

Kollmorgen AKM™ Servomotor Selection Guide



with AKD™ Servo Drive Systems

KOLLMORGEN®

Because Motion Matters™

Kollmorgen.

Every solution comes from a real understanding of the challenges facing machine designers and users.

The ever-escalating demands of the marketplace mean increased pressure on machine designers and users at every turn. Time constraints. Demands for better performance. Having to think about the next-generation machine even before the current one is built. While expectations are enormous, budgets are not. Kollmorgen's innovative motion solutions and broad range of quality products help engineers not only overcome these challenges but also build truly differentiated machines.

Because motion matters, it's our focus. Motion can distinctly differentiate a machine and deliver a marketplace advantage by improving its performance. This translates to overall increased efficiency on the factory floor. Perfectly deployed machine motion can make your customer's machine more reliable and efficient, enhance accuracy and improve operator safety. Motion also represents endless possibilities for innovation. We've always understood this potential, and thus have kept motion at our core, relentlessly developing products that offer precision control of speed, accuracy and position in machines that rely on complex motion.

Removing the Barriers of Design, Sourcing, and Time

At Kollmorgen, we know that OEM engineers can achieve a lot more when obstacles aren't in the way. So, we knock them down in three important ways:

Integrating Standard and Custom Products

The optimal solution is often not clear-cut. Our application expertise allows us to modify standard products or develop totally custom solutions across our whole product portfolio so that designs can take flight.

Providing Motion Solutions, Not Just Components

As companies reduce their supplier base and have less engineering manpower, they need a total system supplier with a wide range of integrated solutions. Kollmorgen is in full response mode with complete solutions that combine programming software, engineering services and best-in-class motion components.

Global Footprint

With direct sales, engineering support, manufacturing facilities, and distributors spanning the Americas, Europe, Middle East, and Asia, we're close to OEMs worldwide. Our proximity helps speed delivery and lend support where and when they're needed.

Financial and Operational Stability

Kollmorgen is part of Danaher Corporation. A key driver in the growth of all Danaher divisions is the Danaher Business System, which relies on the principle of "kaizen" – or continuous improvement. Using world-class tools, cross-disciplinary teams of exceptional people evaluate processes and develop plans that result in superior performance.

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AKM™ Servomotor

Kollmorgen's AKM family of servomotors gives you unprecedented choice and flexibility from a wide range of standard products so you can select the best servomotor for your application. By pairing AKM servomotors with our family of plug-and-play AKD™ servo drives, selecting the right motion control products has never been easier. Pick from thousands of servomotor/servo drive combinations outlined in this selection guide or go to our website to find the best solution for your application.

Standard AKM servomotors and servo drives offer the best of both worlds – the exact specifications of a custom solution with the faster delivery times and lower cost of a standard catalog product. For your truly unique motion control applications, work with our engineering team to customize a solution for your machine design. Either way, standard product or customized, we can help you choose the motion control solution that meets your exact requirements.

The Benefits of AKM Servomotor

- Best-in-Class Performance
 - Industry-leading motor power density
 - Same size AKM/AKD system delivers up to 47% more shaft power than before
 - Compensation for stiff and compliant transmissions and couplings
 - Exceptionally low cogging
- Flexibility to Find an Exact-fit Solution in a Standard Product
 - AKM offers 28 frame-stack combinations and 117 standard windings in a single motor line
 - Over 500,000 standard motor variations including a wide range of mounting, connectivity, feedback and other options
 - Simplifies or eliminates mechanical modifications and engineering adaptation
 - New Washdown and Food Grade options for AKM
 - New higher torque models up to 180 Nm of continuous torque
- Ease-of-Use and Faster Commissioning
 - Plug-and-play motor recognition drive commissioning
 - Reduce cycle time and sensor-and-wiring costs by eliminating traditional homing methods
 - Reduction in set-up time for each servo system

AKM Servomotor Series

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AKM Motors Offer Extremely High Torque Density and High Acceleration

The AKM high-performance motor series offers a wide range of mounting, connectivity, feedback and other options. These motors offer superb flexibility to meet application needs with:

- 8 frame sizes (40 to 260 mm)
- 28 frame-stack length combinations
- 117 'standard' windings

Features

Torque

0.16 to 180 Nm continuous stall torque (1.4 to 1590 lb-in) in 28 frame-stack combinations. Specific torques are often available from multiple frame sizes to optimize mounting and inertia matching capabilities.

Speed

Speeds to 8000 rpm meet high speed application requirements. Windings tailored to lower speeds are also available.

Voltage

AKM motors can be applied to all standard global voltages. Windings are specifically tailored to 75 Vdc, 120, 240, 400 and 480 Vac.

Mounting

Multiple mounting standards are available to meet common European, North American, and Japanese standards.

Feedback

AKM motors include resolver, encoder (commutating), Sine-Absolute encoder or SFD (Smart Feedback Device) feedback options to meet specific application requirements.

Smoothness

Smooth performance results from low-cog, low-harmonic distortion magnetic designs.

Connectivity

Rugged, rotatable IP65 connectors or low cost IP20 Molex plugs are both available to provide flexibility. Single connectors/plugs (combined power and feedback) are also available to minimize motor and cable cost (SFD only).

Thermal

Windings are rated conservatively at 100°C rise over a 40°C ambient while using 155°C (class F) insulation materials. Motors meet applicable cURus and CE requirements and include thermistors. Thermal ratings at 60°C rise are also provided to meet the needs of specific applications.



Kollmorgen Cables Offer the Complete Solution

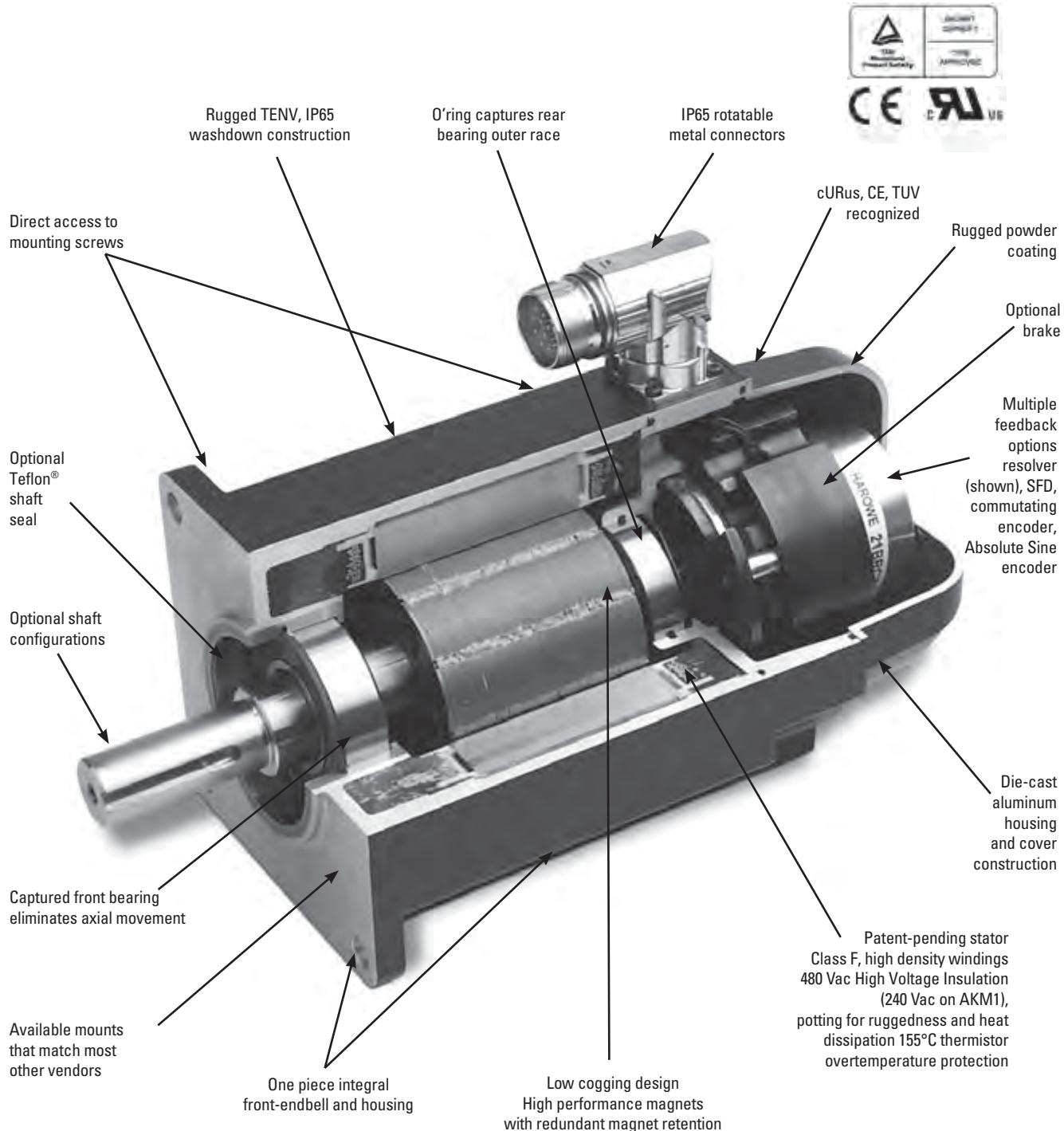
The new Value Line cables provide a cost saving option for applications that don't require long distances or encounter extreme environmental conditions. Value Line is a composite cable that combines power and feedback in one cable to aid in faster machine commissioning. Contact Kollmorgen Customer Support to identify which cable option is best suited for your application.

Options

Additional options:

- Fail-safe brakes
- New, Teflon® shaft seals
- Feedback devices
- Shaft and mounting variations
- Custom windings
- Connectivity

3-D Model Shows Key Design Features



AKD™ Servo Drive

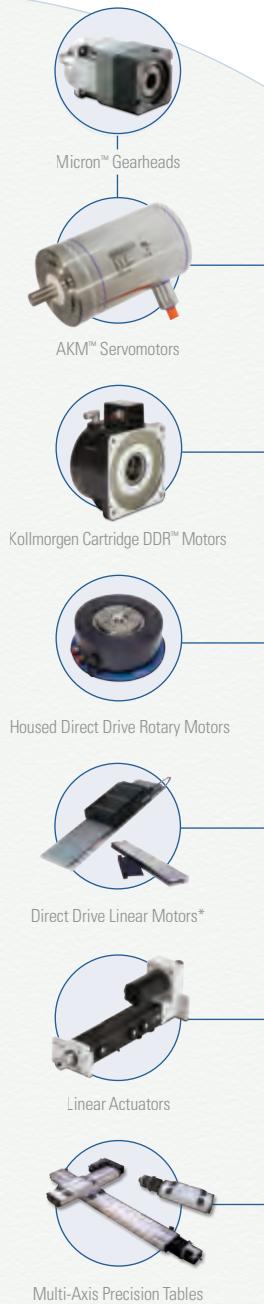
Our AKD series is a complete range of Ethernet-based servo drives that are fast, feature-rich, flexible and integrate quickly and easily into any application. AKD ensures plug-and-play commissioning for instant, seamless access to everything in your machine. And, no matter what your application demands, AKD offers industry-leading servo performance, communication options, and power levels, all in a smaller footprint.

This robust, technologically advanced family of drives delivers optimized performance when paired with our best-in-class components, producing higher quality results at greater speeds and more uptime. With Kollmorgen servo components, we can help you increase your machine's OEE by 50%.

The Benefits of AKD Servo Drive

- Optimized Performance in Seconds
 - Auto-tuning is one of the best and fastest in the industry
 - Automatically adjusts all gains, including observers
 - Immediate and adaptive response to dynamic loads
 - Precise control of all motor types
 - Compensation for stiff and compliant transmission and couplings
- Greater Throughput and Accuracy
 - Up to 27-bit-resolution feedback yields unmatched precision and excellent repeatability
 - Very fast settling times result from a powerful dual processor system that executes industry-leading and patent pending servo algorithms with high resolution
 - Advanced servo techniques such as high-order observer and bi-quad filters yield industry-leading machine performance
 - Highest bandwidth torque-and-velocity loops. Fastest digital current loop in the market
- Easy-to-use Graphical User Interface (GUI) for Faster Commissioning and Troubleshooting
 - Six-channel real-time software oscilloscope commissions and diagnoses quickly
 - Multi-function Bode Plot allows users to quickly evaluate performance
 - Auto-complete of programmable commands saves looking up parameter names
 - One-click capture and sharing of program plots and parameter settings allow you to send machine performance data instantly
 - Widest range of programming options in the industry
- Flexible and Scalable to Meet any Application
 - 3 to 24 Arms continuous current; 9 to 48 Arms peak
 - Very high power density enables an extremely small package
 - True plug-and-play with all standard Kollmorgen servomotors and actuators
 - Supports a variety of single and multi-turn feedback devices—Smart Feedback Device (SFD), EnDat2.2, 01, BiSS, analog Sine/Cos encoder, incremental encoder, HIPERFACE®, and resolver
 - Tightly integrated Ethernet motion buses without the need to add large hardware: EtherCAT®, SynqNet®, Modbus/TCP, EtherNet/IP, PROFINET, and CANopen®
 - Scalable programmability from base torque-and-velocity through multi-axis master

The AKD servo drive delivers cutting-edge technology and performance with one of the most compact footprints in the industry. These feature-rich drives provide a solution for nearly any application, from basic torque-and-velocity applications, to indexing, to multi-axis programmable motion with embedded Kollmorgen Automation Suite. The versatile AKD sets the standard for power density and performance.



Best-in-Class Components

AKD works seamlessly with Kollmorgen motors and actuators—well-known for quality, reliability, and performance.



AKD™ Servo Drive



Industry-leading power density



General Specifications

120 / 240 Vac 1 & 3 Phase (85 - 265 V)	Continuous Current (Arms)	Peak Current (Arms)	Drive Continuous Output Power Capacity (Watts)	Internal Regen (Watts) (Ohms)		Height mm (in)	Width mm (in)	Depth mm (in)	Depth with Cable Bend Radius mm (in)
AKD-■00306	3	9	1100	0	0	168 (6.61)	57 (2.24)	153 (6.02)	184 (7.24)
AKD-■00606	6	18	2000	0	0	168 (6.61)	57 (2.24)	153 (6.02)	184 (7.24)
AKD-■01206	12	30	4000	100	15	195 (7.68)	76 (2.99)	186 (7.32)	215 (8.46)
AKD-■02406	24	48	8000	200	8	250 (9.84)	100 (3.94)	230 (9.06)	265 (10.43)
240/480 Vac 3 Phase (187-528 V)	Continuous Current (Arms)	Peak Current (Arms)	Drive Continuous Output Power Capacity (Watts)	Internal Regen (Watts) (Ohms)		Height mm (in)	Width mm (in)	Depth mm (in)	Depth with Cable Bend Radius mm (in)
AKD-■00307	3	9	2000	100	33	256 (10.08)	70 (2.76)	186 (7.32)	221 (8.70)
AKD-■00607	6	18	4000	100	33	256 (10.08)	70 (2.76)	186 (7.32)	221 (8.70)
AKD-■01207	12	30	8000	100	33	256 (10.08)	70 (2.76)	186 (7.32)	221 (8.70)
AKD-■02407	24	48	16,000	200	23	310 (12.20)	105 (4.13)	229 (9.02)	264 (10.39)
S748	48	96	35,000	—	—	385 (15.16)	190 (7.48)	244 (9.61)	285 (11.22)
S772	72	140	50,000	—	—	385 (15.16)	190 (7.48)	244 (9.61)	285 (11.22)

Note 1: For complete AKD and S700 model nomenclature, refer to pages 72 and 73.

Note 2: Additional AKD information can be found online.

AKM World of Options

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This selection guide outlines the extensive options available within the family of advanced AKM servomotors. Our motors are complemented by a complete family of digital servo drives, offering you the best motion control solution in the marketplace.

Beyond the AKM series, Kollmorgen offers many other outstanding products, from direct drive rotary and linear products, to stepper and synchronous solutions. Even better, Kollmorgen can engineer the right solution for your needs. Ask our Customer Support Center today about a custom solution that fits your needs. Let the experts at Kollmorgen put a world of solutions at your fingertips.

**AKM11x**

The AKM1 frame size with "M" option connectivity and Smart Feedback Device (SFD).

**AKM22x**

The AKM2 frame size with "B" option connectivity, Commutating Encoder Feedback and optional brake.



The AKM3 frame size with "D" option connectivity and SFD Feedback.

**AKM41x**

The AKM4 frame size with "P" option connectivity and SFD Feedback.

**AKM52x**

The AKM5 frame size with "C" option connectivity and optional brake.

**AKM63x**

The AKM6 frame size with "C" option connectivity.

**AKM74x**

The AKM7 frame size with "C" option connectivity and optional brake.

**AKM83x**

The AKM8 frame size with "T" option connectivity.

AKM Washdown and Washdown Food Grade

These motor variants are used in applications that are subject to strict hygiene regulations in which it is essential that the formation of nuclei and corrosion are avoided and in which machines must be cleaned cyclically. These motors are based on the standard types AKM2 – AKM6 with special modifications for use in the food-processing industry, in the packaging industry, or even outdoors. An option for AKM Washdown and Washdown Food motors is to coat the flange.

AKM Washdown

Part Numbers:

AKMxxx-xxxx-0W: Washdown with unpainted flange

AKMxxx-Wxxxx-0W: Washdown with painted flange

Note: The AKM Washdown motors must not come into contact with any unpacked food.

Application Area:	Harsh Environments, Outdoors
Application Examples:	Transport in the food and packaging area without contact with food, Radar stations, wind turbines, offshore installations
Standards:	UL, CE, RoHS
Surface:	Gray 2K paint
Immunity:	Against tested industrial cleaning agents*, corrosion-resistant
Degree of Protection:	IP67
Shaft:	303 Stainless steel (CSN417029)
Rotary Shaft Seal:	PTFE
Lubricant:	Industrial bearing grease, non-food-grade
Connector:	Stainless steel, smooth surface
Screws:	Stainless steel
Name Plate:	Engraved, additional name plate in the package



AKM Washdown Food Grade

Part Numbers:

AKMxxx-xxxx-0F: Washdown with unpainted flange

AKMxxx-Wxxxx-0F: Washdown with painted flange

Note: The surface of the washdown food motor has passed all tests as per FDA Global Migration for indirect contact with food. Any direct contact with unpacked food is not permitted.

Application Examples:	Food and beverages industries; Cutting, packing, and filling without direct contact with food; Motor positioned laterally or below the food.
Standards:	UL, CE, RoHS, FDA
Surface:	White 2K FDA compliant paint**
Immunity:	Against tested industrial cleaning agents*, corrosion-resistant
Degree of Protection:	IP67
Shaft:	303 Stainless steel (CSN417029)
Rotary Shaft Seal:	PTFE as per FDA
Lubricant:	Food grade as per FDA
Connector:	Stainless steel, smooth surface
Screws:	Stainless steel
Name Plate:	Engraved, additional name plate in the package



* Resistance of the AKM Washdown and AKM Washdown Food Grade surfaces to the following industrial cleaning agents has been tested:

P3-topactive DES, P3-topactive LA, P3-topax56, P3-topax 66, P3-topax 91

**Meets FDA global migration standards

AKM Systems Overview

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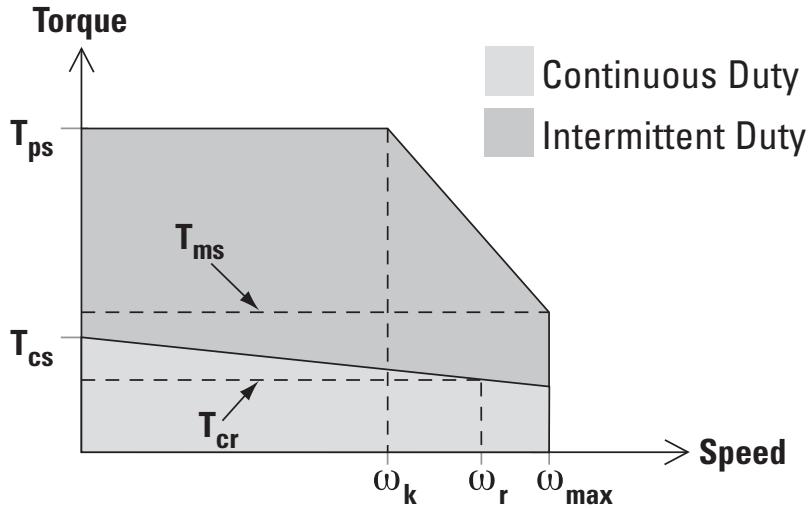

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Definitions

T_{ps}	- Peak stall torque for system
T_{ms}	- Peak torque at maximum speed
T_{cs}	- Continuous torque at stall
T_{cr}	- Continuous rated torque (torque at rated power)
ω_{max}	- Maximum speed
ω_r	- Rated speed (speed at rated power)
ω_k	- Speed at knee in peak envelope (intersection of system peak torque with voltage limit line)

How to Build a Servo Drive and Motor System

System torque/speed information on the following pages is designed to help you select the optimum brushless servomotor/drives combination. The nominal values in this data illustrate performance for the recommended motor/controller systems.

Drive and Motor Performance Curves

The performance characteristics of a brushless servo system (motor/drives combination) are described by a torque/speed operating envelope. As shown above, the shaded areas of the curve indicate the continuous duty and intermittent duty zones of the system.

Continuous Duty Zone

The continuous duty zone is bordered by the maximum continuous torque line up to the intersection with the intermittent duty line. The continuous torque line is set by either the motor's maximum rated temperature, or the drives' rated continuous current output, whichever is less. The system voltage line is set by the voltage rating of the drives, the line voltage supplied, and the motor winding. The system can operate on a continuous basis anywhere within this area, assuming the ambient temperature is 40°C or less.

Intermittent Duty Zone

The intermittent duty zone is bordered by the peak torque line and the system voltage line. The peak torque line is set by either the drives' peak current rating, which the drive can produce for a limited time, or the maximum rated peak current for the motor, whichever is less. Refer to the Rating Data on the pages that follow. Note: Higher torque levels may be achievable at higher power levels.

Consult Kollmorgen Customer Support for more details. The system voltage line is set by the voltage rating of the controller, the line voltage applied and the motor winding. Operation in the intermittent zone must be limited to a duty cycle that will produce an RMS system torque falling within the continuous duty area. The RMS torque value is a function of the magnitude of the intermittent torque and the percentage of the time spent at that torque.

The AKM™ brushless servomotor stands alone in the marketplace in terms of flexibility and performance advantages. Kollmorgen's culture of continuous improvement has paid dividends again. The AKM servomotor's innovative design has been polished and optimized. With the new AKD amplifier, the venerable AKM servomotor sets a new standard of refined servo performance, designed to deliver precise motion and more power for your money. Nowhere else will you find a more versatile and complete servo family to meet your needs and exceed your expectations.

Features

- Eight frame sizes (40 to 260 mm)
- 28 frame-stack length combinations
- 117 standard windings for 120/240/400/480 Vac operation as well as low-voltage DC options
- Flexible flange mount and shaft options
- Industry-leading low-cogging contributing to extreme smoothness
- Wide feedback options for high-performance and precision or rugged environments
- Unmatched customization – special windings, special shafts, and much more



AKD with AKM Plug-and-Play Feedback

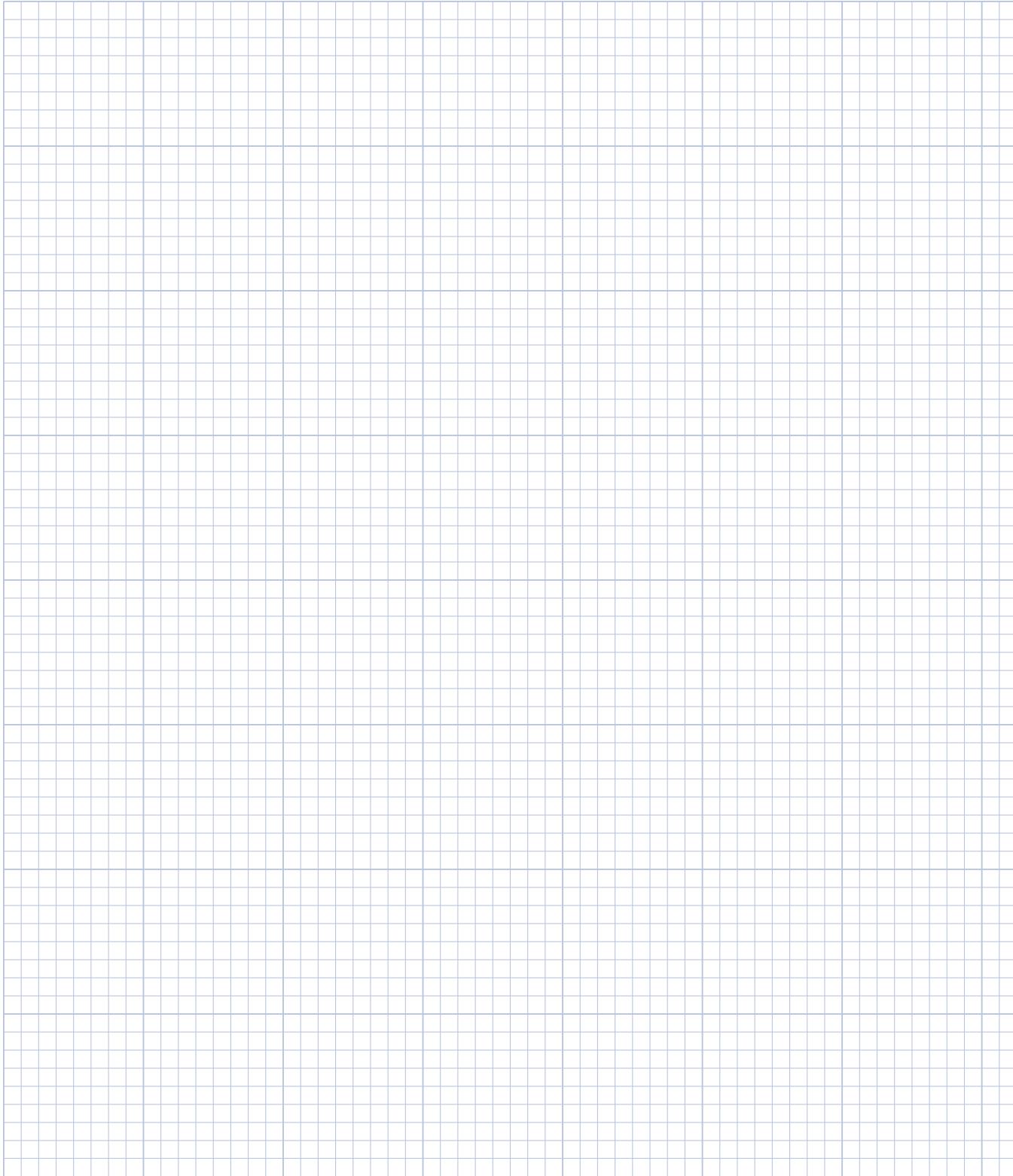
These feedback devices include electronic motor nameplates allowing plug-and-play commissioning, eliminating the need for drive parameter set-up and servo loop tuning in most applications.

