | 500 lines/rev <br> 0.002 revs/pulse <br> $0.0005 \mathrm{revs} / \mathrm{pulse}$ | 1000 lines/rev <br> 0.001 revs/pulse <br> 0,00025 revs/pulse | 1270 lines/rev 0.00079 revs/pulse 0.00019 revs/pulse |
| Maximum Speed Maximum Accel Excitation Power | 50 revs/sec <br> 40 revs $/ \mathrm{sec}^{2}$ <br> + 5 VDC @ 125 ma |  |  |
| Operating Temperature <br> Humidity <br> Shock <br> Weight | $32^{\circ} \mathrm{F}$ to $140^{\circ} \mathrm{F}\left(0^{\circ} \mathrm{C}\right.$ to $\left.60^{\circ} \mathrm{C}\right)$ $20 \%$ to $80 \%$ non condensing 10 G's for 11 msec duration $0.7 \mathrm{lbs}(0,283 \mathrm{~kg})$ |  |  |
| Cable Length <br> Zero Reference Output | $10 \mathrm{ft}(3 \mathrm{~m})$, unterminated 26 gauge leads Once per revolution |  |  |
| Outputs | TTL square wave; Two channel ( $\mathrm{A}+$ \& $\mathrm{B}+$ ); Differential ( $\mathrm{A}-\& \mathrm{~B}$ ); Line Driver |  |  |


[^0]:    (1) Longest possible travel is 30 feet ( 9,1 meters). Any travel length less than 30 feet ( 9,1 meters) can be provided.