Performance Data

AKM Motor		Single-turn Absolute			Multi-turn Absolute		
	AKM Motor	Accuracy (arc-min)	Resolution (bits)	Feedback Type	Accuracy (arc-min)	Resolution (bits)	Feedback Type
Value Line	AKM1	16	24	C	—	—	—
	AKM2-3	9	24	C	8	20	LB
	AKM4-8	9	24	C	4.66	21	LB
Performance Line	AKM2-4	1.0	27	DA	1.0	27	DB
	AKM5-8	0.333	27	DA	0.333	27	DB

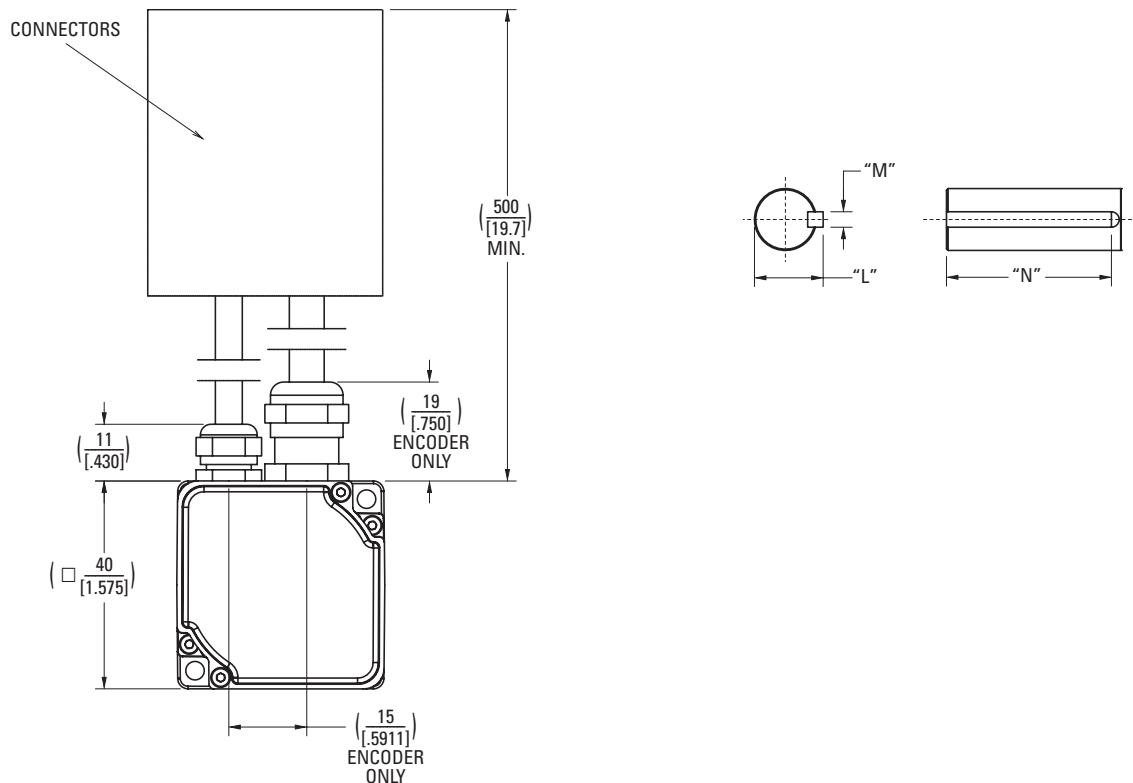
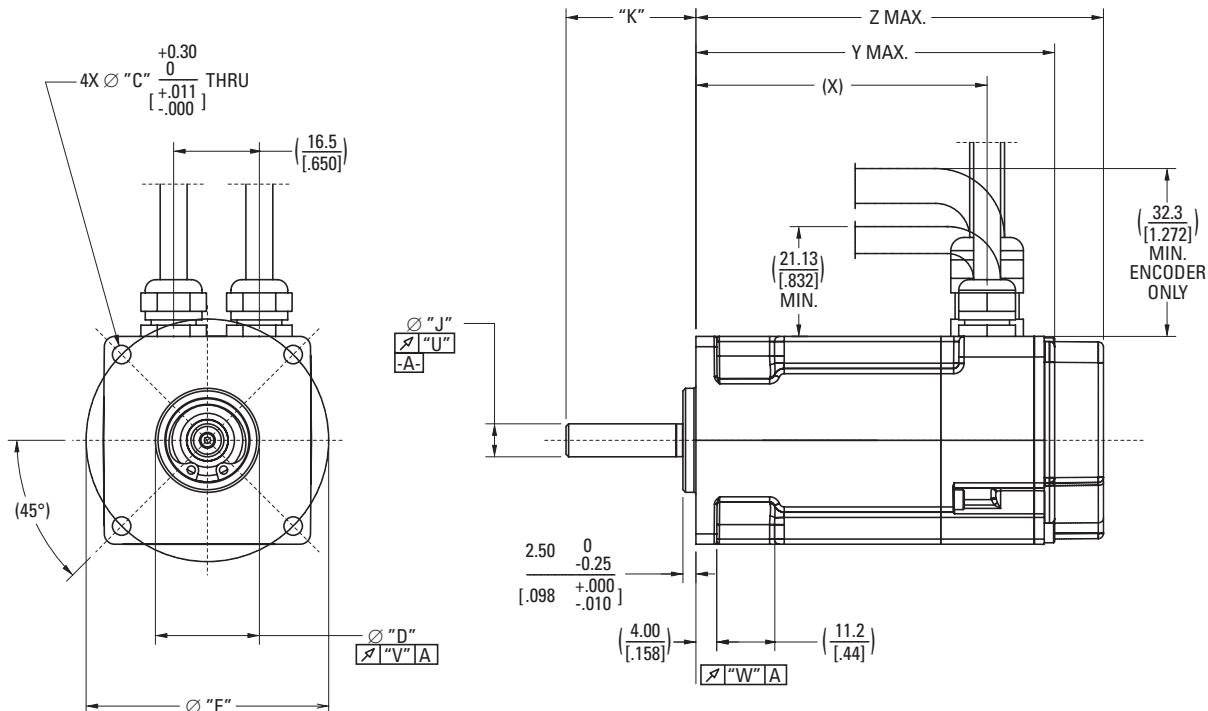
Note: Additional plug-and-play feedback options covered in the feedback devices section on page 60.

Notes



AKM1x Outline Drawings

AKM1x Frame



AKM1x Dimension Data

AKM1x Dimension Data

Mounting Code	"C"	"D"	"E"	"F"	"H"	"J"	"K"	"L"
AK	4.30 [.169]	30 0 -0.021 [1.1811 +.0000] -.0008 h7	46 [1.811]	—	—	8 0 -0.015 [.3150 +.0000] -.0006 h7	25 [.984]	9.20 0 -0.13 [.362 +.000] -.005
AN	4.30 [.169]	30 0 -0.021 [1.1811 +.0000] -.0008 h7	46 [1.811]	—	—	8 0 -0.015 [.3150 +.0000] -.0006 h7	25 [.984]	—
BN	356 [.140]	20.02 ± 0.02 [.788 ± .001]	46.69 [1.838]	—	—	6.350 0 -0.012 [.2500 +.0000] -.0005	25 [.984]	—
CK	3.40 [.134]	30 0 -0.021 [1.1811 +.0000] -.0008 h7	45 [1.772]	—	—	8 0 -0.015 [.3150 +.0000] -.0006 h7	25 [.984]	9.20 0 -0.13 [.362 +.000] -.005
CN	3.40 [.134]	30 0 -0.021 [1.1811 +.0000] -.0008 h7	45 [1.772]	—	—	8 0 -0.015 [.3150 +.0000] -.0006 h7	25 [.984]	—

Mounting Code	"M"	"N"
AK	3 0 -0.025 [.1181 +.0000] -.0010	14 0 -0.2 [.551 +.000] -.008
AN	—	—
BN	—	—
CK	3 0 -0.025 [.1181 +.0000] -.0010	14 0 -0.2 [.551 +.000] -.008
CN	—	—

MODEL	(X)	Y MAX (W/ RESOLVER)	Z MAX (W/ SFD OR ENCODER)
AKM11	56.1 [2.21]	69.6 [2.74]	79.0 [3.11]
AKM12	75.1 [2.96]	88.6 [3.49]	98.0 [3.86]
AKM13	94.1 [3.70]	107.6 [4.24]	117.0 [4.61]

Note 1: Dimensions are in mm [inches].

Note 2: Product designed in metric. English conversions provided for reference only.

AKM1x Performance Data

AKM1x Performance Data – Up to 320 Vdc

				AKM11			AKM12		AKM13	
Parameters	Tol	Symbol	Units	B	C	E	C	E	C	D
Max Rated DC Bus Voltage	Max	Vbus	Vdc	320	160	75	320	160	320	160
Continuous Torque (Stall) for ΔT winding = 100°C ①②⑦⑧	Nom	T _{cs}	Nm	0.183	0.185	0.185	0.310	0.310	0.409	0.401
Continuous Current (Stall) for ΔT winding = 100°C ①②⑦⑧	Nom	I _{cs}	A _{rms}	1.62	1.64	1.64	2.74	2.74	3.62	3.55
Continuous Torque (Stall) for ΔT winding = 60°C ②	Nom	T _{cs}	Nm	0.146	0.148	0.148	0.248	0.248	0.327	0.320
			Ib-in	1.29	1.31	1.31	2.19	2.19	2.89	2.83
Max Mechanical Speed ⑤	Nom	N _{max}	rpm	8000	8000	8000	8000	8000	8000	8000
Peak Torque ①②	Nom	T _p	Nm	0.609	0.614	0.611	1.08	1.08	1.46	1.44
			Ib-in	5.39	5.43	5.41	9.6	9.6	12.9	12.7
Peak Current	Nom	I _p	A _{rms}	4.65	5.79	11.6	6.06	10.9	5.93	9.6
75 Vdc		Rated Torque (speed) ①②⑦⑧⑨	T _{rtd}	Nm	-	-	0.176	-	0.309	-
				Ib-in	-	-	1.56	-	2.73	-
160 Vdc		Rated Speed	N _{rtd}	rpm	-	-	600	-	3000	-
				kW	-	-	0.11	-	0.10	-
320 Vdc		Rated Power (speed) ①②⑦⑧	P _{rtd}	Hp	-	-	0.15	-	0.13	-
				Nm	0.180	0.176	-	0.304	0.279	0.407
560 Vdc		Rated Torque (speed) ①②⑦⑧⑨	T _{rtd}	Ib-in	1.59	1.56	-	2.69	2.47	3.60
				Nm	-	-	-	-	-	3.23
640 Vdc		Rated Speed	N _{rtd}	rpm	4000	6000	-	4000	8000	3000
				kW	0.08	0.11	-	0.13	0.23	0.13
640 Vdc		Rated Power (speed) ①②⑦⑧	P _{rtd}	Hp	0.10	0.15	-	0.17	0.31	0.17
				Ib-in	1.48	-	-	2.47	-	0.41
640 Vdc		Rated Torque (speed) ①②⑦⑧⑨	T _{rtd}	Nm	-	-	-	-	-	-
				Ib-in	-	-	-	-	-	-
640 Vdc		Rated Speed	N _{rtd}	rpm	-	-	-	-	-	-
				kW	-	-	-	-	-	-
640 Vdc		Rated Power (speed) ①②⑦⑧	P _{rtd}	Hp	-	-	-	-	-	-
				Nm	-	-	-	-	-	-
640 Vdc		Rated Torque (speed) ①②⑦⑧⑨	T _{rtd}	Ib-in	-	-	-	-	-	-
				Nm	-	-	-	-	-	-
640 Vdc		Rated Speed	N _{rtd}	rpm	-	-	-	-	-	-
				kW	-	-	-	-	-	-
640 Vdc		Rated Power (speed) ①②⑦⑧	P _{rtd}	Hp	-	-	-	-	-	-
				Ib-in	-	-	-	-	-	-

See following page for notes.

AKM1x Performance Data – Up to 320 Vdc (Continued)

Parameters	Tol	Symbol	Units	AKM11			AKM12		AKM13	
				B	C	E	C	E	C	D
Torque Constant ①	±10%	K _t	Nm/A _{rms}	0.158	0.129	0.064	0.207	0.112	0.278	0.169
			lb-in/A _{rms}	1.40	1.14	0.57	1.83	0.99	2.46	1.50
Back EMF Constant ⑥	±10%	K _e	V/k _{rpm}	10.2	8.3	4.1	13.3	7.2	17.9	10.9
Motor Constant	Nom	K _m	N-m/√W	0.0302	0.0303	0.0296	0.0480	0.0463	0.0618	0.0593
			lb-in/√W	0.267	0.268	0.262	0.425	0.410	0.547	0.525
Resistance (line-line) ⑥	±10%	R _m	ohm	18.23	12.11	3.11	12.4	3.9	13.5	5.41
Inductance (line-line)		L	mH	12.5	8.3	2.04	9.1	2.7	10.3	3.8
Inertia (includes Resolver feedback) ③	±10%	J _m	kg-cm ²	0.017			0.031		0.045	
			lb-in-s ²	1.5E-05			2.7E-05		4.0E-05	
Optional Brake Inertia (additional)	±10%	J _m	kg-cm ²	-			-		-	
			lb-in-s ²	-			-		-	
Weight		W	kg	0.35			0.49		0.63	
			lb	0.8			1.1		1.4	
Static Friction ①⑨		T _f	Nm	0.0011			0.0021		0.0031	
			lb-in	0.01			0.02		0.03	
Viscous Damping ①		K _{dv}	Nm/k _{rpm}	0.0005			0.001		0.0015	
			lb-in/k _{rpm}	0.004			0.009		0.013	
Thermal Time Constant		TCT	minutes	4			6		7	
Thermal Resistance		R _{thw-a}	°C/W	1.83			1.63		1.53	
Pole Pairs				3			3		3	
Heat Sink Size				10"x10"x1/4" Aluminum Plate			10"x10"x1/4" Aluminum Plate		10"x10"x1/4" Aluminum Plate	

Notes:

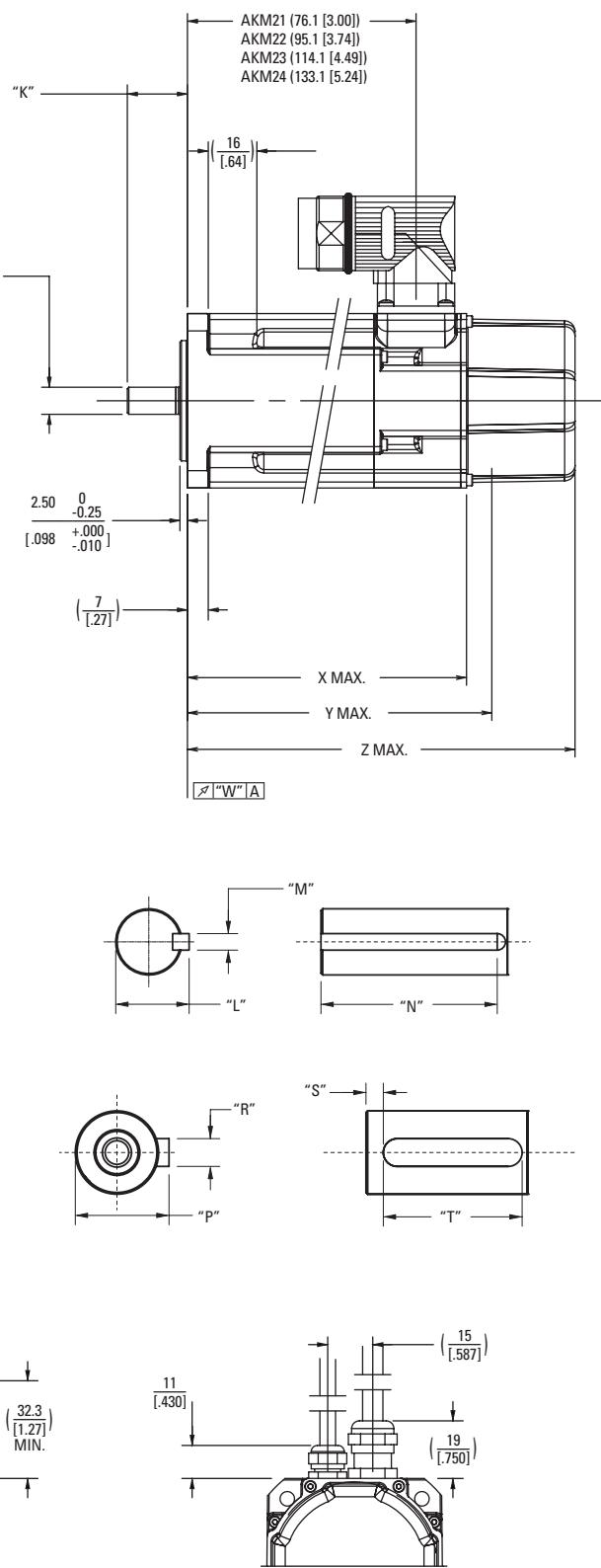
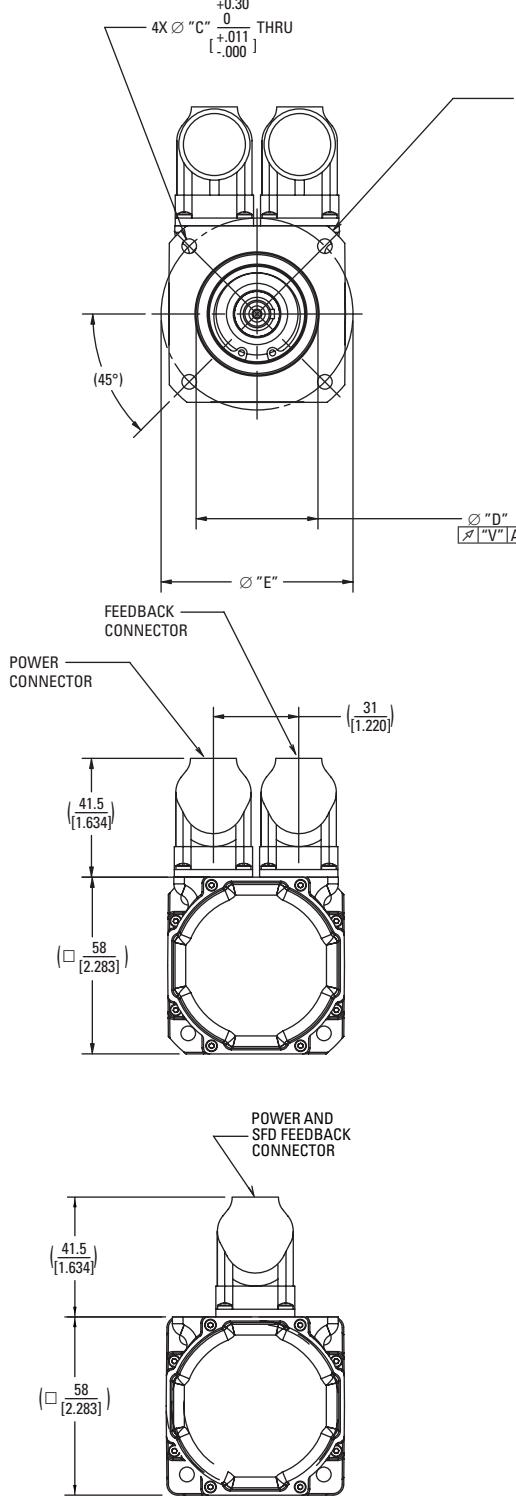
- ① Motor winding temperature rise, $\Delta T=100^{\circ}\text{C}$, at 40°C ambient.
- ② All data referenced to sinusoidal commutation.
- ③ Add parking brake if applicable for total inertia.
- ④ Motor with standard heat sink.
- ⑤ May be limited at some values of Vbus.
- ⑥ Measured at 25°C .
- ⑦ No brake motor option on AKM1.
- ⑧ For non-resolver feedback options: no continuous torque reduction.
- ⑨ For motors with optional shaft seal, reduce torque shown by 0.021 Nm (0.19 lb-in), and increase T_f by the same amount.

Additional Notes: See system data beginning on page 14 for typical torque/speed performance.

Additional windings can be found through our online Motioneer sizing and selection software tool. See page 73 for more information.

AKM2x Outline Drawings

AKM2x Frame



AKM2x Dimension Data

AKM2x Dimension Data

Mounting Code	"C"	"D"	"E"	"F"	"H"	"J"	"K"	"L"
AC	4.80 [.189]	40 ^{+0.011} _{-0.005} [1.5748 ^{+0.004} _{-0.002}]	j6	63 [2.480]	74 [2.913]	D M3 DIN 332	9 ^{+0.010} _{+0.001} [.3543 ^{+0.004} _{+0.000}]	k6
AN	4.80 [.189]	40 ^{+0.011} _{-0.005} [1.5748 ^{+0.004} _{-0.002}]	j6	63 [2.480]	74 [2.913]	D M3 DIN 332	9 ^{+0.010} _{+0.001} [.3543 ^{+0.004} _{+0.000}]	k6
BN	5.10 [.201]	38.10 ⁰ _{-0.05} [1.500 ^{+0.000} _{-0.002}]		66.68 [2.625]	—	—	9.525 ⁺⁰ _{-0.013} [.3750 ^{+0.000} _{-0.005}]	31.75 ± 0.79 [1.250 ± .031]
CK	5.80 [.228]	50 ⁰ _{-0.016} [1.9685 ^{+0.000} _{-0.006}]	h6	70 [2.756]	—	—	14 ⁺⁰ _{-0.011} [.5512 ^{+0.000} _{-0.004}]	h6
DC	5.80 [.228]	40 ^{+0.011} _{-0.005} [1.5748 ^{+0.004} _{-0.002}]	j6	65 [2.559]	—	D M3 DIN 332	9 ^{+0.010} _{+0.001} [.3543 ^{+0.004} _{+0.000}]	k6
DN	5.80 [.228]	40 ^{+0.011} _{-0.005} [1.5748 ^{+0.004} _{-0.002}]	j6	65 [2.559]	—	D M3 DIN 332	9 ^{+0.010} _{+0.001} [.3543 ^{+0.004} _{+0.000}]	k6
EN & EF	5.10 [.201]	38.10 ⁰ _{-0.05} [1.500 ^{+0.000} _{-0.002}]		66.68 [2.625]	—	—	9.525 ⁺⁰ _{-0.013} [.3750 ^{+0.000} _{-0.005}]	20.57 ± 0.25 [0.810 ± 0.010]

Mounting Code	"M"	"N"	"P"	"R"	"S"	"T"	"U"	"V"	"W"
AC	—	—	10.2 ⁰ _{-0.13} [.402 ^{+0.00} _{-0.005}]	3 ⁰ _{-0.025} [.1181 ^{+0.000} _{-0.010}]	300 [118]	12 ⁰ _{-0.20} [.472 ^{+0.00} _{-0.008}]	0.030 [.0011]	0.060 [.0023]	0.060 [.0023]
AN	—	—	—	—	—	—	0.030 [.0011]	0.060 [.0023]	0.060 [.0023]
BN	—	—	—	—	—	—	0.051 [.0020]	0.10 [.004]	0.10 [.004]
CK	5 ⁰ _{-0.03} [.197 ^{+0.000} _{-0.001}]	N9	20 ⁰ _{-0.02} [.787 ^{+0.00} _{-0.008}]	—	—	—	0.035 [.0013]	0.080 [.0031]	0.080 [.0031]
DC	—	—	10.2 ⁰ _{-0.13} [.402 ^{+0.00} _{-0.005}]	3 ⁰ _{-0.025} [.1181 ^{+0.000} _{-0.010}]	300 [118]	12 ⁰ _{-0.20} [.472 ^{+0.00} _{-0.008}]	0.030 [.0011]	0.060 [.0023]	0.060 [.0023]
DN	—	—	—	—	—	—	0.030 [.0011]	0.060 [.0023]	0.060 [.0023]
EN & EF	—	—	—	—	—	—	0.051 [.0020]	0.10 [.004]	0.10 [.004]

MODEL	(X MAX) ("C" Connector Option W/ Resolver)	Y MAX	Z MAX (W/ BRAKE)
AKM21	86.2 [3.39]	95.4 [3.76]	129.5 [5.10]
AKM22	105.2 [4.14]	114.4 [4.50]	148.5 [5.85]
AKM23	124.2 [4.89]	133.4 [5.25]	167.5 [6.59]
AKM24	143.2 [5.64]	152.4 [6.00]	186.5 [7.34]

Note: Dimensions are in mm [inches]. Product designed in metric. English conversions provided for reference only.

AKM2x Performance Data

AKM2x Performance Data – Up to 640 Vdc

Parameters	Tol	Symbol	Units	AKM21			AKM22			AKM23			AKM24		
				C	E	G	C	E	G	D	E	F	D	E	F
Max Rated DC Bus Voltage	Max	Vbus	Vdc	320	160	75	640	320	160	640	320	320	640	320	320
Continuous Torque (Stall) for ΔT winding = 100°C ①②⑦⑧⑨	Nom	T _{cs}	Nm	0.48	0.50	0.50	0.84	0.87	0.88	1.16	1.16	1.18	1.41	1.40	1.42
Continuous Current (Stall) for ΔT winding = 100°C ①②⑦⑧⑨	Nom	I _{cs}	Arms	4.2	4.4	4.4	7.4	7.7	7.8	10.3	10.3	10.4	12.5	12.4	12.6
Continuous Torque (Stall) for ΔT winding = 60°C ②	Nom	T _{cs}	Nm	0.38	0.40	0.40	0.67	0.70	0.70	0.92	0.93	0.94	1.13	1.12	1.14
Max Mechanical Speed ⑤	Nom	N _{max}	rpm	8000	8000	8000	8000	8000	8000	8000	8000	8000	8000	8000	8000
Peak Torque ①②	Nom	T _p	Nm	1.47	1.49	1.51	2.73	2.76	2.79	3.84	3.86	3.88	4.76	4.79	4.82
Peak Current	Nom	I _p	Arms	13.0	13.2	13.4	24.2	24.4	24.7	34.0	34.2	34.3	42.1	42.4	42.7
75 Vdc	Rated Torque (speed) ①②⑦⑧⑨⑩	T _{rtd}	Nm	-	0.48	0.46	-	0.85	0.83	-	-	1.15	-	-	1.39
			lb-in	-	4.2	4.1	-	7.5	7.4	-	-	10.2	-	-	12.3
	Rated Speed	N _{rtd}	rpm	-	2000	4000	-	1000	2500	-	-	1500	-	-	1000
	Rated Power (speed) ①②⑦⑧⑨	P _{rtd}	kW	-	0.10	0.19	-	0.09	0.22	-	-	0.18	-	-	0.15
160 Vdc	Rated Torque (speed) ①②⑦⑧⑨⑩	T _{rtd}	Nm	0.46	0.41	-	0.83	0.81	0.74	1.12	1.1	1.07	1.36	1.34	1.33
			lb-in	4.0	3.7	-	7.3	7.1	6.5	9.9	9.7	9.5	12.0	11.9	11.8
	Rated Speed	N _{rtd}	rpm	2500	7000	-	1000	3500	7000	1500	2500	4500	1500	2000	3000
	Rated Power (speed) ①②⑦⑧⑨	P _{rtd}	kW	0.12	0.30	-	0.09	0.30	0.54	0.18	0.29	0.50	0.21	0.28	0.42
320 Vdc	Rated Torque (speed) ①②⑦⑧⑨⑩	T _{rtd}	Nm	0.39	-	-	0.78	.70	-	1.03	0.98	0.94	1.29	1.24	1.12
			lb-in	3.4	-	-	6.9	6.2	-	9.1	8.7	8.3	11.4	11.0	9.9
	Rated Speed	N _{rtd}	rpm	8000	-	-	3500	8000	-	5000	6500	8000	4000	5500	8000
	Rated Power (speed) ①②⑦⑧⑨	P _{rtd}	kW	0.32	-	-	0.29	0.59	-	0.54	0.67	0.79	0.54	0.71	0.94
560 Vdc	Rated Torque (speed) ①②⑦⑧⑨⑩	T _{rtd}	Nm	-	-	-	0.68	-	-	0.92	-	-	1.11	-	-
			lb-in	-	-	-	6.0	-	-	8.1	-	-	9.8	-	-
	Rated Speed	N _{rtd}	rpm	-	-	-	8000	-	-	8000	-	-	8000	-	-
	Rated Power (speed) ①②⑦⑧⑨	P _{rtd}	kW	-	-	-	0.57	-	-	0.77	-	-	0.93	-	-
640 Vdc	Rated Torque (speed) ①②⑦⑧⑨⑩	T _{rtd}	Nm	-	-	-	0.68	-	-	0.92	-	-	1.11	-	-
			lb-in	-	-	-	6.0	-	-	8.1	-	-	9.8	-	-
	Rated Speed	N _{rtd}	rpm	-	-	-	8000	-	-	8000	-	-	8000	-	-
	Rated Power (speed) ①②⑦⑧⑨	P _{rtd}	kW	-	-	-	0.57	-	-	0.77	-	-	0.93	-	-

See following page for notes.

AKM2x Performance Data – Up to 640 Vdc (Continued)

Parameters	Tol	Symbol	Units	AKM21			AKM22			AKM23			AKM24		
				C	E	G	C	E	G	D	E	F	D	E	F
Torque Constant ①	±10%	K _t	Nm/Arms	0.30	0.16	0.10	0.61	0.32	0.18	0.52	0.42	0.27	0.63	0.50	0.36
			lb-in/Arms	2.7	1.4	0.9	5.4	2.8	1.6	4.6	3.7	2.4	5.6	4.4	3.2
Back EMF Constant ⑥	±10%	K _e	V/k rpm	19.5	10.2	6.6	39	20.4	11.7	33.8	27.0	17.6	40.8	32.5	23.4
			N-m/VW	0.0679	0.0706	0.0680	0.111	0.114	0.110	0.143	0.147	0.144	0.171	0.175	0.171
Motor Constant	Nom	K _m	lb-in/VW	0.601	0.625	0.602	0.986	1.01	0.98	1.27	1.30	1.28	1.52	1.55	1.52
			ohm	13	3.42	1.44	19.98	5.22	1.77	8.77	5.44	2.34	9.02	5.44	2.94
Inductance (line-line)		L	mH	19	5.2	2.18	35.5	9.7	3.19	17.3	11.1	4.68	18.7	11.8	6.16
Inertia (includes Resolver feedback) ③	±10%	J _m	kg-cm ²	0.11			0.16			0.22			0.27		
			lb-in-s ²	9.5E-05			1.4E-04			1.9E-04			2.4E-04		
Optional Brake Inertia (additional)	±10%	J _m	kg-cm ²	0.012			0.012			0.012			0.012		
			lb-in-s ²	1.1E-05			1.1E-05			1.1E-05			1.1E-05		
Weight	W		kg	0.82			1.1			1.38			1.66		
			lb	1.8			2.4			3.0			3.7		
Static Friction ①⑩	T _f		Nm	0.002			0.005			0.007			0.01		
			lb-in	0.02			0.04			0.06			0.09		
Viscous Damping ①	K _{dv}		Nm/k rpm	0.0046			0.0055			0.0065			0.0074		
			lb-in/k rpm	0.04			0.05			0.06			0.07		
Thermal Time Constant	TCT		minutes	8			9			1.			11		
Thermal Resistance	R _{thw-a}		°C/W	1.43			1.19			1.10			1.07		
Pole Pairs				3			3			3			3		
Heat Sink Size				10"x10"x1/4" Aluminum Plate			10"x10"x1/4" Aluminum Plate			10"x10"x1/4" Aluminum Plate			10"x10"x1/4" Aluminum Plate		

Notes:

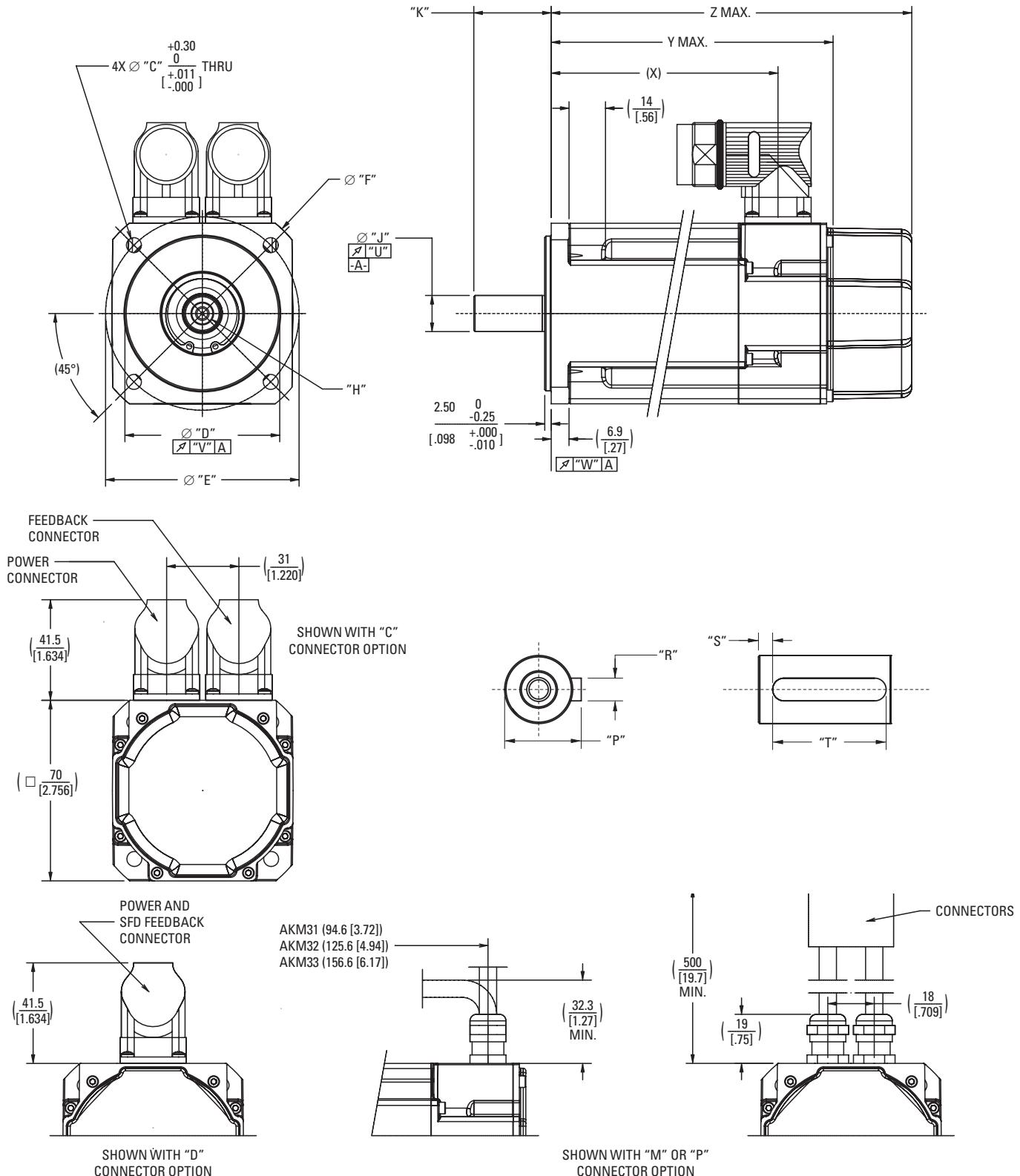
- ① Motor winding temperature rise, $\Delta T=100^\circ\text{C}$, at 40°C ambient.
- ② All data referenced to sinusoidal commutation.
- ③ Add parking brake if applicable for total inertia.
- ④ Motor with standard heat sink.
- ⑤ May be limited at some values of Vbus.
- ⑥ Measured at 25°C .
- ⑦ Brake motor option reduces continuous torque ratings by:
 $\text{AKM21} = 0.00 \quad \text{AKM22} = 0.01 \text{ Nm} \quad \text{AKM23} = 0.02 \text{ Nm} \quad \text{AKM24} = 0.05 \text{ Nm}$
- ⑧ For non-resolver feedback options: no continuous torque reduction.
- ⑨ Motors with non-resolver feedback and brake option, reduce continuous torque by:
 $\text{AKM21} = 0.00 \quad \text{AKM22} = 0.02 \text{ Nm} \quad \text{AKM23} = 0.05 \text{ Nm} \quad \text{AKM24} = 0.12 \text{ Nm}$
- ⑩ For motors with optional shaft seal, reduce torque shown by 0.047 Nm (0.41 lb-in), and increase T_f by the same amount.

Additional Notes: See system data beginning on page 14 for typical torque/speed performance.

Additional windings can be found through our online Motioneer sizing and selection software tool. See page 73 for more information.

AKM3x Outline Drawings

AKM3x Frame



AKM3x Dimension Data

AKM3x Dimension Data

Mounting Code	"C"	"D"	"E"	"F"	"H"	"J"	"K"	"P"
AC	5.80 [.228]	60 ^{+0.012} _{-0.007} [2.3622 ^{+0.004} _{-0.002}] j6	75 [2.953]	90 [3.543]	D M5 DIN 332	14 ^{+0.012} _{+0.001} [.5512 ^{+0.005} _{+0.000}] k6	30.0 [1.181]	16 ⁰ _{-0.13} [.630 ^{+0.00} _{-.005}]
AN	5.80 [.228]	60 ^{+0.012} _{-0.007} [2.3622 ^{+0.004} _{-0.002}] j6	75 [2.953]	90 [3.543]	D M5 DIN 332	14 ^{+0.012} _{+0.001} [.5512 ^{+0.005} _{+0.000}] k6	30.0 [1.181]	—
CC	5.80 [.228]	60 ^{+0.012} _{-0.007} [2.3622 ^{+0.004} _{-0.002}] j6	85 [3.346]	—	D M5 DIN 332	14 ^{+0.012} _{+0.001} [.5512 ^{+0.005} _{+0.000}] k6	30.0 [1.181]	16 ⁰ _{-0.13} [.630 ^{+0.00} _{-.005}]
CN	5.80 [.228]	60 ^{+0.012} _{-0.007} [2.3622 ^{+0.004} _{-0.002}] j6	85 [3.346]	—	D M5 DIN 332	14 ^{+0.012} _{+0.001} [.5512 ^{+0.005} _{+0.000}] k6	30.0 [1.181]	—
GC	5.80 [.228]	60 ^{+0.012} _{-0.007} [2.3622 ^{+0.004} _{-0.002}] j6	75 [2.953]	90 [3.543]	D M5 DIN 332	11 ^{+0.012} _{+0.001} [.4331 ^{+0.005} _{+0.000}] k6	23 [.906]	12.5 ⁰ _{-0.13} [.492 ^{+0.00} _{-.005}]
GN	5.80 [.228]	60 ^{+0.012} _{-0.007} [2.3622 ^{+0.004} _{-0.002}] j6	75 [2.953]	90 [3.543]	D M5 DIN 332	11 ^{+0.012} _{+0.001} [.4331 ^{+0.005} _{+0.000}] k6	23 [.906]	—

Mounting Code	"R"	"S"	"T"	"U"	"V"	"W"
AC	5 ⁰ [-0.03 [.197 +.000 -.001]] N9	5.00 [1.97]	20 ⁰ [-0.20 [.787 +.000 -.008]]	0.035 [.0013]	0.080 [.0031]	0.080 [.0031]
AN	—	—	—	0.035 [.0013]	0.080 [.0031]	0.080 [.0031]
CC	5 ⁰ [-0.03 [.197 +.000 -.001]] N9	5.00 [1.97]	20 ⁰ [-0.20 [.787 +.000 -.008]]	0.035 [.0013]	0.080 [.0031]	0.080 [.0031]
CN	—	—	—	0.035 [.0013]	0.080 [.0031]	0.080 [.0031]
GC	4 ⁰ [-0.03 [.157 +.000 -.001]] N9	3.5 [1.138]	16 ⁰ [-0.20 [.630 +.000 -.008]]	0.035 [.0013]	0.080 [.0031]	0.080 [.0031]
GN	—	—	—	0.035 [.0013]	0.080 [.0031]	0.080 [.0031]
CN	—	—	—	0.035 [.0013]	0.080 [.0031]	0.080 [.0031]

MODEL	(X)	Y MAX	Z MAX (W/BRAKE)
AKM31	87.9 [3.46]	109.8 [4.32]	141.3 [5.56]
AKM32	118.9 [4.68]	140.8 [5.54]	172.3 [6.78]
AKM33	149.9 [5.90]	171.8 [6.76]	203.3 [8.00]

Note 1: Dimensions are in mm [inches].

Note 2: Product designed in metric. English conversions provided for reference only.

AKM3x Performance Data

AKM3x Performance Data – Up to 640 Vdc

				AKM31			AKM32			AKM33			
Parameters		Tol	Symbol	Units	C	E	H	C	E	H	C	E	H
Max Rated DC Bus Voltage	Max	Vbus	Vdc	640	320	160	640	640	320	640	640	320	
Continuous Torque (Stall) for ΔT winding = 100°C ①②⑦⑧⑨	Nom	T_{cs}	Nm	1.15	1.20	1.23	2.00	2.04	2.10	2.71	2.79	2.88	
Continuous Current (Stall) for ΔT winding = 100°C ①②⑦⑧⑨			lb-in	10.2	10.6	10.8	17.7	18.1	18.6	24.0	24.7	25.5	
Continuous Current (Stall) for ΔT winding = 100°C ①②⑦⑧⑨	Nom	I_{cs}	Arms	1.37	2.99	5.85	1.44	2.82	5.50	1.47	2.58	5.62	
Continuous Torque (Stall) for ΔT winding = 60°C ②	Nom	T_{cs}	Nm	0.92	0.96	0.98	1.60	1.63	1.68	2.17	2.23	2.30	
Continuous Torque (Stall) for ΔT winding = 60°C ②			lb-in	8.1	8.5	8.7	14.2	14.4	14.9	19.2	19.7	20.4	
Max Mechanical Speed ⑤	Nom	N_{max}	rpm	8000	8000	8000	8000	8000	8000	8000	8000	8000	
Peak Torque ①②	Nom	T_p	Nm	3.88	4.00	4.06	6.92	7.11	7.26	9.76	9.96	10.22	
Peak Torque ①②			lb-in	34.3	35.4	35.9	61.2	62.9	64.3	86.4	88.1	90.5	
Peak Current	Nom	I_p	Arms	5.5	12.0	23.4	5.7	11.3	22.0	5.9	10.3	22.5	
75 Vdc	Rated Torque (speed) ①②⑦⑧⑨⑩	T_{rtd}	Nm	-	1.19	1.20	-	-	2.06	-	-	2.82	
			lb-in	-	10.5	10.6	-	-	18.2	-	-	24.6	
	Rated Speed	N_{rtd}	rpm	-	750	2000	-	-	1200	-	-	800	
160 Vdc	Rated Power (speed) ①②⑦⑧⑨	P_{rtd}	kW	-	0.09	0.25	-	-	0.26	-	-	0.24	
			Hp	-	0.13	0.34	-	-	0.35	-	-	0.32	
	Rated Torque (speed) ①②⑦⑧⑨⑩	T_{rtd}	Nm	-	1.17	0.97	-	2.01	1.96	-	-	2.66	
250 Vdc	Rated Speed	N_{rtd}	lb-in	-	10.3	8.6	-	17.7	17.4	-	-	23.5	
			rpm	-	2500	6000	-	1000	3000	-	-	2500	
	Rated Power (speed) ①②⑦⑧⑨	P_{rtd}	kW	-	0.31	0.61	-	0.21	0.62	-	-	0.70	
350 Vdc	Rated Torque (speed) ①②⑦⑧⑨⑩	T_{rtd}	Hp	-	0.41	0.82	-	0.28	0.83	-	-	0.93	
			Nm	1.12	0.95	-	1.95	1.91	1.45	2.64	2.62	2.27	
			lb-in	9.9	8.4	-	17.3	16.9	12.8	23.4	23.2	20.1	
450 Vdc	Rated Speed	N_{rtd}	rpm	2500	6000	-	1500	3000	7000	1000	2000	5500	
	Rated Power (speed) ①②⑦⑧⑨	P_{rtd}	kw	0.29	0.60	-	0.31	0.6	1.06	0.28	0.55	1.31	
			Hp	0.39	0.80	-	0.41	0.80	1.42	0.37	0.74	1.75	
550 Vdc	Rated Torque (speed) ①②⑦⑧⑨⑩	T_{rtd}	Nm	1.00	-	-	1.86	1.50	-	2.54	2.34	-	
	lb-in	8.9	-	-	16.5	13.3	-	22.5	20.7	-			
	Rated Speed	N_{rtd}	rpm	5000	-	-	3000	6500	-	2000	4500	-	
650 Vdc	Rated Power (speed) ①②⑦⑧⑨	P_{rtd}	kW	0.52	-	-	0.58	1.02	-	0.53	1.10	-	
			Hp	0.70	-	-	0.78	1.37	-	0.71	1.48	-	
	Rated Torque (speed) ①②⑦⑧⑨⑩	T_{rtd}	Nm	0.91	-	-	1.83	1.22	-	2.50	2.27	-	
750 Vdc	Rated Speed	N_{rtd}	lb-in	8.1	-	-	16.2	10.8	-	22.1	20.1	-	
			rpm	6000	-	-	3500	8000	-	2500	5000	-	
	Rated Power (speed) ①②⑦⑧⑨	P_{rtd}	kW	0.57	-	-	0.67	1.02	-	0.65	1.19	-	
	Hp	0.77	-	-	0.90	1.37	-	0.88	1.59	-			

See following page for notes.

AKM3x Performance Data – Up to 640 Vdc (Continued)

Parameters	Tol	Symbol	Units	AKM31			AKM32			AKM33		
				C	E	H	C	E	H	C	E	H
Torque Constant ①	±10%	K _t	Nm/A _{rms}	0.85	0.41	0.21	1.40	0.73	0.39	1.86	1.10	0.52
			lb-in/A _{rms}	7.5	3.6	1.9	12.4	6.5	3.5	16.5	9.7	4.6
Back EMF Constant ②	±10%	K _e	V/k _{rpm}	54.5	26.1	13.7	89.8	47.1	24.8	120	70.6	33.4
Motor Constant	Nom	K _m	N·m/√W	0.150	0.154	0.151	0.235	0.237	0.245	0.295	0.299	0.303
			lb-in/√W	1.33	1.36	1.34	2.08	2.10	2.17	2.61	2.65	2.68
Resistance (line-line) ⑥	±10%	R _m	ohm	21.4	4.74	1.29	23.76	6.32	1.69	26.59	9.01	1.96
Inductance (line-line)		L	mH	37.5	8.6	2.4	46.5	12.8	3.55	53.6	18.5	4.1
Inertia (includes Resolver feedback) ③	±10%	J _m	kg·cm ²	0.33			0.59			0.85		
			lb-in·s ²	2.9E-04			5.2E-04			7.5E-04		
Optional Brake Inertia (additional)	±10%	J _m	kg·cm ²	0.012			0.012			0.012		
			lb-in·s ²	1.1E-05			1.1E-05			1.1E-05		
Weight		W	kg	1.55			2.23			2.9		
			lb	3.4			4.9			6.4		
Static Friction ①⑩		T _f	Nm	0.014			0.02			0.026		
			lb-in	0.12			0.18			0.23		
Viscous Damping ①		K _{dv}	Nm/k _{rpm}	0.002			0.003			0.004		
			lb-in/k _{rpm}	0.02			0.03			0.04		
Thermal Time Constant		TCT	minutes	14			17			20		
Thermal Resistance		R _{thw-a}	°C/W	1.11			0.92			0.78		
Pole Pairs				4			4			4		
Heat Sink Size				10" x 10" x 1/4" Aluminum Plate			10" x 10" x 1/4" Aluminum Plate			10" x 10" x 1/4" Aluminum Plate		

Notes:

① Motor winding temperature rise, $\Delta T=100^{\circ}\text{C}$, at 40°C ambient.

② All data referenced to sinusoidal commutation.

③ Add parking brake if applicable for total inertia.

④ Motor with standard heat sink.

⑤ May be limited at some values of Vbus.

⑥ Measured at 25°C .

⑦ Brake motor option reduces continuous torque ratings by:

AKM31 = 0.0 Nm AKM32 = 0.05 Nm AKM33 = 0.1 Nm

⑧ For non-resolver feedback options: no continuous torque reduction.

⑨ Motors with non-resolver feedback and brake option, reduce continuous torque by:

AKM31 = 0.0 Nm AKM32 = 0.1 Nm AKM33 = 0.2 Nm

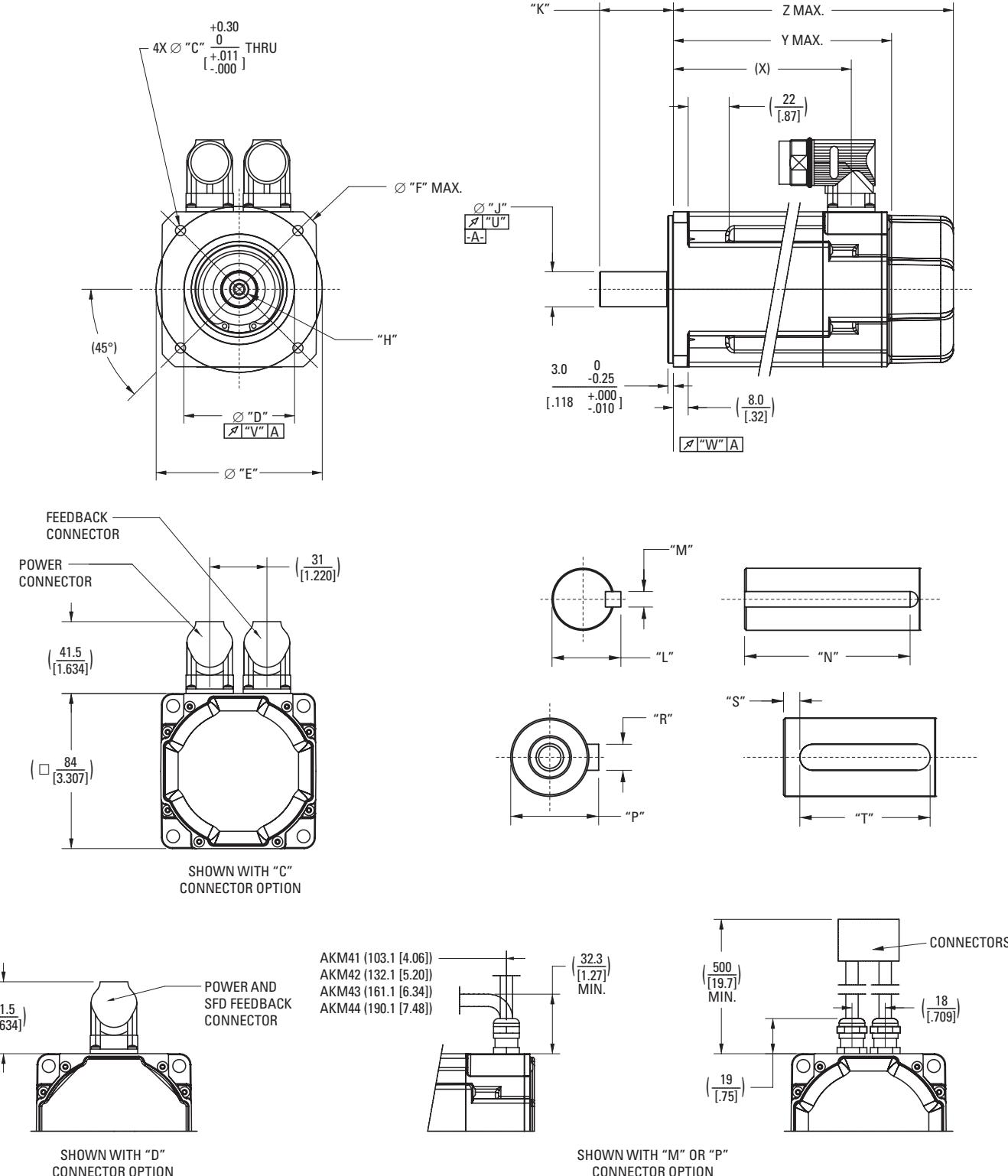
⑩ For motors with optional shaft seal, reduce torque shown by 0.047 Nm (0.41 lb-in), and increase T_f by the same amount.

Additional Notes: See system data beginning on page 14 for typical torque/speed performance.

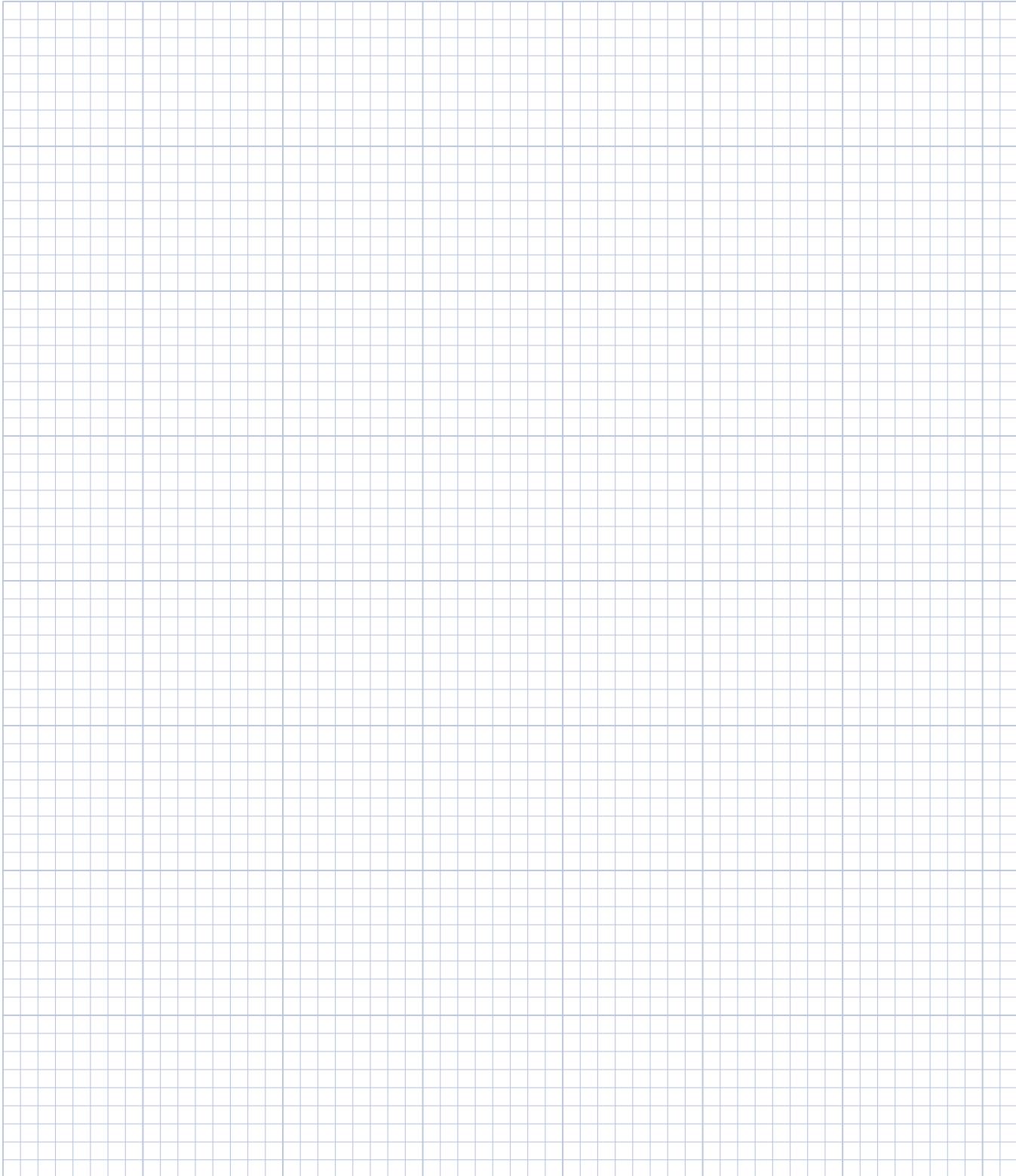
Additional windings can be found through our online Motioneering sizing and selection software tool. See page 73 for more information.

AKM4x Outline Drawings

AKM4x Frame



Notes



AKM4x Dimension Data

AKM4x Dimension Data

Mounting Code	"C"	"D"	"E"	"F"	"H"	"J"	"K"	"L"	
AC	7 [.276]	80 ^{+0.012} _{-0.007} ^{+0.004} _{-0.002} [3.1496 -.0002]	j6	100 [3.937]	—	D M6 DIN 332	19 ^{+0.015} _{-0.013} ^{+0.002} _{-0.006} ^{+0.006} _{-0.001} [.7480 -.0001]	k6	40.0 [1.57]
AN	7 [.276]	80 ^{+0.012} _{-0.007} ^{+0.004} _{-0.002} [3.1496 -.0002]	j6	100 [3.937]	—	D M6 DIN 332	19 ^{+0.015} _{-0.013} ^{+0.002} _{-0.006} ^{+0.006} _{-0.001} [.7480 -.0001]	k6	40.0 [1.57]
BK	5.54 [.218]	73.025 ⁰ ^{-0.051} ^{+0.000} [2.8750 -.0020]		98.43 [3.875]	—	—	15.875 ⁰ ^{-0.013} ^{+0.000} [.6250 -.0005]		52.40 ± 0.79 [2.063 ± .031]
CC	5.54 [.218]	60 ^{+0.012} _{-0.007} ^{+0.004} _{-0.002} [2.3622 -.0002]	j6	90 [3.543]	109 [4.291]	D M6 DIN 332	19 ^{+0.015} _{-0.013} ^{+0.002} ^{+0.006} ^{+0.001} [.7480 -.0001]	k6	40.0 [1.57]
CN	5.54 [.218]	60 ^{+0.012} _{-0.007} ^{+0.004} _{-0.002} [2.3622 -.0002]	j6	90 [3.543]	109 [4.291]	D M6 DIN 332	19 ^{+0.015} _{-0.013} ^{+0.002} ^{+0.006} ^{+0.001} [.7480 -.0001]	k6	40.0 [1.57]
EK	5.54 [.218]	73.025 ⁰ ^{-0.051} ^{+0.000} [2.8750 -.0020]		98.43 [3.875]	—	—	12.700 ⁰ ^{-0.013} ^{+0.000} [.5000 -.0005]		31.75 ± 0.25 [1.250 ± .010]
GC	7 [.276]	80 ^{+0.012} _{-0.007} ^{+0.004} _{-0.002} [3.1496 -.0002]	j6	100 [3.937]	—	D M6 DIN 332	14 ^{+0.012} _{-0.001} ^{+0.001} ^{+0.005} ^{+0.000} [.5512 -.0000]	k6	30 [1.18]
GN	7 [.276]	80 ^{+0.012} _{-0.007} ^{+0.004} _{-0.002} [3.1496 -.0002]	j6	100 [3.937]	—	D M6 DIN 332	14 ^{+0.012} _{-0.001} ^{+0.001} ^{+0.005} ^{+0.000} [.5512 -.0000]	k6	30 [1.18]
HC	5.54 [.218]	60 ^{+0.012} _{-0.007} ^{+0.004} _{-0.002} [2.3622 -.0002]	j6	90 [3.543]	109 [4.291]	D M6 DIN 332	14 ^{+0.012} _{-0.001} ^{+0.001} ^{+0.005} ^{+0.000} [.5512 -.0000]	k6	30 [1.18]
HN	5.54 [.218]	60 ^{+0.012} _{-0.007} ^{+0.004} _{-0.002} [2.3622 -.0002]	j6	90 [3.543]	109 [4.291]	D M6 DIN 332	14 ^{+0.012} _{-0.001} ^{+0.001} ^{+0.005} ^{+0.000} [.5512 -.0000]	k6	30 [1.18]
KK	7 [.276]	70 ⁺⁰ ^{-0.03} ^{+0.000} [2.7559 -.0012]	h7	90 [3.543]	109 [4.291]	—	16 ⁺⁰ ^{+0.011} ^{+0.000} ^{+0.004} [.6299 -.0004]	h6	40.0 [1.57]

MODEL	(X)	Y MAX	Z MAX (W/ BRAKE)
AKM41	96.4 [3.80]	118.8 [4.68]	152.3 [6.00]
AKM42	125.4 [4.94]	147.8 [5.82]	181.3 [7.14]
AKM43	154.4 [6.08]	176.8 [6.96]	210.3 [8.28]
AKM44	183.4 [7.22]	205.8 [8.10]	239.3 [9.42]

Note 1: Dimensions are in mm [inches].

Note 2: Product designed in metric. English conversions provided for reference only.

AKM4x Dimension Data

Mounting Code	"M"	"N"	"P"	"R"	"S"	"T"	"U"	"V"	"W"
AC	—	—	21.5 ⁰ _{-0.13} [.846 ⁺⁰⁰⁰ _{-.005}]	6 ⁰ _{-0.03} [.236 ⁺⁰⁰⁰ _{-.001}] N9	4.00 [1.57]	32 ⁰ _{-0.30} [1.260 ⁺⁰⁰⁰ _{-.012}]	0.040 [.0015]	0.080 [.0031]	0.080 [.0031]
AN	—	—	—	—	—	—	0.040 [.0015]	0.080 [.0031]	0.080 [.0031]
BK	4.762 ⁰ _{-0.050} [.1875 ⁺⁰⁰⁰⁰ _{-.0020}]	34.93 ± 0.25 [1.375 ± .010]	—	—	—	—	0.051 [.0020]	0.10 [.004]	0.10 [.004]
CC	—	—	21.5 ⁰ _{-0.13} [.846 ⁺⁰⁰⁰ _{-.005}]	6 ⁰ _{-0.03} [.236 ⁺⁰⁰⁰ _{-.001}] N9	4.00 [1.57]	32 ⁰ _{-0.30} [1.260 ⁺⁰⁰⁰ _{-.012}]	0.040 [.0015]	0.080 [.0031]	0.080 [.0031]
CN	—	—	—	—	—	—	0.040 [.0015]	0.080 [.0031]	0.080 [.0031]
EK	3.175 ⁰ _{-0.050} [.1250 ⁺⁰⁰⁰⁰ _{-.0020}]	19.05 ± 0.25 [.750 ± .010]	—	—	—	—	0.051 [.0020]	0.10 [.004]	0.10 [.004]
GC	—	—	16 ⁰ _{-0.13} [.630 ⁺⁰⁰⁰ _{-.005}]	5 ⁰ _{-0.03} [.197 ⁺⁰⁰⁰ _{-.001}] N9	6.00 [.236]	20 ⁰ _{-0.20} [.787 ⁺⁰⁰⁰ _{-.008}]	0.040 [.0015]	0.080 [.0031]	0.080 [.0031]
GN	—	—	—	—	—	—	0.040 [.0015]	0.080 [.0031]	0.080 [.0031]
HC	—	—	16 ⁰ _{-0.13} [.630 ⁺⁰⁰⁰ _{-.005}]	5 ⁰ _{-0.03} [.197 ⁺⁰⁰⁰ _{-.001}] N9	6.00 [.236]	20 ⁰ _{-0.20} [.787 ⁺⁰⁰⁰ _{-.008}]	0.040 [.0015]	0.080 [.0031]	0.080 [.0031]
HN	—	—	—	—	—	—	0.040 [.0015]	0.080 [.0031]	0.080 [.0031]
KK	5 ⁰ _{-0.03} [.197 ⁺⁰⁰⁰⁰ _{-.001}]	30 ⁰ _{-0.20} [1.181 ⁺⁰⁰⁰ _{-.008}]	—	—	—	—	0.051 [.0020]	0.008 [.0031]	0.008 [.0031]

AKM4x Performance Data

Sold & Serviced By:



Toll Free Phone: 877-378-0240

Toll Free Fax: 877-378-0249

sales@servo2go.com

www.servo2go.com

AKM4x Performance Data – Up to 640 Vdc

Parameters	Tol	Sym	Units	AKM41			AKM42				AKM43				AKM44		
				C	E	H	C	E	G	J	E	H	L	E	H	J	
Max Rated DC Bus Voltage	Max	Vbus	Vdc	640	640	320	640	640	640	320	640	640	320	640	640	640	
Continuous Torque (Stall) for ΔT winding = 100°C ①②⑦⑧⑨	Nom	T _{cs}	Nm	1.95	2.02	2.06	3.35	3.42	3.53	3.56	4.70	4.82	4.73	5.76	5.89	6.00	
			lb-in	17.3	17.9	18.2	29.6	30.3	31.2	31.5	41.6	42.7	41.9	51.0	52.1	53.1	
Continuous Current (Stall) for ΔT winding = 100°C ①②⑦⑧⑨	Nom	I _{cs}	A _{rms}	1.46	2.85	5.60	1.40	2.74	4.80	8.40	2.76	5.4	11.2	2.9	5.6	8.8	
Continuous Torque (Stall) for ΔT winding = 60°C ②	Nom	T _{cs}	Nm	1.56	1.62	1.65	2.68	2.74	2.82	2.85	3.76	3.86	3.78	4.61	4.71	4.80	
			lb-in	13.8	14.3	14.6	23.7	24.2	25.0	25.2	33.3	34.2	33.5	40.8	41.7	42.5	
Max Mechanical Speed ⑤	Nom	N _{max}	rpm	6000	6000	6000	6000	6000	6000	6000	6000	6000	6000	6000	6000	6000	
Peak Torque ①②	Nom	T _p	Nm	6.12	6.28	6.36	11.1	11.3	11.5	11.6	15.9	16.1	16.0	19.9	20.2	20.4	
			lb-in	54.2	55.6	56.3	98.2	99.7	102	103	141	142	142	176	179	181	
Peak Current	Nom	I _p	A _{rms}	5.8	11.4	22.4	5.60	11.0	19.2	33.7	11.0	21.6	44.6	11.4	22.4	35.2	
Rated Torque (speed) ①②⑦⑧⑨⑩	Trtd	Nm	-	-	1.99	-	-	-	-	-	-	-	-	-	-		
		lb-in	-	-	17.6	-	-	-	-	-	-	-	-	-	-		
Rated Speed		N _{rtd}	rpm	-	-	1000	-	-	-	-	-	-	-	-	-	-	
Rated Power (speed) ①②⑦⑧⑨	Prtd	kW	-	-	0.21	-	-	-	-	-	-	-	-	-	-		
		Hp	-	-	0.28	-	-	-	-	-	-	-	-	-	-		
Rated Torque (speed) ①②⑦⑧⑨⑩	Trtd	Nm	-	1.94	1.86	-	-	-	3.03	-	4.46	3.78	-	5.44	-		
		lb-in	-	17.2	16.5	-	-	-	26.8	-	39.4	33.5	-	48.2	-		
Rated Speed		N _{rtd}	rpm	-	1200	3000	-	-	-	3000	-	1200	3000	-	1000	-	
Rated Power (speed) ①②⑦⑧⑨	Prtd	kW	-	0.24	0.58	-	-	-	0.95	-	0.56	1.19	-	0.57	-		
		Hp	-	0.33	0.78	-	-	-	1.28	-	0.75	1.59	-	0.76	-		
Rated Torque (speed) ①②⑦⑧⑨⑩	Trtd	Nm	1.88	1.82	1.62	-	3.12	2.90	2.38	4.24	3.86	2.53	5.22	4.66	3.84		
		lb-in	16.6	16.1	14.3	-	27.6	25.7	21.1	37.5	34.2	22.4	46.2	41.2	34.0		
Rated Speed		N _{rtd}	rpm	1200	3000	6000	-	1800	3500	6000	1500	3000	6000	1200	2500	4000	
Rated Power (speed) ①②⑦⑧⑨	Prtd	kW	0.24	0.57	1.02	-	0.59	1.06	1.50	0.67	1.21	1.59	0.66	1.22	1.61		
		Hp	0.32	0.77	1.36	-	0.79	1.42	2.00	0.89	1.63	2.13	0.88	1.64	2.16		
Rated Torque (speed) ①②⑦⑧⑨⑩	Trtd	Nm	1.77	1.58	-	3.10	2.81	2.35	-	3.92	2.81	-	4.80	3.48	2.75		
		lb-in	15.7	14.0	-	27.4	24.9	20.8	-	34.7	24.9	-	42.5	30.8	24.3		
Rated Speed		N _{rtd}	rpm	3000	6000	-	1500	3500	6000	-	2500	5500	-	2000	4500	6000	
Rated Power (speed) ①②⑦⑧⑨	Prtd	kW	0.56	0.99	-	0.49	1.03	1.48	-	1.03	1.62	-	1.01	1.64	1.73		
		Hp	0.75	1.33	-	0.65	1.38	1.98	-	1.38	2.17	-	1.35	2.20	2.32		
Rated Torque (speed) ①②⑦⑧⑨⑩	Trtd	Nm	1.74	1.58	-	3.02	2.72	2.35	-	3.76	2.58	-	4.56	2.93	2.75		
		lb-in	15.4	14.0	-	26.7	24.1	20.8	-	33.3	22.8	-	40.4	26.0	24.3		
Rated Speed		N _{rtd}	rpm	3500	6000	-	2000	4000	6000	-	3000	6000	-	2500	5500	6000	
Rated Power (speed) ①②⑦⑧⑨	Prtd	kW	0.64	0.99	-	0.63	1.14	1.48	-	1.18	1.62	-	1.19	1.69	1.73		
		Hp	0.85	1.33	-	0.85	1.53	1.98	-	1.58	2.17	-	1.60	2.27	2.32		

See following page for notes.

AKM4x Performance Data – Up to 640 Vdc (Continued)

Parameters	Tol	Sym	Units	AKM41			AKM42				AKM43			AKM44		
				C	E	H	C	E	G	J	E	H	L	E	H	J
Torque Constant ①	±10%	K _t	Nm/A _{rms}	1.34	0.71	0.37	2.40	1.26	0.74	0.43	1.72	0.89	0.43	2.04	1.06	0.69
			lb-in/ A _{rms}	11.9	6.3	3.3	21.2	11.2	6.5	3.8	15.2	7.9	3.8	18.1	9.4	6.1
Back EMF Constant ⑥	±10%	K _e	V/krpm	86.3	45.6	23.7	154	80.9	47.5	27.5	111	57.4	27.5	132	68.0	44.2
Motor Constant	Nom	K _m	N-m/√W	0.237	0.236	0.242	0.374	0.369	0.381	0.393	0.479	0.501	0.465	0.567	0.580	0.581
			lb-in/√W	2.10	2.09	2.14	3.31	3.26	3.37	3.47	4.24	4.44	4.12	5.01	5.13	5.14
Resistance (line-line) ⑥	±10%	R _m	ohm	21.3	6.02	1.56	27.5	7.78	2.51	0.8	8.61	2.1	0.57	8.64	2.23	0.94
Inductance (line-line)		L	mH	66.1	18.4	5.0	97.4	26.8	9.2	3.1	32.6	8.8	2.0	33.9	9.1	3.8
Inertia (includes Resolver feedback) ③	±10%	J _m	kg-cm ²	0.81			1.5				2.1			2.7		
			lb-in-s ²	7.2E-04			1.3E-03				1.8E-03			2.4E-03		
Optional Brake Inertia (additional)	±10%	J _m	kg-cm ²	0.068			0.068				0.068			0.068		
			lb-in-s ²	6.0E-05			6.0E-05				6.0E-05			6.0E-05		
Weight		W	kg	2.44			3.39				4.35			5.3		
			lb	5.4			7.5				9.6			11.7		
Static Friction ①⑩		T _f	Nm	0.014			0.026				0.038			0.05		
			lb-in	0.12			0.23				0.34			0.44		
Viscous Damping ①		K _{dv}	Nm/krpm	0.009			0.013				0.017			0.021		
			lb-in/ k rpm	0.08			0.12				0.15			0.19		
Thermal Time Constant		TCT	minutes	13			17				20			24		
Thermal Resistance		R _{thw-a}	°C/W	0.97			0.80				0.70			.65		
Pole Pairs				5			5				5			5		
Heat Sink Size				10"x10"x1/4" Aluminum Plate			10"x10"x1/4" Aluminum Plate				10"x10"x1/4" Aluminum Plate			10"x10"x1/4" Aluminum Plate		

Notes:

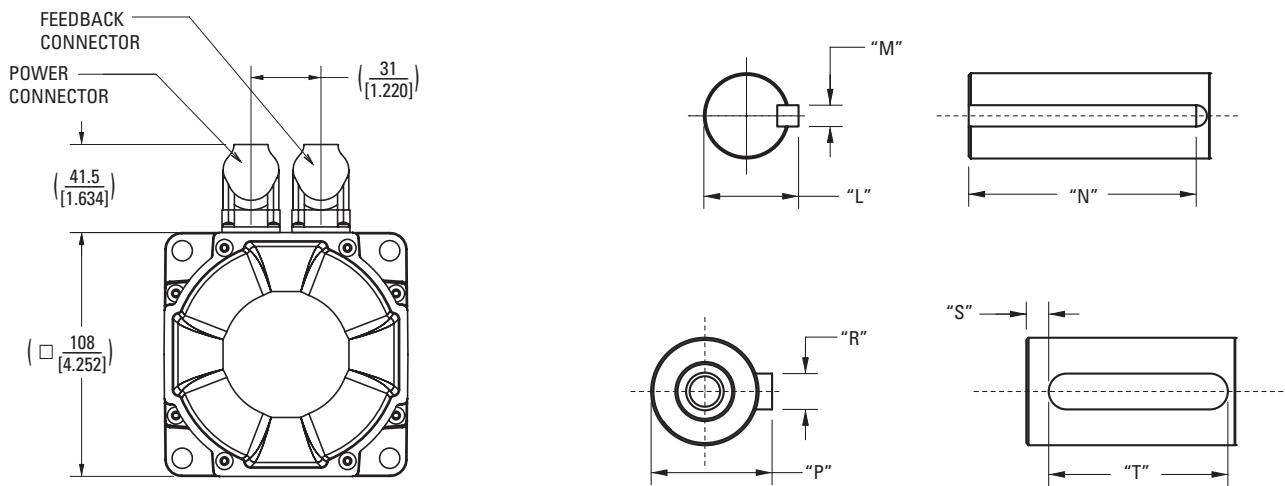
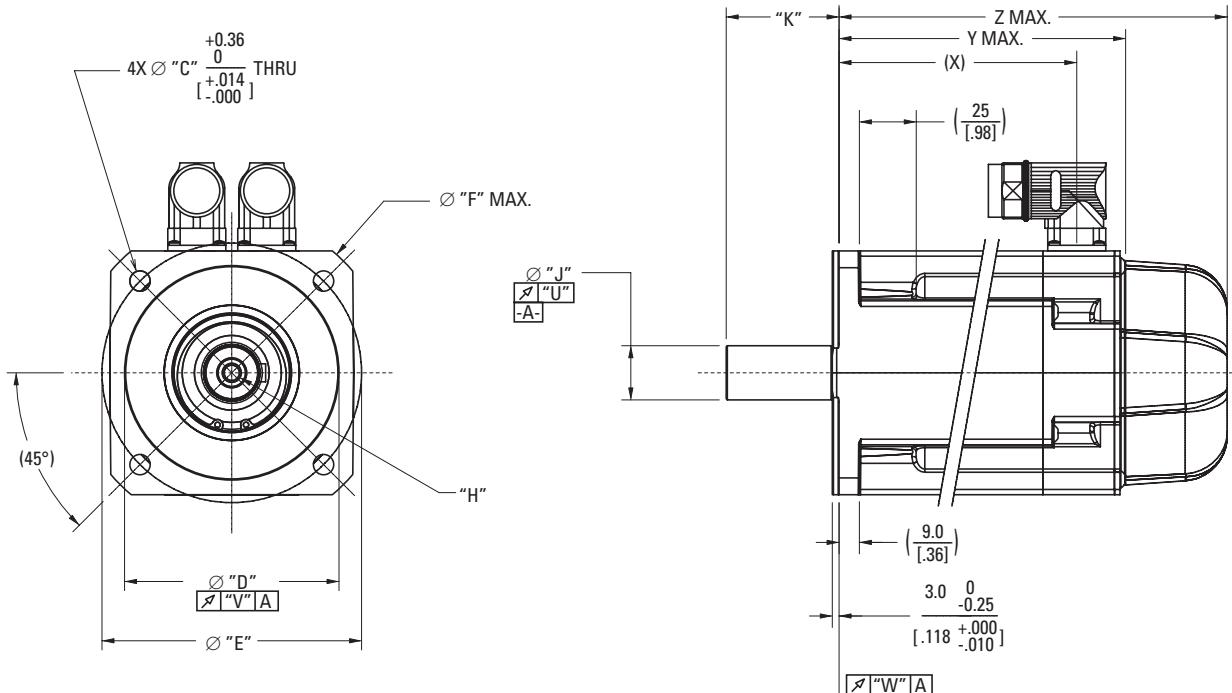
- ① Motor winding temperature rise, ΔT=100°C, at 40°C ambient.
- ② All data referenced to sinusoidal commutation.
- ③ Add parking brake if applicable for total inertia.
- ④ Motor with standard heat sink.
- ⑤ May be limited at some values of Vbus.
- ⑥ Measured at 25°C.
- ⑦ Brake motor option reduces continuous torque ratings by 0.12 Nm.
- ⑧ Non-Resolver feedback options reduces continuous ratings by:
AKM41 = 0.1 Nm AKM42 = 0.1 Nm AKM43 = 0.2 Nm AKM44 = 0.3 Nm
- ⑨ Motors with non-resolver feedback and brake option, reduce continuous torque by:
AKM41 = 0.22 Nm AKM42 = 0.36 Nm AKM43 = 0.55 Nm AKM44 = 0.76 Nm
- ⑩ For motors with optional shaft seal, reduce torque shown by 0.071 Nm (0.63 lb-in), and increase T_f by the same amount.

Additional Notes: See system data beginning on page 14 for typical torque/speed performance.

Additional windings can be found through our online Motioneering sizing and selection software tool. See page 73 for more information.

AKM5x Outline Drawings

AKM5x Frame



AKM5x Dimension Data

AKM5x Dimension Data

Mounting Code	"C"	"D"	"E"	"F"	"H"	"J"	"K"	"L"
AC	9 [.354]	110 +0.013 -0.009 [4.3307 +.0005 -.0003] j6	130 [5.118]	—	D M8 DIN 332	24 +0.015 +0.002 [.9449 +.0006 +.0001] k6	[50.0] [1.97]	—
AN	9 [.354]	110 +0.013 -0.009 [4.3307 +.0005 -.0003] j6	130 [5.118]	—	D M8 DIN 332	24 +0.015 +0.002 [.9449 +.0006 +.0001] k6	50.0 [1.97]	—
BK	8.33 [.328]	55.563 0 -0.051 [2.1874 +.0000 -.0020]	125.73 [4.950]	—	—	19.05 0 +0.013 [.7500 +.0000 +.0005]	57.15 ± 0.79 [2.250 ± .031]	21.15 0 -0.43 [.83 +.000 -.017]
CC	9 [.354]	95 +0.013 -0.009 [3.7402 +.0005 -.0003] j6	115 [4.528]	140 [5.512]	D M8 DIN 332	24 +0.015 +0.002 [.9449 +.0006 +.0001] k6	50.0 [1.97]	—
CN	9 [.354]	95 +0.013 -0.009 [3.7402 +.0005 -.0003] j6	115 [4.528]	140 [5.512]	D M8 DIN 332	24 +0.015 +0.002 [.9449 +.0006 +.0001] k6	50.0 [1.97]	—
DK	8.33 [.328]	63.5 0 -0.05 [2.500 +.000 -.002]	127 [5.000]	—	—	19.05 +0 +0.013 [.7500 +.0000 +.0005]	57.15 ± 0.79 [2.250 ± .031]	21.15 0 -0.43 [.83 +.000 -.017]
EK	8.33 [.328]	55.563 0 -0.051 [2.1874 +.0000 -.0020]	125.73 [4.950]	—	—	15.875 0 +0.013 [.6250 +.0000 +.0005]	44.45 [1.750]	17.91 0 -0.43 [.705 +.000 -.017]
GC	9 [.354]	110 +0.013 -0.009 [4.3307 +.0005 -.0003] j6	130 [5.118]	—	D M6 DIN 332	19 +0.015 +0.002 [.7480 +.0006 +.0001] k6	40 [1.57]	—
GN	9 [.354]	110 +0.013 -0.009 [4.3307 +.0005 -.0003] j6	130 [5.118]	—	D M6 DIN 332	19 +0.015 +0.002 [.7480 +.0006 +.0001] k6	40.0 [1.57]	—
HC	9 [.354]	95 +0.013 -0.009 [3.7402 +.0005 -.0003] j6	115 [4.528]	140 [5.512]	D M6 DIN 332	19 +0.015 +0.002 [.7480 +.0006 +.0001] k6	40 [1.57]	—
HN	9 [.354]	95 +0.013 -0.009 [3.7402 +.0005 -.0003] j6	115 [4.528]	140 [5.512]	D M6 DIN 332	19 +0.015 +0.002 [.7480 +.0006 +.0001] k6	40.0 [1.57]	—

Continued on the following page

MODEL	Z MAX (SINE ENCODER (NO BRAKE))	Z MAX (SINE ENCODER (W/ BRAKE))	(X)	Y MAX	Z MAX (W/ BRAKE)
AKM51	146.0 [5.75]	189.0 [7.44]	105.3 [4.15]	127.5 [5.02]	172.5 [6.79]
AKM52	177.0 [6.97]	220.0 [8.66]	136.3 [5.37]	158.5 [6.24]	203.5 [8.01]
AKM53	208.0 [8.19]	251.0 [9.88]	167.3 [6.59]	189.5 [7.46]	234.5 [9.23]
AKM54	239.0 [9.41]	282.0 [11.10]	198.3 [7.81]	220.5 [8.68]	265.5 [10.45]

Note 1: Dimensions are in mm [inches].

Note 2: Product designed in metric. English conversions provided for reference only.

AKM5x Dimension Data

AKM5x Dimension Data (continued)

Mounting Code	"M"	"N"	"P"	"R"	"S"	"T"	"U"	"V"	"W"
AC	–	–	27 ⁰ _{-0.29} [1.063 ^{.000} _{-.001}]	8 ⁰ _{-0.036} [.3150 ⁺⁰⁰⁰⁰ _{-.0014}]	N9 5.00 [1.97]	40 ⁰ _{-0.30} [1.575 ⁺⁰⁰⁰ _{-.012}]	0.040 [.0015]	0.100 [.0039]	0.100 [.0039]
AN	–	–	–	–	–	–	0.040 [.0015]	0.100 [.0039]	0.100 [.0039]
BK	4.763 ⁰ _{-0.050} [.1875 ⁺⁰⁰⁰⁰ _{-.0020}]	38.1 ± 0.25 [1.500 ± .010]	–	–	–	–	0.051 [.0020]	0.10 [.004]	0.10 [.004]
CC	–	–	27 ⁰ _{-0.29} [1.063 ^{.000} _{-.011}]	8 ⁰ _{-0.036} [.3150 ⁺⁰⁰⁰⁰ _{-.0014}]	N9 5.00 [1.97]	40 ⁰ _{-0.30} [1.575 ⁺⁰⁰⁰ _{-.012}]	0.040 [.0015]	0.080 [.0031]	0.080 [.0031]
CN	–	–	–	–	–	–	0.040 [.0015]	0.080 [.0031]	0.080 [.0031]
DK	4.763 ⁰ _{-0.050} [.1875 ⁺⁰⁰⁰⁰ _{-.0020}]	34.93 ± 0.25 [1.375 ± .010]	–	–	–	–	0.051 [.0020]	0.05 [.002]	0.10 [.004]
EK	4.763 ⁰ _{-0.050} [.1875 ⁺⁰⁰⁰⁰ _{-.0020}]	38.1 ± 0.25 [1.500 ± .010]	–	–	–	–	0.051 [.0020]	0.10 [.004]	0.10 [.004]
GC	–	–	21.5 ⁰ _{-0.13} [.846 ⁺⁰⁰⁰ _{-.005}]	6 ⁰ _{-0.03} [.236 ⁺⁰⁰⁰ _{-.001}]	N9 4.00 [.157]	32 ⁰ _{-0.30} [1.260 ⁺⁰⁰⁰ _{-.012}]	0.040 [.0015]	0.080 [.0031]	0.080 [.0031]
GN	–	–	–	–	–	–	–	–	–
HC	–	–	21.5 ⁰ _{-0.13} [.846 ⁺⁰⁰⁰ _{-.005}]	6 ⁰ _{-0.03} [.236 ⁺⁰⁰⁰ _{-.001}]	N9 4.00 [.157]	32 ⁰ _{-0.30} [1.260 ⁺⁰⁰⁰ _{-.012}]	0.040 [.0015]	0.080 [.0031]	0.080 [.0031]
HN	–	–	–	–	–	–	–	–	–

Notes

AKM5x Performance Data – Up to 640 Vdc (Continued)

Parameters	Tol	Sym	Units	AKM51			AKM52				AKM53				AKM54			
				E	H	L	E	H	L	M	G	H	L	P	H	K	L	N
Torque Constant ①	±10%	K_t	Nm/ A _{rms}	1.72	0.80	0.41	2.79	1.44	0.75	0.66	2.39	1.75	0.99	0.60	2.6	1.50	1.13	0.80
			lb-in/ A _{rms}	15.2	7.1	3.6	24.7	12.7	6.6	5.8	21.2	15.5	8.8	5.3	22.7	13.3	10.0	7.1
Back EMF Constant ⑥	±10%	K_e	V/krpm	110	51.3	26.6	179	92.7	48.3	42.4	154	112	63.6	38.4	166	96.6	72.9	51.3
Motor Constant	Nom	K_m	N-m/√W	0.469	0.465	0.447	0.761	0.767	0.784	0.770	0.979	0.986	0.973	0.926	1.19	1.18	1.14	1.14
			lb-in/√W	4.15	4.12	3.96	6.73	6.79	6.94	6.81	8.67	8.73	8.61	8.19	10.5	10.4	10.1	10.1
Resistance (line-line) ⑥	±10%	R_m	ohm	8.98	1.97	0.56	8.96	2.35	0.61	0.49	3.97	2.1	0.69	0.28	3.2	1.08	0.65	0.33
Inductance (line-line)		L	mH	36.6	7.9	2.1	44.7	11.9	3.24	2.5	21.3	11.4	3.64	1.3	18.3	6.2	3.5	1.8
Inertia (includes Resolver feedback) ③	±10%	J_m	kg-cm ²	3.4			6.2				9.1				12			
			lb-in-s ²	3.0E-03			5.5E-03				8.1E-03				0.011			
Optional Brake Inertia (additional)	±10%	J_m	kg-cm ²	0.17			0.17				0.17				0.17			
			lb-in-s ²	1.5E-04			1.5E-04				1.5E-04				1.5E-04			
Weight		W	kg	4.2			5.8				7.4				9			
			lb	9.3			12.8				16.3				19.8			
Static Friction ⑪⑩		T _f	Nm	0.022			0.04				0.058				0.077			
			lb-in	0.19			0.35				0.51				0.68			
Viscous Damping ①		K_{dv}	Nm/ krpm	0.033			0.042				0.052				0.061			
			lb-in/ krpm	0.29			0.37				0.46				0.54			
Thermal Time Constant	TCT	minutes		20			24				28				31			
Thermal Resistance	R _{thw-a}	°C/W		0.68			0.56				0.50				0.45			
Pole Pairs				5			5				5				5			
Heat Sink Size				12"x12"x1/2" Aluminum Plate			12"x12"x1/2" Aluminum Plate				12"x12"x1/2" Aluminum Plate				12"x12"x1/2" Aluminum Plate			

Notes:

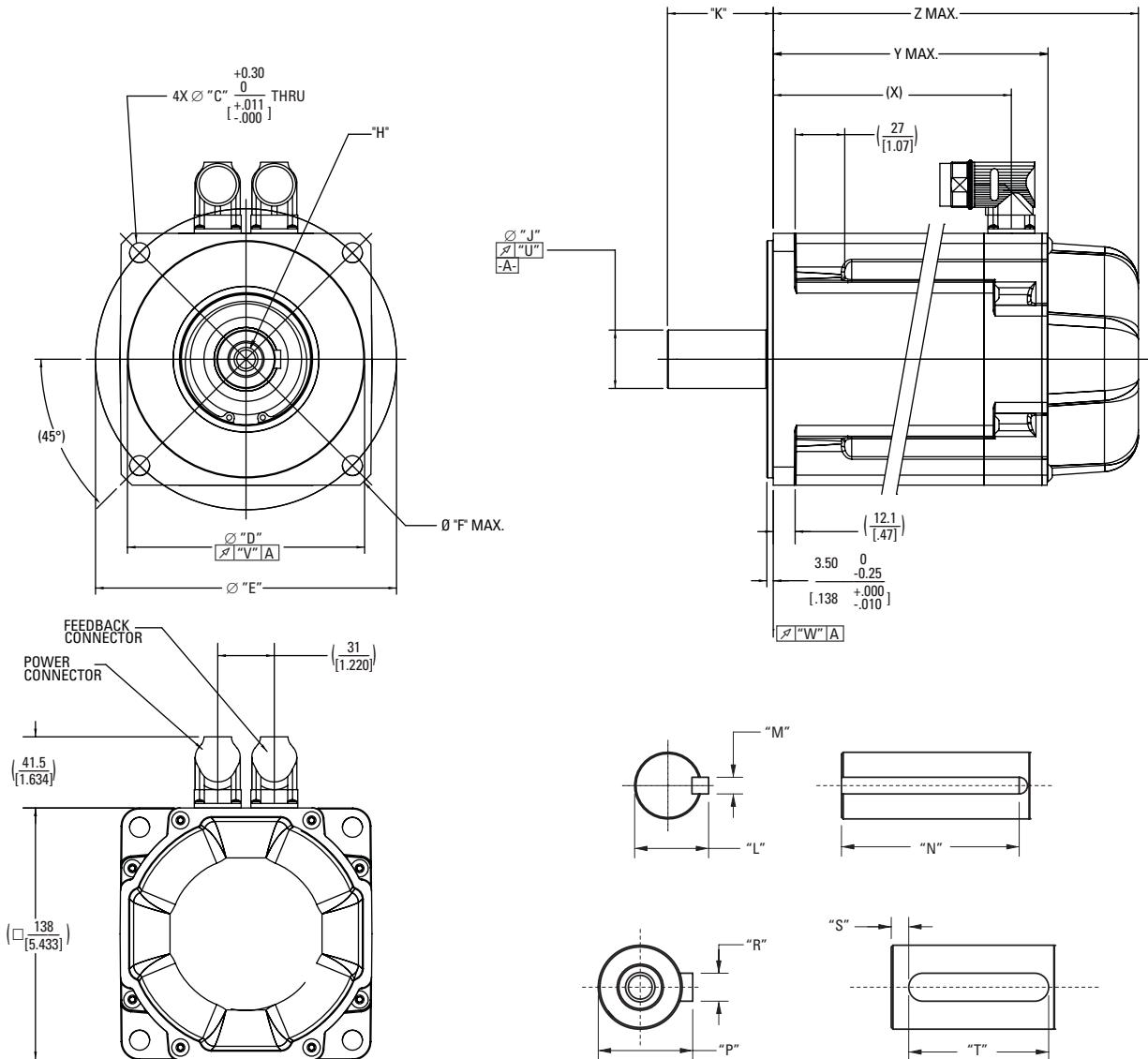
- ① Motor winding temperature rise, $\Delta T=100^{\circ}\text{C}$, at 40°C ambient.
- ② All data referenced to sinusoidal commutation.
- ③ Add parking brake if applicable for total inertia.
- ④ Motor with standard heat sink.
- ⑤ May be limited at some values of Vbus.
- ⑥ Measured at 25°C .
- ⑦ Brake motor option reduces continuous torque ratings by:
 $\text{AKM51} = 0.15 \text{ Nm}$ $\text{AKM52} = 0.26 \text{ Nm}$ $\text{AKM53} = 0.35 \text{ Nm}$ $\text{AKM54} = 0.43 \text{ Nm}$
- ⑧ Non-Resolver feedback options reduce continuous torque ratings by:
 $\text{AKM51} = 0.15 \text{ Nm}$ $\text{AKM52} = 0.34 \text{ Nm}$ $\text{AKM53} = 0.58 \text{ Nm}$ $\text{AKM54} = 0.86 \text{ Nm}$
- ⑨ Motors with non-resolver feedback and brake option, reduce continuous torque by:
 $\text{AKM51} = 0.39 \text{ Nm}$ $\text{AKM52} = 0.76 \text{ Nm}$ $\text{AKM53} = 1.13 \text{ Nm}$ $\text{AKM54} = 1.55 \text{ Nm}$
- ⑩ For motors with optional shaft seal, reduce torque shown by 0.013 Nm (0.12 lb-in), and increase T_f by the same amount.

Additional Notes: See system data beginning on page 14 for typical torque/speed performance.

Additional windings can be found through our online Motioneering sizing and selection software tool. See page 73 for more information.

AKM6x Outline Drawings

AKM6x Frame



AKM6x Dimension Data

AKM6x Dimension Data

Mounting Code	"C"	"D"	"E"	"F"	"H"	"J"	"K"	"L"
AC	11.00 [.433]	130 ^{+0.014} _{-0.011} [5.1181 ^{+0.005} _{-0.004}] j6	165.00 [6.496]	—	D M12 DIN 332	32 ^{+0.018} _{+0.002} [1.2598 ^{+0.007} _{+0.001}] k6	58 [2.28]	—
AN	11.00 [.433]	130 ^{+0.014} _{-0.011} [5.1181 ^{+0.005} _{-0.004}] j6	165.00 [6.496]	—	D M12 DIN 332	32 ^{+0.018} _{+0.002} [1.2598 ^{+0.007} _{+0.001}] k6	58 [2.28]	—
GC	11.00 [.433]	130 ^{+0.014} _{-0.011} [5.1181 ^{+0.005} _{-0.004}] j6	165.00 [6.496]	—	D M8 DIN 332	24 ^{+0.015} _{+0.002} [.9449 ^{+0.006} _{+0.001}] k6	50 [1.97]	—
GN	11.00 [.433]	130 ^{+0.014} _{-0.011} [5.1181 ^{+0.005} _{-0.004}] j6	165.00 [6.496]	—	D M8 DIN 332	24 ^{+0.015} _{+0.002} [.9449 ^{+0.006} _{+0.001}] k6	50 [1.97]	—
KK	9.00 [.354]	110 ⁰ [4.3307 ^{+0.000} _{-0.013}] h7	145.00 [5.709]	165 [6.496]	—	28 ⁺⁰ [1.1024 ^{+0.013} _{+0.005}] h6	60 [2.36]	31 ⁰ [1.220 ^{-0.29} _{+0.00}] -.011
LK	3/18 - 16 UNC-2B	114.3 ⁰ [4.5000 ^{+0.000} _{-0.030}]	149.225 [5.875]	165 [6.496]	—	28.580 ⁰ [1.1250 ^{+0.013} _{+0.000}] +.0005	69.85 [2.75]	31.39 ⁰ [1.236 ^{-0.43} _{+0.00}] -.017

Mounting Code	"M"	"N"	"P"	"R"	"S"	"T"	"U"	"V"	"W"
AC	—	—	35 ⁰ [1.378 ^{+0.00} _{-0.001}]	10 ⁰ [.3937 ^{+0.000} _{-0.014}] N9	5.00 [.197]	45 ⁰ [1.772 ^{+0.00} _{-0.012}]	0.050 [.0019]	0.100 [.0039]	0.100 [.0039]
AN	—	—	—	—	—	—	0.050 [.0019]	0.100 [.0039]	0.100 [.0039]
GC	—	—	27 ⁰ [1.063 ^{+0.00} _{-0.001}]	8 ⁰ [.3150 ^{+0.000} _{-0.014}] N9	5.00 [.197]	40 ⁰ [1.575 ^{+0.00} _{-0.012}]	0.050 [.0019]	0.100 [.0039]	0.100 [.0039]
GN	—	—	—	—	—	—	0.050 [.0019]	0.100 [.0039]	0.100 [.0039]
KK	8 ⁰ [.3150 ^{+0.000} _{-0.014}]	50 ⁰ [1.969 ^{+0.00} _{-0.12}]	—	—	—	—	0.050 [.0019]	0.100 [.0039]	0.100 [.0039]
LK	6.35 ⁰ [2.75 ^{+0.00} _{-0.002}]	38.1 ± 0.25 [1.500 ± .010]	—	—	—	—	0.050 [.0019]	0.100 [.0039]	0.100 [.0039]

MODEL	Z MAX SINE ENCODER (NO BRAKE)	Z MAX SINE ENCODER (W/ BRAKE)	(X)	Y MAX	Z MAX (W/ BRAKE)
AKM62	172.2 [6.78]	218.7 [8.85]	130.5 [5.14]	153.7 [6.05]	200.7 [7.90]
AKM63	197.2 [7.76]	224.7 [9.63]	155.5 [6.12]	178.7 [7.04]	225.7 [8.89]
AKM64	222.2 [8.75]	268.7 [10.62]	180.5 [7.11]	203.7 [8.02]	250.7 [9.87]
AKM65	247.2 [9.73]	294.7 [11.60]	205.5 [8.09]	228.7 [9.00]	275.7 [10.85]

Note 1: Dimensions are in mm [inches].

Note 2: Product designed in metric. English conversions provided for reference only.

AKM6x Performance Data

AKM6x Performance Data – Up to 640 Vdc

					AKM62				AKM63				AKM64			AKM65		
					H	L	M	Q	H	L	M	Q	K	L	Q	L	M	P
Max Rated DC Bus Voltage	Max	Vbus	Vdc	640	640	640	320	640	640	640	320	640	640	640	640	640	640	
Continuous Torque (Stall) for ΔT winding = 100°C ①②⑦⑧⑨	Nom	T _{c_s}	Nm	11.9	12.2	12.2	12.0	16.6	16.8	17.0	16.7	20.8	21.0	20.6	25	25.0	24.5	
Continuous Current (Stall) for ΔT winding = 100°C ①②⑦⑧⑨	Nom	I _{c_s}	A _{rms}	5.4	12.0	13.4	21.8	5.6	11.1	13.8	22.4	9.2	12.8	20.7	12.2	13.6	19.8	
Continuous Torque (Stall) for ΔT winding = 60°C ②	Nom	T _{c_s}	Nm	9.5	9.8	9.72	9.6	13.3	13.4	13.6	13.4	16.6	16.8	16	20	20.0	19.6	
Continuous Torque (Stall) for ΔT winding = 60°C ②	Nom	T _{c_s}	lb-in	84	87	86.0	85	118	119	120	119	147	149	142	177	177	173	
Max Mechanical Speed ⑤	Nom	N _{max}	rpm	6000	6000	6000	6000	6000	6000	6000	6000	6000	6000	6000	6000	6000	6000	
Peak Torque ①②	Nom	T _p	Nm	29.6	30.1	30.2	29.8	42.1	42.6	43.0	42.4	53.5	54.1	53.2	65.2	65.2	65.2	
			lb-in	262	266	267	264	373	377	381	374	473	479	471	577	577	577	
Peak Current	Nom	I _p	A _{rms}	16.2	36.0	40.3	65.4	16.8	33.3	41.4	67.2	27.5	38.4	62.1	36.6	40.9	59.4	
75 Vdc	Rated Torque (speed) ①②⑦⑧⑨⑩	T _{rtd}	Nm	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
			lb-in	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
	Rated Speed	N _{rtd}	rpm	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
	Rated Power (speed) ①②⑦⑧⑨	P _{rtd}	kW	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
			Hp	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
160 Vdc	Rated Torque (speed) ①②⑦⑧⑨⑩	T _{rtd}	Nm	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
			lb-in	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
	Rated Speed	N _{rtd}	rpm	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
	Rated Power (speed) ①②⑦⑧⑨	P _{rtd}	kW	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
			Hp	-	-	-	-	-	-	-	-	-	-	-	-	-	-	
320 Vdc	Rated Torque (speed) ①②⑦⑧⑨⑩	T _{rtd}	Nm	10.8	10.0	9.50	6.5	-	14.2	14.3	11.9	18.8	18.4	15.3	22.4	21.9	19.1	
			lb-in	99	89	84.1	58	-	126	127	105	166	163	135	198	194	169	
	Rated Speed	N _{rtd}	rpm	1000	2500	3000	5500	-	1500	2000	3500	1200	1500	3000	1300	1500	2400	
	Rated Power (speed) ①②⑦⑧⑨	P _{rtd}	kW	1.17	2.62	2.98	3.74	-	2.23	2.99	4.36	2.36	2.89	4.81	3.05	3.44	4.8	
			Hp	1.57	3.51	4.00	5.02	-	2.99	4.01	5.85	3.17	3.87	6.45	4.09	4.61	6.44	
560 Vdc	Rated Torque (speed) ①②⑦⑧⑨⑩	T _{rtd}	Nm	10.2	7.42	5.70	-	14.6	12.9	11.3	-	17.2	15.6	10.7	19.2	18.8	14.9	
			lb-in	90.3	65.7	50.4	-	129	114	100	-	152	138	95	170	166	132	
	Rated Speed	N _{rtd}	rpm	2000	5000	6000	-	1500	3000	4000	-	2000	3000	5000	2500	2700	4000	
	Rated Power (speed) ①②⑦⑧⑨	P _{rtd}	kW	2.14	3.89	3.58	-	2.29	4.05	4.73	-	3.60	4.90	5.6	5.03	5.32	6.24	
			Hp	2.86	5.21	4.80	-	3.08	5.43	6.34	-	4.83	6.57	7.51	6.74	7.13	8.37	
640 Vdc	Rated Torque (speed) ①②⑦⑧⑨⑩	T _{rtd}	Nm	9.9	5.74	5.70	-	14.2	12.0	10.5	-	16.3	14.4	7.4	18.6	18.1	11.6	
			lb-in	87.6	50.8	50.4	-	126	106	92.9	-	144	127	66	165	160	103	
	Rated Speed	N _{rtd}	rpm	2400	6000	6000	-	1800	3500	4500	-	2500	3500	6000	2800	3000	5000	
	Rated Power (speed) ①②⑦⑧⑨	P _{rtd}	kW	2.49	3.61	3.58	-	2.68	4.4	4.95	-	4.27	5.28	4.65	5.37	5.69	6.08	
			Hp	3.34	4.84	4.80	-	3.59	5.90	6.63	-	5.72	7.07	6.23	7.2	7.62	8.14	

See following page for notes.

AKM6x Performance Data – Up to 640 Vdc (Continued)

Parameters	Tol	Sym	Units	AKM62				AKM63				AKM64			AKM65		
				H	L	M	Q	H	L	M	Q	K	L	Q	L	M	P
Torque Constant ①	±10%	K_t	Nm/A _{rms}	2.2	1.0	0.91	0.60	3.00	1.5	1.24	0.75	2.28	1.66	1.0	2.1	1.85	1.3
			lb-in/ A _{rms}	19.5	8.85	8.1	5.3	26.6	13.3	11.0	7.1	20.2	14.7	8.85	18.6	16.4	11.5
Back EMF Constant ⑥	±10%	K_e	V/krpm	142	65.5	58.8	35.5	191.5	98.2	79.9	48.3	147	107	64.4	133	119	80.5
Motor Constant	Nom	K_m	N-m/V/W	0.989	0.949	0.984	1.00	1.32	1.26	1.30	1.28	1.57	1.57	1.44	1.81	1.77	1.75
			lb-in/V/W	8.75	8.40	8.71	8.85	11.7	11.2	11.5	11.3	13.9	13.9	12.8	16.0	15.6	15.4
Resistance (line-line) ⑥	±10%	R_m	ohm	3.3	0.74	0.57	0.24	3.43	0.94	0.61	0.23	1.41	0.75	0.32	0.90	0.73	0.37
Inductance (line-line)		L	mH	25.4	5.4	4.4	1.6	28.1	7.4	4.9	1.8	11.8	6.2	2.3	7.6	6.1	2.8
Inertia (includes Resolver feedback) ③	±10%	J_m	kg-cm ²	17				24				32			40		
			lb-in-s ²	0.015				0.021				0.028			0.035		
Optional Brake Inertia (additional)	±10%	J_m	kg-cm ²	0.61				0.61				0.61			0.61		
			lb-in-s ²	5.4E-04				5.4E-04				5.4E-04			5.4E-04		
Weight		W	kg	8.9				11.1				13.3			15.4		
			lb	19.6				24.4				29.3			33.9		
Static Friction ①⑩		T_f	Nm	0.05				0.1				0.15			0.2		
			lb-in	0.44				0.9				1.3			1.8		
Viscous Damping ①		K_{dv}	Nm/k _{rpm}	0.04				0.06				0.08			0.1		
			lb-in/ k _{rpm}	0.35				0.53				0.71			0.9		
Thermal Time Constant		TCT	minutes	20				25				30			35		
Thermal Resistance		R _{thw-a}	°C/W	0.46				0.41				0.38			0.35		
Pole Pairs				5				5				5			5		
Heat Sink Size				18" x 18" x 1/2" Aluminum Plate				18" x 18" x 1/2" Aluminum Plate				18" x 18" x 1/2" Aluminum Plate			18" x 18" x 1/2" Aluminum Plate		

Notes:

① Motor winding temperature rise, $\Delta T=100^{\circ}\text{C}$, at 40°C ambient.

② All data referenced to sinusoidal commutation.

③ Add parking brake if applicable for total inertia.

④ Motor with standard heat sink.

⑤ May be limited at some values of Vbus.

⑥ Measured at 25°C .

⑦ Brake motor option reduces continuous torque ratings by:

AKM62 = 0.5 Nm AKM63 = 0.9 Nm AKM64 = 1.3 Nm AKM65 = 1.7 Nm

⑧ Non-Resolver feedback options reduce continuous torque ratings by:

AKM62 = 0.9 Nm AKM63 = 1.2 Nm AKM64 = 1.5 Nm AKM65 = 1.8 Nm

⑨ Motors with non-resolver feedback and brake option, reduce continuous torque by:

AKM62 = 1.6 Nm AKM63 = 2.4 Nm AKM64 = 3.1 Nm AKM65 = 4.0 Nm

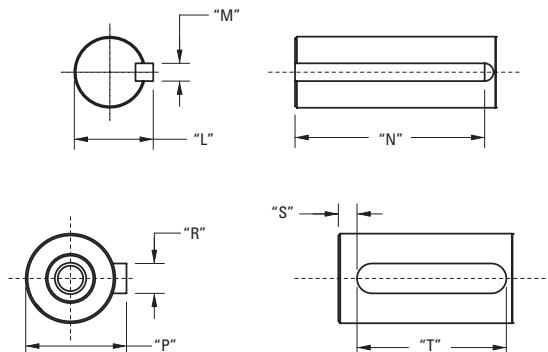
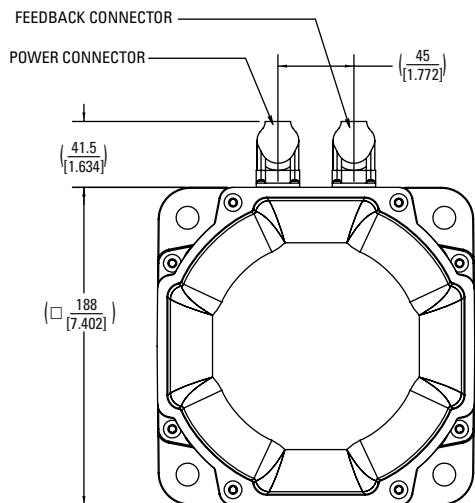
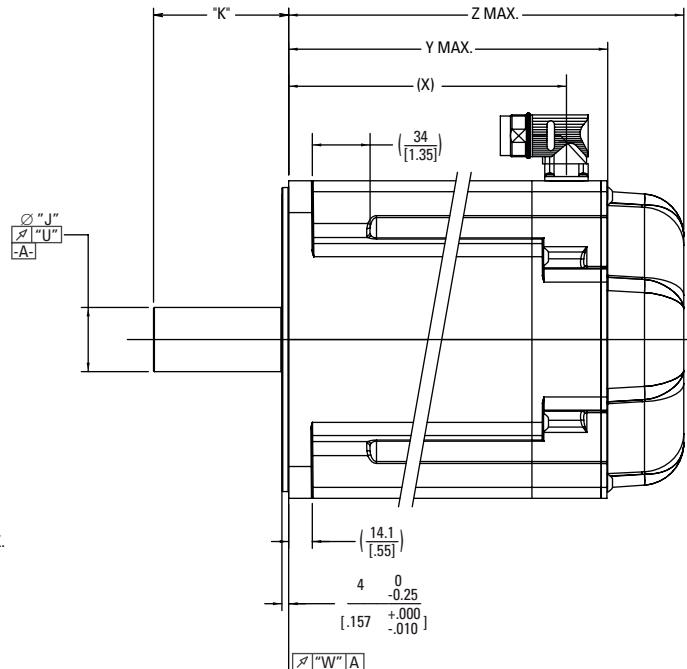
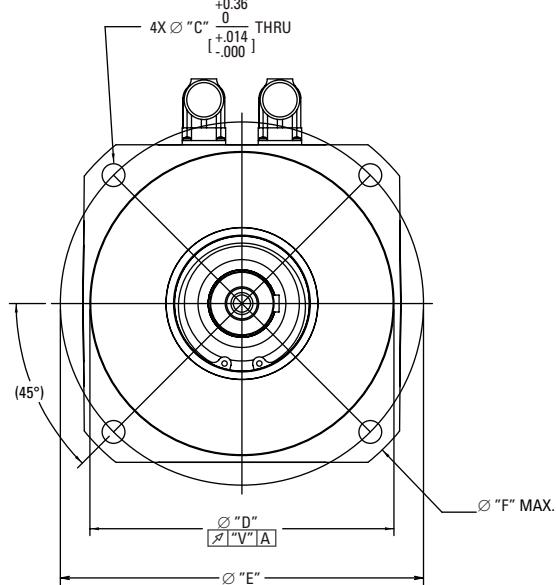
⑩ For motors with optional shaft seal, reduce torque shown by 0.25 Nm (2.21 lb-in), and increase T_f by the same amount.

Additional Notes: See system data beginning on page 14 for typical torque/speed performance.

Additional windings can be found through our online Motioneering sizing and selection software tool. See page 73 for more information.

AKM7x Outline Drawings

AKM7x Frame



AKM7x Dimension Data

AKM7x Dimension Data

Mounting Code	"C"	"D"	"E"	"F"	"H"	"J"	"K"	"L"
AC	13.50 [.531]	180 ^{+0.014} _{-0.011} [7.0866 ^{.0005} _{-.0004}] j6	215.00 [8.465]	—	D M12 DIN 332	38 ^{+0.018} _{+0.002} [1.496 ^{.0007} _{+.0001}] k6	80 [3.15]	—
AN	13.50 [.531]	180 ^{+0.014} _{-0.011} [7.0866 ^{.0005} _{-.0004}] j6	215.00 [8.465]	—	D M12 DIN 332	38 ^{+0.018} _{+0.002} [1.496 ^{.0007} _{+.0001}] k6	80 [3.15]	—
GC	13.50 [.531]	180 ^{+0.014} _{-0.011} [7.0866 ^{.0005} _{-.0004}] j6	215.00 [8.465]	—	D M12 DIN 332	32 ^{+0.018} _{+0.002} [1.5298 ^{.0007} _{+.0001}] k6	58.5 [2.30]	—
GN	13.50 [.531]	180 ^{+0.014} _{-0.011} [7.0866 ^{.0005} _{-.0004}] j6	215.00 [8.465]	—	D M12 DIN 332	32 ^{+0.018} _{+0.002} [1.5298 ^{.0007} _{+.0001}] k6	58.5 [2.30]	—
KK	13.50 [.531]	114.3 ⁰ [4.5000 ^{-.025} _{+.0000}] [-.0010]	200 [7.874]	225 [8.858]	—	35 ⁺⁰ [1.3779 ^{.016} _{+.0000}] [+.0005] h6	79 [3.11]	38 ⁰ [1.496 ^{-.29} _{+.000}] [-.011]

Mounting Code	"M"	"N"	"P"	"R"	"S"	"T"	"U"	"V"	"W"
AC	—	—	41 ⁰ [1.614 ^{.000} _{-.011}]	10 ⁰ [.3937 ^{.0000} _{-.0014}]	N9	5.00 [.197]	70 ⁰ [2.756 ^{.000} _{-.012}]	0.050 [.0019]	0.100 [.0039]
AN	—	—	—	—	—	—	0.050 [.0019]	0.100 [.0039]	0.100 [.0039]
GC	—	—	35 ⁰ [1.378 ^{.000} _{-.011}]	108 ⁰ [.3937 ^{.0000} _{-.0014}]	N9	4 [.157]	50 ⁰ [1.969 ^{.000} _{-.012}]	0.050 [.0019]	0.100 [.0039]
GN	—	—	—	—	—	—	0.050 [.0019]	0.100 [.0039]	0.100 [.0039]
KK	10 ⁰ [.3937 ^{.0000} _{-.0014}]	70 ⁰ [2.756 ^{.000} _{-.12}]	—	—	—	—	0.050 [.0019]	0.100 [.0039]	0.100 [.0039]

MODEL	Z MAX SINE ENCODER (NO BRAKE)	Z MAX SINE ENCODER (W/ BRAKE)	(X)	Y MAX	Z MAX (W/ BRAKE)
AKM72	201.7 [7.94]	253.3 [9.97]	164.5 [6.48]	192.5 [7.58]	234.5 [9.23]
AKM73	235.7 [9.38]	287.3 [11.31]	198.5 [7.81]	226.5 [8.92]	268.5 [10.57]
AKM74	269.7 [10.62]	321.3 [12.65]	232.5 [9.15]	260.5 [10.26]	302.5 [11.91]

Note 1: Dimensions are in mm [inches].

Note 2: Product designed in metric. English conversions provided for reference only.

AKM7x Performance Data

AKM7x Performance Data – Up to 640 Vdc

					AKM72			AKM73			AKM74			
Parameters			Tol	Symbol	Units	L	P	Q	L	P	Q	L	P	Q
Max Rated DC Bus Voltage	Max	Vbus	Vdc		640	640	640	640	640	640	640	640	640	640
Continuous Torque (Stall) for ΔT winding = 100°C ①②⑦⑧⑨	Nom	T _{cs}	Nm	30	29.4	29.5	42	41.6	41.5	53.0	52.5	52.2		
			lb-in	266	260	261	372	368	367	469	465	426		
Continuous Current (Stall) for ΔT winding = 100°C ①②⑦⑧⑨	Nom	I _{cs}	A _{rms}		11.5	18.7	23.5	12.1	19.5	24.5	12.9	18.5	26.1	
Continuous Torque (Stall) for ΔT winding = 60°C ②	Nom	T _{cs}	Nm	24	23.5	23.6	33.6	33.3	33.2	42.4	42.0	41.8		
			lb-in	212	208	209	297	295	294	375	372	370		
Max Mechanical Speed ⑤	Nom	N _{max}	rpm		6000	6000	6000	6000	6000	6000	6000	6000	6000	6000
Peak Torque ①②	Nom	T _p	Nm	79.5	78.5	78.4	113	111	111	143	142	141		
			lb-in	704	695	694	1000	985	982	1269	1253	1250		
Peak Current	Nom	I _p	A _{rms}		34.5	56.1	70.5	36.3	58.6	73.5	38.7	55.5	78.3	
75 Vdc		T _{rtd}	Nm	-	-	-	-	-	-	-	-	-	-	
			lb-in	-	-	-	-	-	-	-	-	-	-	
Rated Speed		N _{rtd}	rpm		-	-	-	-	-	-	-	-	-	
Rated Power (speed) ①②⑦⑧⑨		P _{rtd}	kW	-	-	-	-	-	-	-	-	-	-	
			Hp	-	-	-	-	-	-	-	-	-	-	
160 Vdc		T _{rtd}	Nm	-	-	-	-	-	-	-	-	-	-	
			lb-in	-	-	-	-	-	-	-	-	-	-	
Rated Speed		N _{rtd}	rpm		-	-	-	-	-	-	-	-	-	
Rated Power (speed) ①②⑦⑧⑨		P _{rtd}	kW	-	-	-	-	-	-	-	-	-	-	
			Hp	-	-	-	-	-	-	-	-	-	-	
320 Vdc		T _{rtd}	Nm	-	23.8	23.3	-	34.7	33.4	-	-	-	42.8	
			lb-in	-	211	205	-	307	296	-	-	-	379	
Rated Speed		N _{rtd}	rpm		-	1800	2000	-	1300	1500	-	-	-	1200
Rated Power (speed) ①②⑦⑧⑨		P _{rtd}	kW	-	4.49	4.86	-	4.72	5.25	-	-	-	5.38	
			Hp	-	6.01	6.52	-	6.33	7.04	-	-	-	7.21	
560 Vdc		T _{rtd}	Nm	25.3	20.1	16.3	34.4	28.5	25.2	43.5	39.6	31.5		
			lb-in	224	178	144	304	252	223	385	350	279		
Rated Speed		N _{rtd}	rpm	1500	3000	4000	1400	2400	3000	1200	1800	2500		
Rated Power (speed) ①②⑦⑧⑨		P _{rtd}	kW	3.97	6.31	6.83	5.04	7.16	7.92	5.47	7.46	8.25		
			Hp	5.32	8.46	9.16	6.76	9.60	10.6	7.33	10.0	11.1		
640 Vdc		T _{rtd}	Nm	24.3	18.2	14.1	33.8	26.3	22.0	41.5	35.9	27.3		
			lb-in	215	161	125	299	233	195	367	318	242		
Rated Speed		N _{rtd}	rpm	1800	3500	4500	1500	2800	3500	1400	2000	3000		
Rated Power (speed) ①②⑦⑧⑨		P _{rtd}	kW	4.58	6.67	6.65	5.31	7.71	8.07	6.08	7.52	8.58		
			Hp	6.14	8.94	8.91	7.12	10.3	10.8	8.16	10.1	11.5		

See following page for notes.

AKM7x Performance Data – Up to 640 Vdc (Continued)

Parameters	Tol	Symbol	Units	AKM72			AKM73			AKM74		
				L	P	Q	L	P	Q	L	P	Q
Torque Constant ①	±10%	K _t	Nm/A _{rms}	2.6	1.58	1.3	3.5	2.13	1.7	4.14	2.84	2.0
			lb-in/A _{rms}	23.0	14.0	11.5	31.0	18.9	15	36.6	25.1	17.7
Back EMF Constant ⑥	±10%	K _e	V/k _{rpm}	169	102	81.2	225	137	109	266	183	129
			N-m/vW	2.21	2.18	2.08	2.93	2.82	2.67	3.51	3.38	3.27
Motor Constant	Nom	K _m	lb-in/vW	19.6	19.3	18.4	25.9	25.0	23.6	31.0	29.9	28.9
			ohm	0.92	0.35	0.26	0.95	0.38	0.25	0.93	0.47	0.25
Inductance (line-line)		L	mH	13.6	5.0	3.2	15.7	5.9	3.7	16.4	7.7	3.8
			kg-cm ²	65			92			120		
Inertia (includes Resolver feedback) ③	±10%	J _m	lb-in-s ²	0.057			0.082			0.11		
			kg-cm ²	1.64			1.64			1.64		
Optional Brake Inertia (additional)	±10%	J _m	lb-in-s ²	1.46 x 10 ⁻³			1.46 x 10 ⁻³			1.46 x 10 ⁻³		
			kg	19.7			26.7			33.6		
Weight		W	lb	43.4			58.8			74.0		
			Nm	0.16			0.24			0.33		
Static Friction ①⑩		T _f	lb-in	1.4			2.1			2.9		
			Nm	0.06			0.13			0.2		
Viscous Damping ①		K _{dv}	lb-in/k _{rpm}	0.5			1.2			1.8		
			Nm/k _{rpm}	0.06			0.13			0.2		
Thermal Time Constant		TCT	minutes	46			53			60		
Thermal Resistance		R _{thw-a}	°C/W	0.39			0.33			0.30		
Pole Pairs				5			5			5		
Heat Sink Size				18"x18"x1/2" Aluminum Plate			18"x18"x1/2" Aluminum Plate			18"x18"x1/2" Aluminum Plate		

Notes:

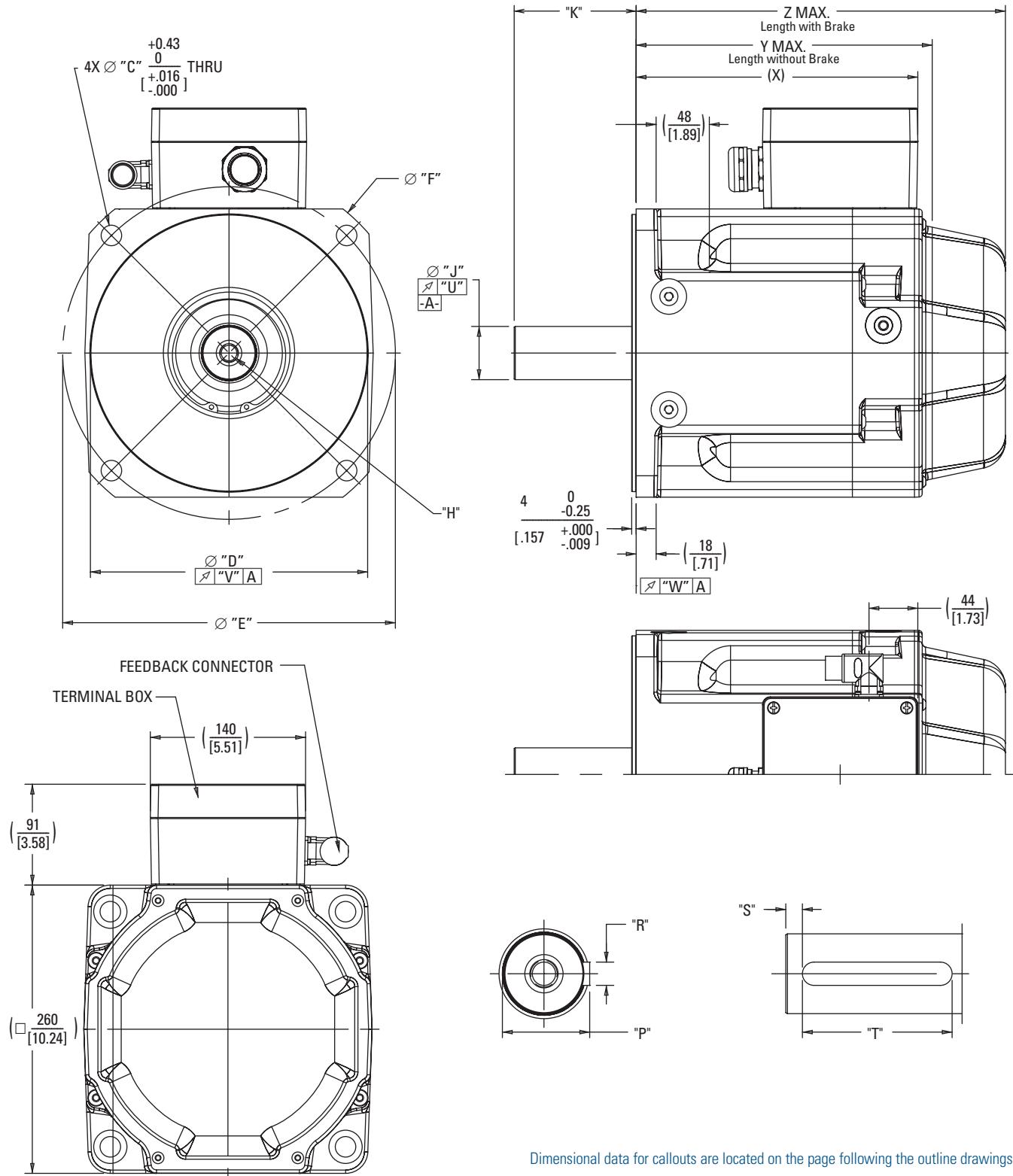
- ① Motor winding temperature rise, $\Delta T=100^{\circ}\text{C}$, at 40°C ambient.
- ② All data referenced to sinusoidal commutation.
- ③ Add parking brake if applicable for total inertia.
- ④ Motor with standard heat sink.
- ⑤ May be limited at some values of Vbus.
- ⑥ Measured at 25°C .
- ⑦ Brake motor option reduces continuous torque ratings by 1 Nm.
- ⑧ Non-Resolver feedback options reduce continuous torque ratings by:
AKM72 = 2.0 Nm AKM73 = 2.7 Nm AKM74 = 3.4 Nm
- ⑨ Motors with non-resolver feedback and brake option, reduce continuous torque by:
AKM72 = 3.9 Nm AKM73 = 5.1 Nm AKM74 = 6.2 Nm
- ⑩ For motors with optional shaft seal, reduce torque shown by 0.25 Nm (2.21 lb-in), and increase T_f by the same amount.

Additional Notes: See system data beginning on page 14 for typical torque/speed performance.

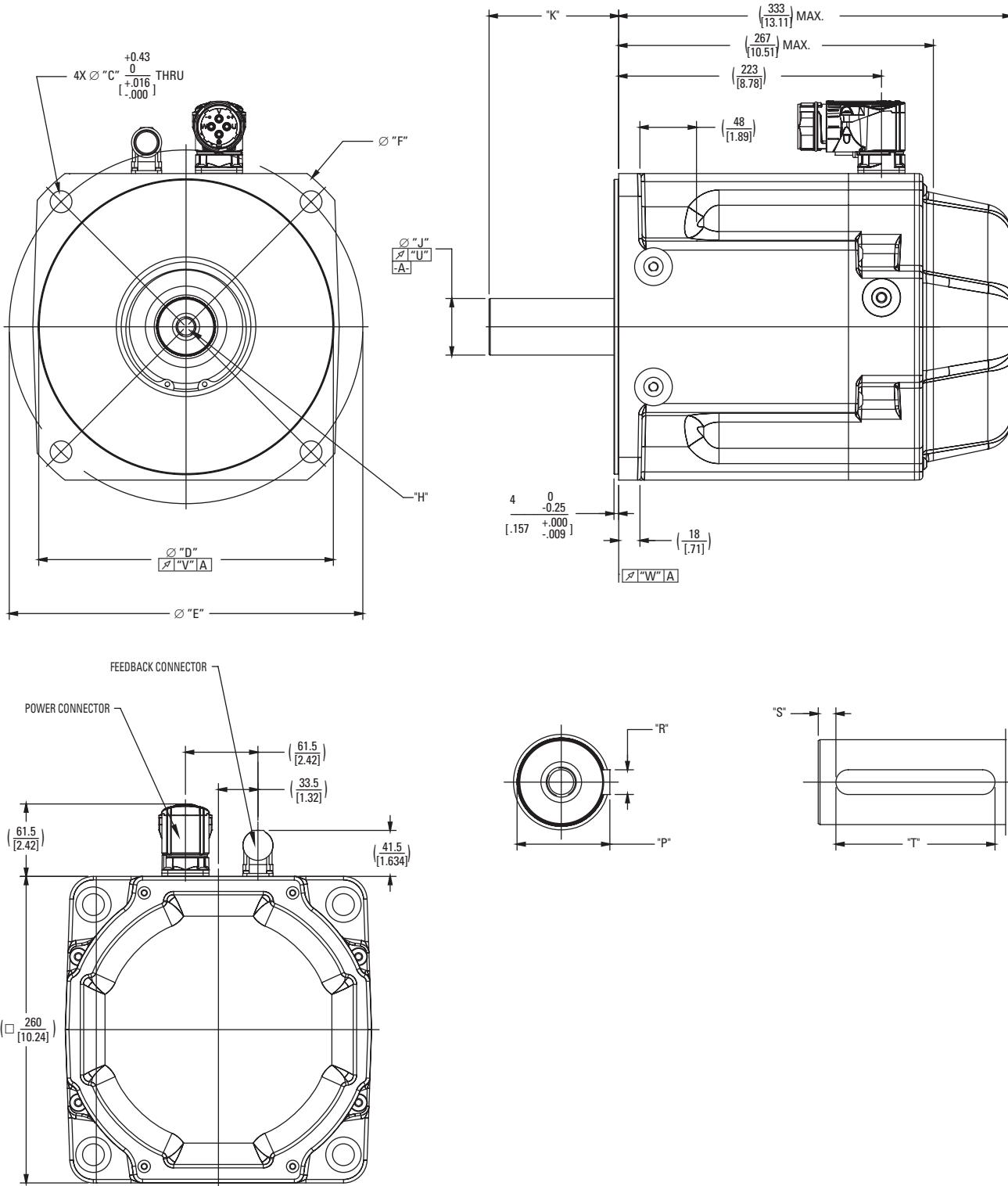
Additional windings can be found through our online Motioneer engineering sizing and selection software tool. See page 73 for more information.

AKM8x Outline Drawings

AKM8x Frame with Terminal Box



Dimensional data for callouts are located on the page following the outline drawings.

AKM82 Frame with Rotatable IP65 Connectors

Dimensional data for callouts are located on the following page.

AKM8x Dimension Data

AKM8x Dimension Data

Mounting Code	"C"	"D"	"E"	"F"	"H"	"J"	"K"	"P"	"R"	"S"	"T"	"U"	"V"	"W"
AC	18.5 [.728]	250 +0.016 -0.013 [9.8425 +0.006 -.0005] j6	300 [11.811]	-	D M16 DIN 332	48 +0.018 +0.002 [1.8898 +0.007 +.0001] k6	110 [4.33]	51.5 0 -0.29 [2.028 +0.000 -.011]	14 0 -0.043 [.5512 +0.0000 -.0016] h9	10 [.394]	90 0 -0.50 [3.543 +0.000 -.019]	0.050 [.0019]	0.125 [.0049]	0.125 [.0049]
AN	18.5 [.728]	250 +0.016 -0.013 [9.8425 +0.006 -.0005] j6	300 [11.811]	-	D M16 DIN 332	48 +0.018 +0.002 [1.8898 +0.007 +.0001] k6	110 [4.33]	-	-	-	-	0.050 [.0019]	0.125 [.0049]	0.125 [.0049]
CC	14.5 [.571]	230 +0.016 -0.013 9.055 +0.006 -.0005] j6	265 [10.433]	300 [11.811]	D M16 DIN 332	48 +0.018 +0.002 [1.8898 +0.007 +.0001] k6	110 [4.33]	51.5 0 -0.29 [2.028 +0.000 -.011]	14 0 -0.043 [.5512 +0.0000 -.0016] h9	10 [.394]	90 0 -0.50 [3.543 +0.000 -.019]	0.050 [.0019]	0.100 [.0039]	0.100 [.0039]
CN	14.5 [.571]	230 +0.016 -0.013 [9.055 +0.006 -.0005] j6	265 [10.433]	300 [11.811]	D M16 DIN 332	48 +0.018 +0.002 [1.8898 +0.007 +.0001] k6	82 [3.228]	-	-	-	-	0.050 [.0019]	0.100 [.0039]	0.100 [.0039]
HC	14.5 [.571]	230 -0.013 +0.006 [9.055 -.0005 -.0005] j6	265 [10.433]	300 [11.811]	D M16 DIN 332	42 +0.018 +0.002 [1.6535 +0.007 +.0001] k6	82 [3.228]	45 0 -0.29 [1.7772 +0.000 -.011]	12 0 -0.043 [.5512 +0.0000 -.0016] h9	8 [.315]	63 0 -0.50 [2.480 +0.000 -.019]	0.050 [.0019]	0.100 [.0039]	0.100 [.0039]
HN	14.5 [.571]	230 +0.016 -0.013 [9.055 +0.006 -.0005] j6	265 [10.433]	300 [11.811]	D M16 DIN 332	42 +0.018 +0.002 [1.6535 +0.007 +.0001] k6	82 [3.228]	-	-	-	-	0.050 [.0019]	0.100 [.0039]	0.100 [.0039]
GC	18.5 [.728]	250 +0.016 -0.013 [9.8425 +0.006 -.0005] j6	300 [11.811]	-	D M16 DIN 332	48 +0.018 +0.002 [1.8898 +0.007 +.0001] k6	82 [3.228]	51.5 0 -0.29 [2.028 +0.000 -.011]	14 0 -0.043 [.5512 +0.0000 -.0016] h9	8 [.315]	63 0 -0.50 [2.480 +0.000 -.019]	0.050 [.0019]	0.125 [.0049]	0.125 [.0049]
GN	18.5 [.728]	250 +0.016 -0.013 [9.8425 +0.006 -.0005] j6	300 [11.811]	-	D M16 DIN 332	48 +0.018 +0.002 [1.8898 +0.007 +.0001] k6	82 [3.228]	-	-	-	-	0.050 [.0019]	0.125 [.0049]	0.125 [.0049]
REINFORCED BEARINGS	MC	250 +0.016 -0.013 [9.8425 +0.006 -.0005] j6	300 [11.811]	-	D M16 DIN 332	48 +0.018 +0.002 [1.8898 +0.007 +.0001] k6	110 [4.33]	51.5 0 -0.29 [2.028 +0.000 -.011]	14 0 -0.043 [.5512 +0.0000 -.0016] h9	10 [.394]	90 0 -0.50 [3.543 +0.000 -.019]	0.050 [.0019]	0.125 [.0049]	0.125 [.0049]
	MN	250 +0.016 -0.013 [9.8425 +0.006 -.0005] j6	300 [11.811]	-	D M16 DIN 332	48 +0.018 +0.002 [1.8898 +0.007 +.0001] k6	110 [4.33]	-	-	-	-	0.050 [.0019]	0.125 [.0049]	0.125 [.0049]
	TC	230 +0.016 -0.013 [9.055 +0.006 -.0005] j6	265 [10.433]	300 [11.811]	D M16 DIN 332	48 +0.018 +0.002 [1.8898 +0.007 +.0001] k6	110 [4.33]	51.5 0 -0.29 [2.028 +0.000 -.011]	14 0 -0.043 [.5512 +0.0000 -.0016] h9	10 [.394]	90 0 -0.50 [3.543 +0.000 -.019]	0.050 [.0019]	0.100 [.0039]	0.100 [.0039]
	TN	230 +0.016 -0.013 [9.055 +0.006 -.0005] j6	265 [10.433]	300 [11.811]	D M16 DIN 332	48 +0.018 +0.002 [1.8898 +0.007 +.0001] k6	110 [4.33]	-	-	-	-	0.050 [.0019]	0.100 [.0039]	0.100 [.0039]

MODEL	(X)	Y MAX (W/O Brake)	Z MAX (W/ BRAKE)
AKM82 "H" Connector	223.0 [8.78]	267.0 [10.51]	333.0 [13.11]
AKM82 "T" TERMINAL BOX	255.0 [10.04]	267.0 [10.51]	333.0 [13.11]
AKM83 "T" TERMINAL BOX	335.5 [13.21]	347.5 [13.68]	413.5 [16.25]
AKM84 "T" TERMINAL BOX	416.0 [16.38]	428.0 [16.85]	494.0 [19.45]

Note: Dimensions are in mm [inches]. Product designed in metric. English conversions provided for reference only.

AKM8x Performance Data

AKM8x Performance Data – Up to 640 Vdc

Parameters		Tol	Symbol	Units	AKM82T	AKM83T	AKM84T
Max Rated DC Bus Voltage	Max	Vbus	Vdc	640	640	640	640
Continuous Torque (Stall) for ΔT winding = 100°C ①②⑦⑧⑨	Nom	T_{cs}	Nm	75	130	180	
			lb-in	664	1151	1593	
Continuous Current (Stall) for ΔT winding = 100°C ①②⑦⑧⑨	Nom	I_{cs}	Arms	48	62	67	
Continuous Torque (Stall) for ΔT winding = 60°C ②	Nom	T_{cs}	Nm	58.1	100	140	
			lb-in	514	885	1239	
Max Mechanical Speed ⑤	Nom	N_{max}	rpm	3000	3000	3000	
Peak Torque ①②	Nom	T_p	Nm	210	456	668	
			lb-in	1859	4036	5912	
Peak Current	Nom	I_p	Arms	240	310	335	
Rated Torque (speed) ①②⑦⑧⑨⑩		T_{rtd}	Nm	-	-	-	
			lb-in	-	-	-	
Rated Speed		N_{rtd}	rpm	-	-	-	
Rated Power (speed) ①②⑦⑧⑨		P_{rtd}	kW	-	-	-	
			Hp	-	-	-	
Rated Torque (speed) ①②⑦⑧⑨⑩		T_{rtd}	Nm	-	-	-	
			lb-in	-	-	-	
Rated Speed		N_{rtd}	rpm	-	-	-	
Rated Power (speed) ①②⑦⑧⑨		P_{rtd}	kW	-	-	-	
			Hp	-	-	-	
Rated Torque (speed) ①②⑦⑧⑨⑩		T_{rtd}	Nm	-	-	-	
			lb-in	-	-	-	
Rated Speed		N_{rtd}	rpm	-	-	-	
Rated Power (speed) ①②⑦⑧⑨		P_{rtd}	kW	-	-	-	
			Hp	-	-	-	
Rated Torque (speed) ①②⑦⑧⑨⑩		T_{rtd}	Nm	47.5	70	105	
			lb-in	420	620	929	
Rated Speed		N_{rtd}	rpm	2500	2200	1800	
Rated Power (speed) ①②⑦⑧⑨		P_{rtd}	kW	12.4	16.1	19.8	
			Hp	16.65	21.62	26.58	
Rated Torque (speed) ①②⑦⑧⑨⑩		T_{rtd}	Nm	38	60	93	
			lb-in	336	531	823	
Rated Speed		N_{rtd}	rpm	3000	2500	2000	
Rated Power (speed) ①②⑦⑧⑨		P_{rtd}	kW	11.9	15.7	19.5	
			Hp	16.0	21.0	26.1	

See following page for notes.

AKM8x Performance Data

AKM8x Performance Data – Up to 640 Vdc (Continued)

Parameters	Tol	Symbol	Units	AKM82T	AKM83T	AKM84T
Torque Constant ①	±10%	K_t	Nm/A _{rms}	1.6	2.1	2.7
			lb-in/A _{rms}	14	19	23.8
Back EMF Constant ⑥	±10%	K_e	V/krpm	108	140	177
			N-m/√W	4.31	6.94	9.15
Motor Constant	Nom	K_m	lb-in/√W	38.1	61.4	81.0
			kg-cm ²	172	334	495
Resistance (line-line) ⑥	±10%	R_m	ohm	0.092	0.061	0.058
			mH	2.73	2.36	2.5
Inductance (line-line)		L	kg-cm ²	0.15	0.29	0.43
			lb-in-s ²	5.53	5.53	5.53
Inertia (includes Resolver feedback) ③		J_m	kg-cm ²	4.90E-03	4.90E-03	4.90E-03
			lb-in-s ²			
Optional Brake Inertia (additional)		J_m	kg	49	73	97
			lb	107.8	160.6	213.4
Weight		W	Nm	1.7	1.83	2.34
			lb-in	15.05	16.20	20.71
Static Friction ①⑩		T_f	Nm/krpm	0.35	0.95	1.6
			lb-in/krpm	3.10	8.41	14.16
Viscous Damping ①		K_{dv}				
Thermal Time Constant		TCT	minutes	71	94	116
Thermal Resistance		R_{thw-a}	°C/W	0.225	0.203	0.183
Pole Pairs				5	5	5
Heat Sink Size				18"x18"x1/2" Aluminum Plate	18"x18"x1/2" Aluminum Plate	18"x18"x1/2" Aluminum Plate

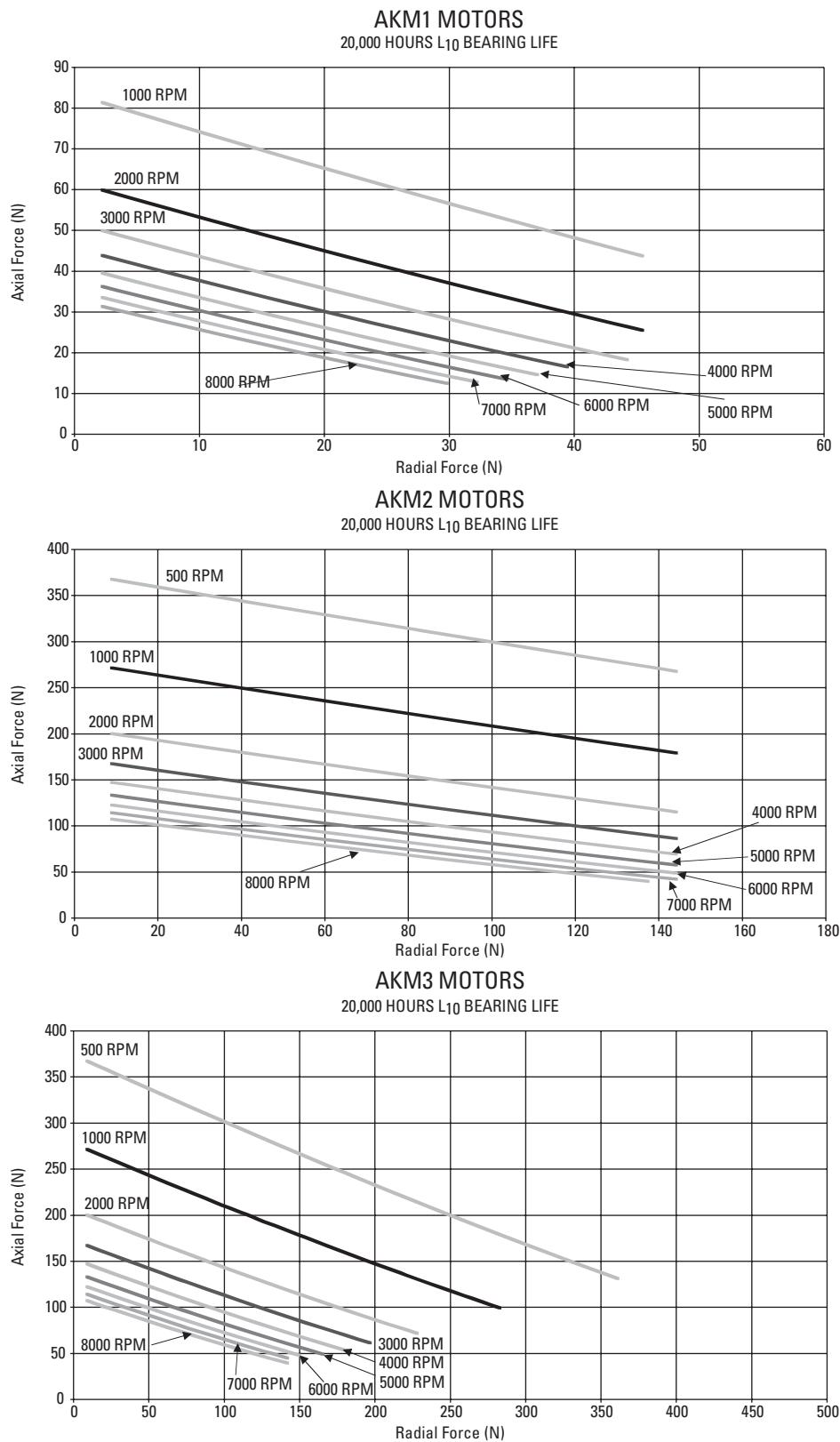
Notes:

- ① Motor winding temperature rise, $\Delta T = 100^\circ\text{C}$, at 40°C ambient.
- ② All data referenced to sinusoidal commutation.
- ③ Add parking brake if applicable for total inertia.
- ④ Motor with standard heat sink.
- ⑤ May be limited at some values of Vbus.
- ⑥ Measured at 25°C .
- ⑦ Brake option decreases continuous torque by 6Nm
- ⑧ Brake option increases weight by 9 kg
- ⑨ Non-Resolver feedback options reduce continuous torque ratings by:
AKM82 = 9 Nm, AKM83 = 6 Nm, AKM84 = 18 Nm
- ⑩ Motor with non-resolver feedback and brake options reduce continuous torque ratings by:
AKM82 = 17 Nm, AKM83 = 16 Nm, AKM84 = 28 Nm

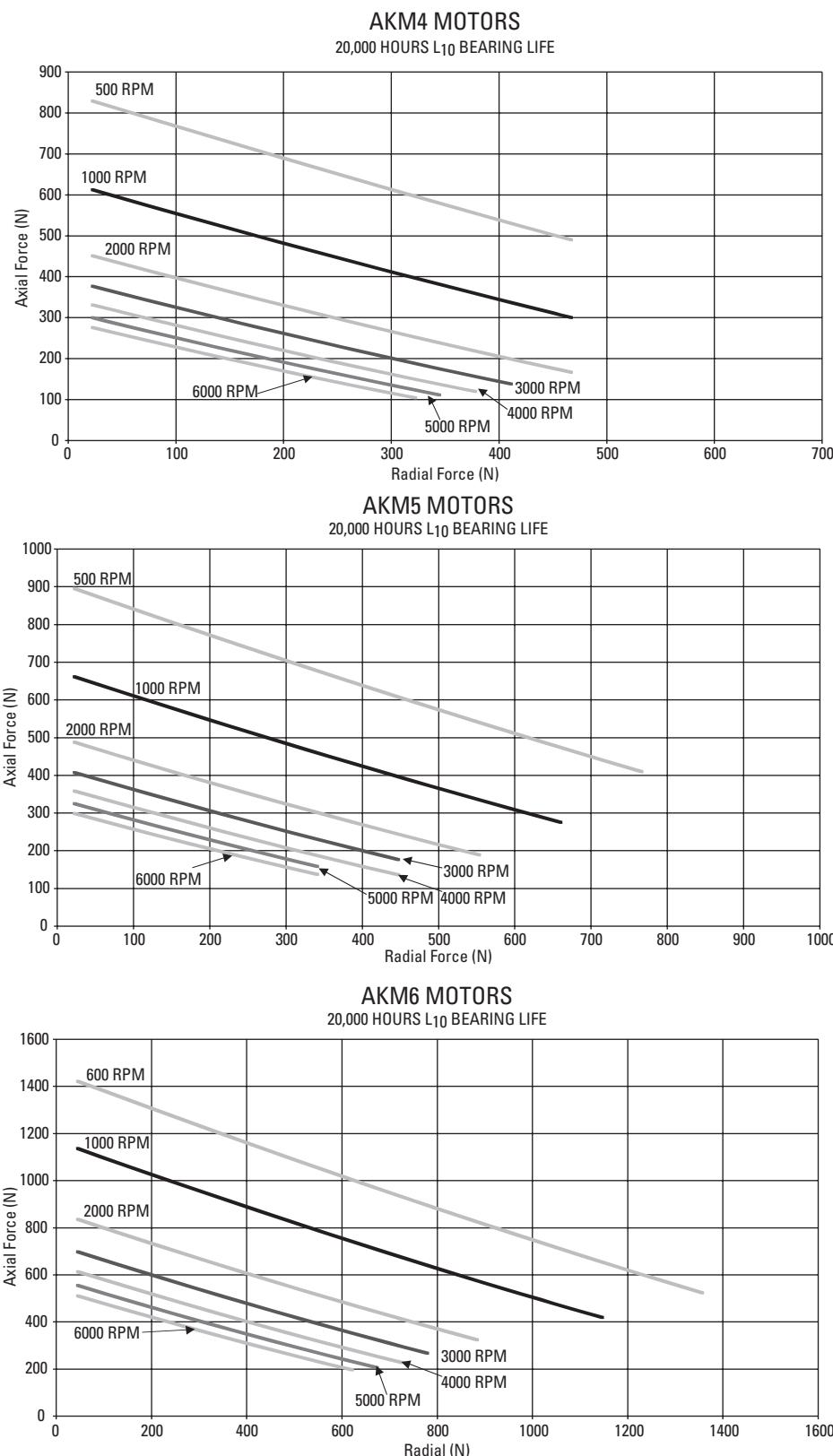
Additional Notes: See system data beginning on page 14 for typical torque/speed performance.

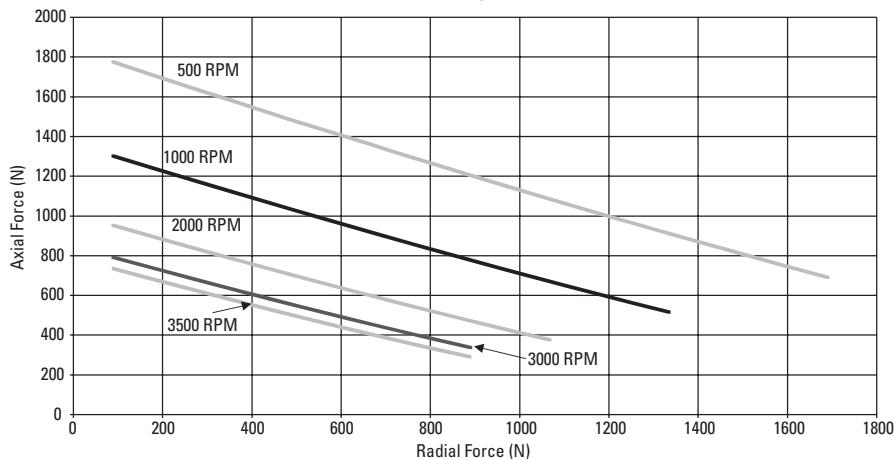
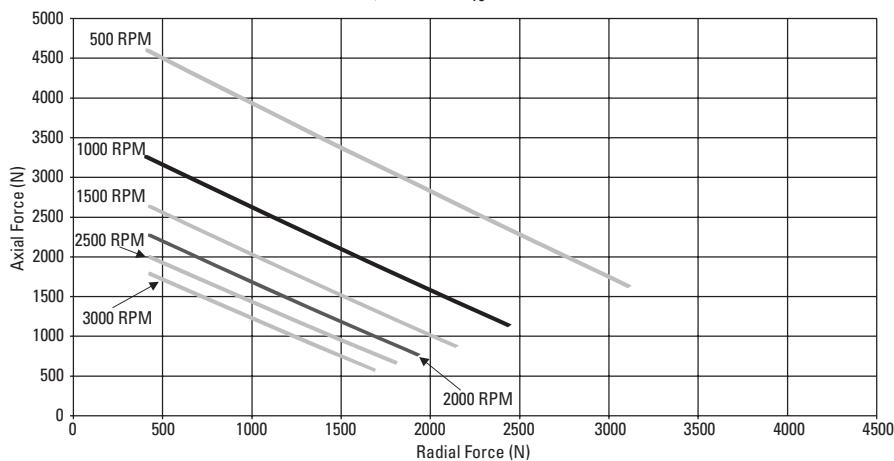
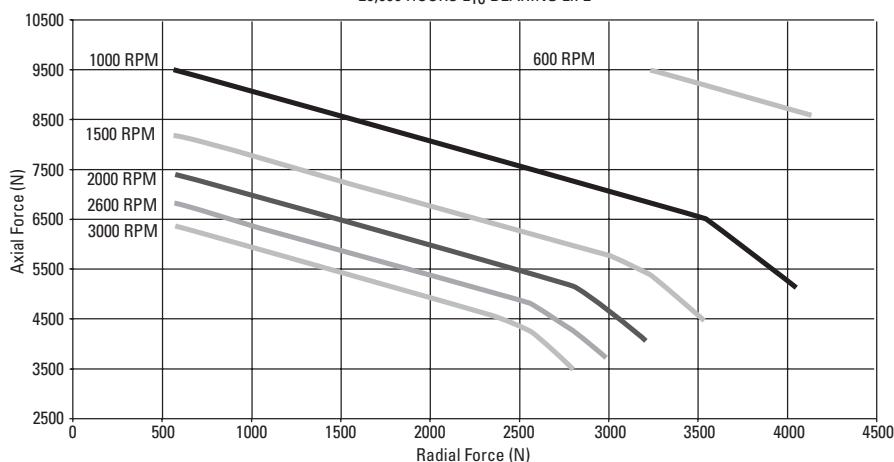
Additional windings can be found through our online Motioneer sizing and selection software tool. See page 73 for more information.

L10 Bearing Fatigue and Shaft Loading



L10 Bearing Fatigue and Shaft Loading



AKM7 MOTORS20,000 HOURS L₁₀ BEARING LIFE**AKM8 MOTORS**20,000 HOURS L₁₀ BEARING LIFE**AKM83 & 84 MOTOR WITH REINFORCED BEARING**20,000 HOURS L₁₀ BEARING LIFE**Shaft Loading**

Motor	Max. Radial Force (N)	Max. Axial Force (N)
AKM1	48	200
AKM2	150	600
AKM3	340	600
AKM4	500	1400
AKM5	830	1740
AKM6	1940	2200
AKM7	2300	3000
AKM8	2752	4750

The maximum radial load ratings reflect the following assumptions:

1. Motors are operated with peak torque of the longest member of the frame size.
2. Fully reversed load applied to the end of the smallest diameter standard mounting shaft extension. Excluding AKM4X-EK which is rated at 240 N max. radial force.
3. Infinite life with 99% reliability.
4. Safety factor = 2.

Teflon Shaft Seals

There is a normal break-in period for our Teflon shaft seals. Best conditions during the break-in period would be at the operational temperature and speed that would be typical for the application.

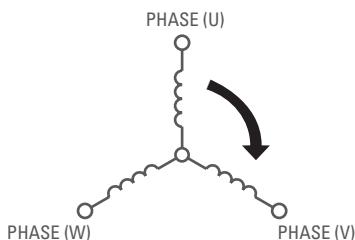
During the break-in period, some "shedding" of Teflon material is normal. The debris is not a sign of seal deterioration or failure. The material "shed" should be reduced with usage.

Typically, a few hours at operational speed is enough to break-in the shaft seal.

Feedback Options

Phasing Diagram - All Motors

Motor Winding Configuration



General notes:

- 1 When motor is rotated CW (viewed from drive shaft end), these waveforms result:
Voltage U , leads V , leads W.
Voltage U-W leads Voltage V-W by 60° electrical.
- 2A PTC thermistor ($155^{\circ}\text{C} \pm 5^{\circ}\text{C}$ switching temperature) installed.
Resistance at 25°C : ≤ 550 ohms.
Switching Resistance: ≥ 1330 ohms within $\pm 5^{\circ}\text{C}$ of switch temperature.

- 2B Optional KTY84-130 Nominal Resistance at 25°C , 603 ohms.
- 2C Optional KTY83-110 Nominal Resistance at 25°C , 1000 ohms.
- 3 When optional shaft seal is included on front shaft extension, note that static friction stated in catalog or on winding data sheet is measured without shaft seal installed.
- 4 Standard outline drawings showing mounting dimensions and standard winding information are available on our website or by calling the Kollmorgen Customer Support at 1-540-633-3545, or through email at support@kollmorgen.com.

Feedback Summary for AKM Servomotor with AKD Servo Drive

Feedback Device/ (Motor designation)	Plug & Play, Motor ID ³	AKM Models	Device Resolution Cycles or Lines/rev	Resolution after AKD Interpolation ⁴ : counts (arc-min)	Accuracy: Arc-min (±)
Comcoder (1-)	N	AKM1-8	1024	4096 (5.27)	5.27
Comcoder (2-)	N	AKM1-8	2048	8192 (2.64)	2.64
Resolver (R-)	N	AKM1	1	65536 (0.330)	15
		AKM2-8			8
SFD (C-)	Y	AKM1	16,777,216 (0.00129 arc-min)	N/A	16
		AKM2-8			9
Endat 2.1 ¹ (DA)	Y	AKM2-4	512	134,217,728 (0.000161)	1.0
		AKM5-8	2048		0.333
Endat 2.1Multi-turn ^{1,2} (DB)	Y	AKM2-4	512	134,217,728 (0.000161)	1.0
		AKM5-8	2048		0.333
BiSS ¹ (AA)	Y	AKM2-8	2048	134,217,728 (0.000161)	0.60
BiSS Multi-turn ^{1,2} (AB)	Y	AKM2-8	2048	134,217,728 (0.000161)	0.60
Inductive enc. ¹ (LA)	Y	AKM2,3	16	1,048,576 (0.0206)	8
		AKM4-7	32	2,097,152 (0.0103)	4.66
Inductive enc. Multi-turn ^{1,2} (LB)	Y	AKM2,3	16	1,048,576 (0.0206)	8
		AKM4-7	32	2,097,152 (0.0103)	4.66

Note 1: Not available for AKM1.

Note 2: Provides 4096 turns of absolute positioning.

Note 3: These feedback devices include electronic motor nameplate data allowing plug-and-play commissioning, eliminating the need for drive parameter set-up and servo loop tuning in most applications.

Note 4: AKD interpolation for sinusoidal feedback devices is 2^{16} , however the resulting usable resolution for positioning may be much less for very high resolution systems.

Servomotor Feedback Combinations

AKM Family of Servomotors with Smart Feedback Device (SFD)

The SFD Feedback communicates with the drive over a four-wire interface. Two wires supply +5V power at <150 mA and the second pair is an RS-485 digital communications link. The device includes EEPROM memory to save motor parameters.

Angle Measurement:

Resolution: $2^{24} = 16,777,216$ counts per rev
 $= 0.0013$ arc-min
 Accuracy: $< \pm 0.75$ arc-min electrical + sensor error
 Size 10 sensor ± 16 arc-min net (AKM 1)
 Size 15 sensor ± 9 arc-min net (AKM 2,3,4)
 Size 21 sensor ± 9 arc-min net (AKM 5,6,7)
 Electrical Noise: $< 2^{17}$ Rev rms at full bandwidth
 Bandwidth: > 2000 Hz at -3 dB
 > 1000 Hz at -45° phase lag
 Max Tracking Rate: > 50,000 RPM
 Velocity Ripple: < 0.2% p-p electronics only
 Size 10 sensor < 2.5% p-p net (AKM 1)
 Size 15 sensor < 1.5% p-p net (AKM 2,3,4)
 Size 21 sensor < 1.5% p-p net (AKM 5,6,7)
 Velocity Noise: < 4 RPM rms at full bandwidth

Digital Communications:

Baud Rate: 2.5 MBaud
 Signaling: RS-485 differential, 8 bit data with odd parity compatible with standard UARTs
 Update Period: Once every 51.2 uSec new position sample
 Error Detection: 5 bit CRC in addition to parity check
 EEPROM Memory: Does a data dump when the unit powers up.

Power Supply:

Supply at Drive: 5.0 V ± 0.25 V ($\pm 5\%$)
 Supply at SFD in motor: 4.25 V to 5.25 V
 Nominal Supply Current: 120 mA
 Worst Case Supply: 150 mA
 Cable Resistance: +5V, Rtn: < 3.3 Ohm net

Environmental:

Operating Ambient: -20 to 120° C
 Humidity: 10% to 90% non-condensing
 Storage Temperature: -40 to 135°C

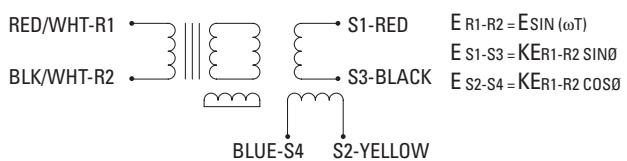
Resolver (Feedback)

Resolver Data	Units	AKM 1	AKM 2, 3, 4	AKM 5, 6, 7, 8
Type		1 Speed	1 Speed	1 Speed
Input Voltage	V _{RMS}	7.0	7.0	7.0
	k Hz	10	10	10
Input Current Max.	mA	30	50	50
Transformation Ratio	10%	0.5	0.5	0.5
Null Voltage	mV _{RMS}	50	30	30
Max. Error (pk-pk)	MINS.	30	18	18
Phase Shift	Degrees	-9	0	0
Operating Temperature	°C	-55° to 155°	-55° to 155°	-55° to 155°
Rotor Inertia Max.	kg-cm ²	0.002	0.046	0.497

Resolver Alignment

With positive DC current into phase W and out of phase V (U floats) the resolver is aligned to electrical ± 5 counts. ie. Voltage S1-S3 set to null voltage S2-S4 max in phase with reference (R1-R2).

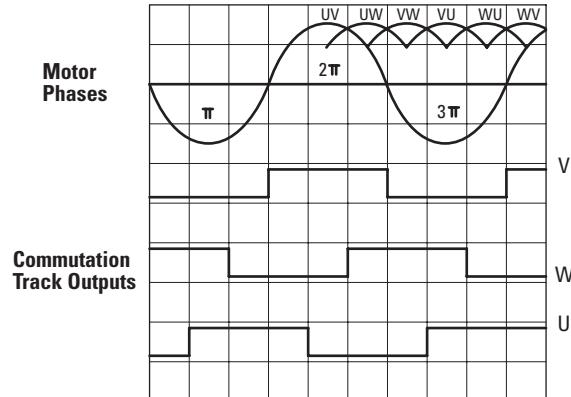
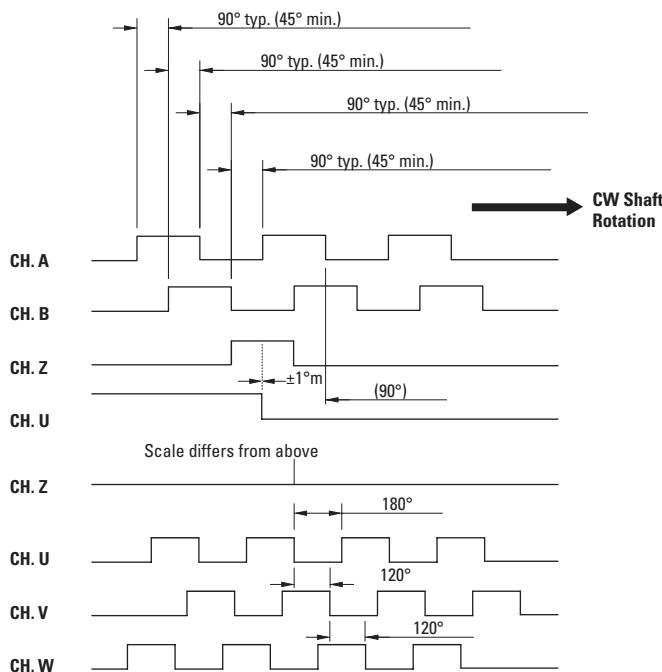
Resolver Winding Configuration



Servomotor Feedback Combinations

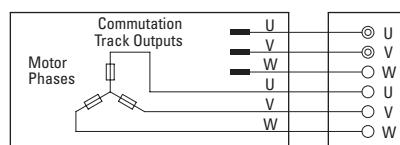
Commutating Encoder Option

Commutating Encoder



Max. Misalignment between rising edge of commutation track V & zero crossing of back EMF UV <= 5° electrical.

Motor Connections



Output Comm: Open Collector W 2.2 k OHMS
External Pull Ups
(SINK 8 mA MAX.)

Parameter	Units	1- (AKM1-8)	2- (AKM1-8)	ED (AKM2-8)	EE (AKM2-8)	EF (AKM2-4)	EF (AKM5-8)	EG (AKM2-8)	EM (AKM2-8)	EH (AKM2-8)	EN (AKM5-8)	EJ (AKM5-8)
Input Voltage	Vdc ±10%						5					
Output Data												
Line Count		1,024	2,048	500	1,000	2,000	2,000	2,500	4,096	5,000	8,192	10,000
Frequency Response	KHz	200	200	200	200	200	200	200	500	500	1000	1000
Max. Speed	RPM	12,000	12,000	12,000	12,000	12,000	7,500	12,000	7,324	8,000	3,662	3,000
Min. Edge Separation of Incremental Channel	°e MIN.						45					
Index to U Comm Channel							±/-1°m Index Center To U Falling Edge					
Index Pulse Width							Gated With B Low					
Incremental Channel Accuracy							±1 Arc Min. (AKM2-8), ±2.5 Arc Min. (AKM1) Max. Edge to Edge					
Max. Acceleration	Rad/s ²						100,000					
Operating Temperature	°C						0-120					
Storage Temperature	°C		0-120					-40 - 120				

	Type	AKM1	AKM2	AKM3	AKM4	AKM5, 6, 7, 8
Commutating Channel	All Models	6 Pole 60°m ±6 Min.	6 Pole 60°m ±6 Min.	8 Pole 45°m ±6 Min.	10 Pole 36°m ±6 Min.	10 Pole 36°m ±6 Min.
Moment of Inertia (kg·cm ²)	1-2-	0.0016	0.0048	0.0048	0.0048	0.0275
	All Ex Models	NA	0.0048	0.0048	0.0048	0.0275

Absolute Sine Encoder Options

Encoder Alignment

With positive DC current into phase W and out of phase V (U floats) the encoder is aligned to ± 1 electrical degree¹.

EnDat Optical

Type	Single-Turn "DA"		Multi-Turn "DB"	
Frame Size	AKM 2, 3, 4	AKM 5, 6, 7, 8	AKM 2, 3, 4	AKM 5, 6, 7, 8
Cycles Per Revolution	512	2048	512	2048
Input Voltage	Vdc $\pm 5\%$	5	5	5
Current Consumption	mA MAX.	160	150	200
Operating Temperature	$^{\circ}\text{C}$ MIN/MAX	-20/115	-20/115	-20/115
Inertia	kg-cm ²	0.040	0.260	0.040
Output Interface	HEIDENHAIN EnDat			
Type	ECN1113	ECN1313	EQN1125	EQN1325

EnDat Inductive

Type	Single-Turn "LA"		Multi-Turn "LB"	
Frame Size	AKM 2, 3	AKM 4, 5, 6, 7	AKM 2, 3	AKM 4, 5, 6, 7
Cycles Per Revolution	16	32	16	32
Input Voltage	Vdc $\pm 5\%$	5	5	5
Current Consumption	mA MAX.	160	170	190
Operating Temperature	$^{\circ}\text{C}$ MIN/MAX	-20/115	-20/115	-20/115
Inertia	kg-cm ²	0.0076	0.022	0.0076
Output Interface	HEIDENHAIN EnDat			
Type	ECI 1118	ECI1319	EQI 1130	EQI1331

BiSS Optical

Type	Single-Turn "AA"		Multi-Turn "AB"	
Frame Size	AKM 2, 3, 4	AKM 5, 6, 7, 8	AKM 2, 3, 4	AKM 5, 6, 7, 8
Cycles Per Revolution	2048	2048	2048	2048
Input Voltage	Vdc $\pm 5\%$	5	5	5
Current Consumption	mA MAX.	45	70	85
Operating Temperature	$^{\circ}\text{C}$ MIN/MAX	-20/115	-20/115	-20/115
Inertia	kg-cm ²	0.025	0.038	0.025
Output Interface	BiSS			
Type	AD36	AD58	AD36	AD58

Note 1: EnDat Inductive is aligned to +/- 3 electrical degrees

Brake Option

Failsafe, Holding Brake

The holding brake is designed to provide static holding torque to the motor shaft with the brake coil de-energized. The brake must first be released (coil energized) prior to commanding motor rotation as determined by its drop-out time. The brake is intended for holding or “parking” of a stationary motor. It is not intended for dynamic braking. There should be absolutely no motion of the rotor when power is removed from the brake coil.

AKM Motor Brake Specifications

Motor Family	Minimum Static Torque @120°C		Weight		Power Consumption @24V, 20°C	Current @24V, 20°C	Inertia		Closing Time (engage)	Opening Time (release)	Backlash	
	Nm	lb-in	Kg	lb			ADC	kg·cm²	lb-in·sec²		Maximum	Typical
AKM2	1.42	12.6	0.27	0.59	8.4	0.35	0.011	0.97E-05	36	35	1.01	0.46
AKM3	2.5	22.1	0.35	0.77	10.1	0.42	0.011	0.97E-05	20	50	1.01	0.46
AKM4	5.3	46.9	0.63	1.39	12.8	0.53	0.068	6.02E-05	30	75	0.81	0.37
AKM5	14.5	128	1.1	2.42	19.5	0.82	0.173	1.53E-04	30	115	0.71	0.31
AKM6	25	221	2	4.4	25.7	1.07	0.605	5.35E-04	40	155	0.51	0.24
AKM7	53	469	2.9	6.38	35.6	1.48	1.64	1.46E-03	70	170	0.44	0.20
AKM8	150	1330	8	17.5	49	2.04	5.53	4.90E-03	100	300	0.44	0.20

Note 1: Contamination of the motor internal compartment by oil or other foreign materials will result in failure of the brake. Check the suitability of motor sealing for the working environment.

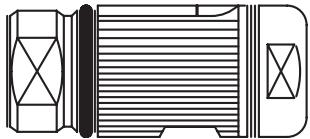
Note 2: Operating Voltage: 24 Vdc ± 10%.

Note 3: Maximum backlash is calculated using worst-case tolerancing, and typical backlash is calculated using statistical tolerancing.

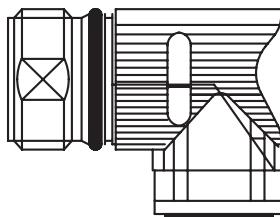
Servomotor Connector Options

B, C, G, H, & T Power Connectors

B, C- Connector

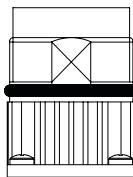


Cable Option (AKM 1& 2 Only)
Connector Part Number:
BKUA-199-NN-00-11-0035-000
(For AKM 1 & 2)



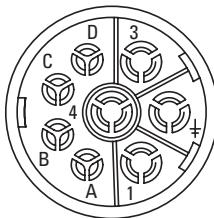
Motor Mounted Option
Connector Part Number:
BEDC-089-NN-00-00-0005-000

G- Connector



Motor Mounted Option
Connector Part Number:
BEDC-089-NN-00-00-0011-000
(AKM 2, 3, 4, 5, 6 & 7)

Power Connector (View Facing Front)



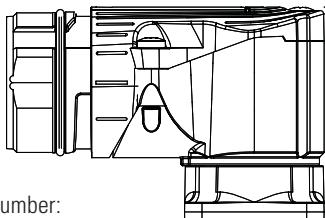
Pin	Function	Color
1	U	Blue
‡	PE	Grn/Yel
3	W	Violet
4	V	Brown
A	Brake +	Black
B	Brake -	Black
C	N/C	
D	N/C	

Shield Connected to Motor
Ground Internal to Motor
(For AKM 1 & 2)

Suggested Mating Connector

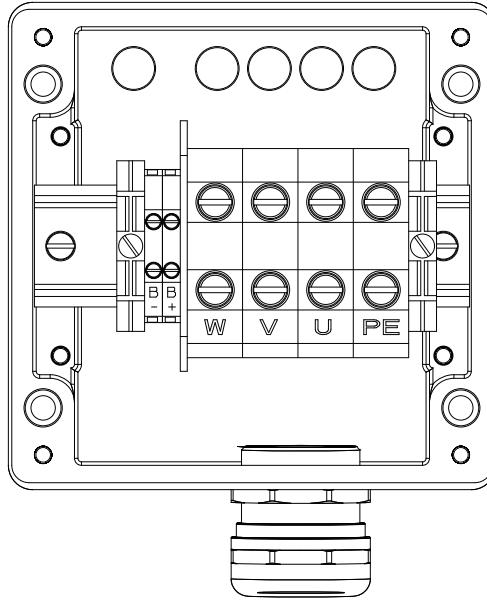
Intercontec
BSTA-108-NN-00-08-0036-000

H- Connector

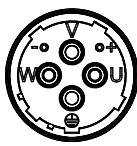


Connector Part Number:
CEDE-270-NN-00-00-0051-000

T- Connector



Power Connector (View Facing Front)



Pin	Function	Color
U	U	Blue
‡	PE	Grn/Yel
W	W	Violet
W	V	Brown
+	Brake +	Black
-	Brake -	Black

Suggested Mating Connector

Intercontec
CSTA-263-NN-00-45-0001-000

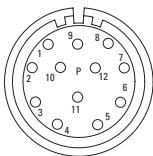
Shield Connected to Motor
Ground Internal to Motor

Terminal Box AKM8 Only

Servomotor Connector Options

B, C, G, H, & T Feedback Connectors

SFD Feedback (View Facing Front)



Connector Part Number:
AKUA-020-NN-00-09-0035-000 (For AKM 1 & 2)
AEDC-052-NN-00-00-0012-000 (For AKM 2, 3, 4, 5, 6, 7, & 8)

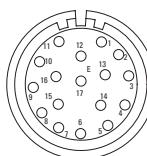
Pin	Function	Color
1	SFD +5V	Red
2	SFD +5V RTN	Black
3	SFD COM-	Yellow
4	SFD COM+	Blue
5	SFD COM Shield (AKM 1, 2)	
6	N/C	
7	N/C	
8	N/C	
9	N/C	
10	N/C	
11	N/C	
12	N/C	

Shield is Not Connected at Motor End

Suggested Mating Connector

Intercontec
ASTA-021-NN-00-10-0035-000

Commutating Encoder (View Facing Front)



Connector Part Number:
AKUA-034-NN-00-09-0035-000 (For AKM 1 & 2)
AEDC-113-NN-00-00-0012-000 (For AKM 2, 3, 4, 5, 6, & 7)

Pin	Function	Color
1	B	Green
2	\bar{B}	Gn/Blk
3	A	Blue
4	\bar{A}	Blue/Blk
5	Z	Violet
6	\bar{Z}	Violet/Blk
7	Gnd	Black
8	Thermal Sensor +	Orange
9	Thermal Sensor -	Orange/White
10	Vcc	Red
11	N/C	
12	N/C	
13	N/C	
14	N/C	
15	U	Brown
16	V	Grey
17	W	White

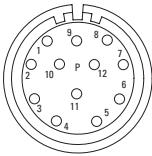
Shield is Not Connected at Motor End
On motor mounted connectors, the thermal sensor lead colors
are (+) Blue, (-) Black.

Suggested Mating Connector

Intercontec
ASTA-035-NN-00-10-0035-000

B, C, G, H, & T Feedback Connectors

Resolver (View Facing Front)



Connector Part Number:
AKUA-020-NN-00-09-0035-000 (For AKM 1 & 2)
AEDC-052-NN-00-00-0012-000 (For AKM 2, 3, 4, 5, 6, 7, & 8)

Pin	Function	Color
1	N/C	
2	Thermal Sensor +	Orange
3	S4, COS-	Blue
4	S3, SIN-	Black
5	R2, REF-	Blk/Wht
6	Thermal Sensor -	Orange/White
7	S2, COS+	Yellow
8	S1, SIN+	Red
9	R1, REF+	Red/Wht
10	N/C	
11	N/C	
12	N/C	

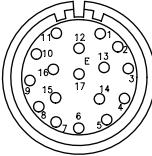
Shield is Not Connected at Motor End
On motor mounted connectors, the thermal sensor lead colors are (+) Blue, (-) Black.

Suggested Mating Connector

Intercontec

ASTA-021-NN-00-10-0035-000

"AA" & "AB" Absolute Encoder (View Facing Front)



Connector Part Number:
AEDC-113-NN-00-00-0012-000 (For AKM 3, 4, 5, 6, & 7)

Pin	Function	Color
1	B-	Red/Blk
2	Gnd	Wht/Blk
3	A-	Yel/Blk
4	Vcc (5Vdc)	Brn/Grn
5	Data	Gray
6	N/C	
7	Thermal Sensor+	Green
8	Clock	Violet
9	B+	Blu/Blk
10	Un Sense (Common)	White
11	A+	Grn/Blk
12	Up Sense (VCC)	Blue
13	Data	Pink
14	Thermal Sensor-	Brown
15	Clock	Yellow
16	N/C	
17	N/C	

Shield is Not Connected at Motor End

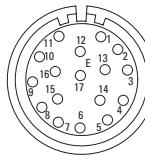
Suggested Mating Connector

Intercontec

ASTA-035-NN-00-10-0035-000

"DA" & "DB" Absolute Encoder (View Facing Front)

"LA" & "LB" Absolute Encoder (Inductive)



Connector Part Number:
AKUA-034-NN-00-09-0035-000 (For AKM 2)
AEDC-113-NN-00-00-0012-000 (For AKM 3, 4, 5, 6, 7 & 8)

Pin	Function	Color	AKM3, 4, 5, 6, 7, 8 (Motor-mounted connector)
1	B-	Red/Blk	Red/Blk
2	GND	Wht/Grn	Wht/Grn
3	A-	Yel/Blk	Yel/Blk
4	Vcc (5Vdc)	Brn/Grn	Brn/Grn
5	Data	Gray	Gray
6	N/C		
7	Thermal Sensor +	Green	Blue
8	Clock	Violet	Violet
9	B+	Blu/Blk	Blu/Blk
10	Un Sense (common)	White	White
11	A+	Grn/Blk	Grn/Blk
12	Up Sense (VCC)	Blue	Blue
13	Data	Pink	Pink
14	Thermal Sensor-	Brown	Black
15	Clock	Yellow	Yellow
16	N/C		
17	N/C		

Shield is Not Connected at Motor End

Suggested Mating Connector

Intercontec

ASTA-035-NN-00-10-0035-000

Option "DA" = Single-Turn Absolute
Option "DB" = Multi-Turn Absolute

Mating Connector Kits

(For Use On Motors With "C & G" Connectors Only)

Connector Part Number: BEDC-089-NN-00-00-0005-000

Resolver	CKT-T1A-SRE	CKT-T1B-SRE
Encoder	CKT-T1A-SCE	CKT-T1B-SCE

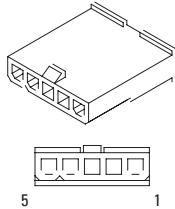
Mating Connector Kits Include Both Power and Feedback Connectors.

Servomotor Connector Options

"M" Connector Options

(AKM 1, 2, 3 & 4 Only) If additional dimensions or connectors are required, contact Kollmorgen Customer Support.

Power Connector (Non Brake, View Facing Front)



Connector Part Number: Molex 39-01-4056 (Eng No. 5559-05P3)

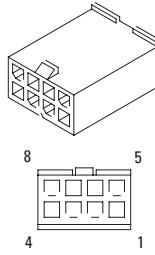
Pin	Function	Color
1	U	Blue
2	V	Brown
3	W	Violet
4	Gnd	Grn/Yel
5	Shield	

Shield Connected to Motor
Ground Internal to Motor

Suggested Mating Connector

Molex 39-01-4050

Power Connector (Brake, View Facing Front)



Connector Part Number:
Molex 39-01-3083 (Eng No. 5559-08P1)

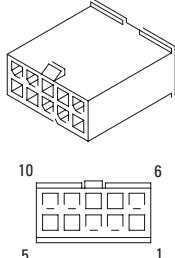
Pin	Function	Color
1	U	Blue
2	V	Brown
3	W	Violet
4	Gnd	Grn/Yel
5	Shield	
6	Brake+	Black
7	Brake-	Black
8	N/C	

Shield Connected to Motor
Ground Internal to Motor

Suggested Mating Connector

Molex 39-01-2080

SFD (View Facing Front)



Connector Part Number: Molex 43020-1001

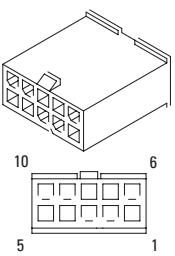
Pin	Function	Color
1	SFD +5V	Red
2	SFD +5V RTN	Black
3	SFD COM-	Yellow
4	SFD COM+	Blue
5	SFD COM Shield	
6	N/C	
7	N/C	
8	N/C	
9	N/C	
10	N/C	

Shield Is Not Connected at Motor End

Suggested Mating Connector

Molex 43025-1000

Resolver (View Facing Front)



Connector Part Number: Molex 43020-1001

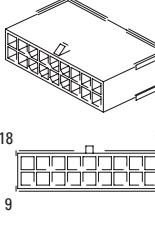
Pin	Function	Color
1	N/C	
2	Thermal Sensor +	Orange
3	S4, COS-	Blue
4	S3, SIN-	Black
5	R2, REF-	Blk/Wht
6	Thermal Sensor -	Orange/White
7	S2, COS+	Yellow
8	S1, SIN+	Red
9	R1, REF+	Red/Wht
10	Shield	

Shield Is Not Connected at Motor End

Suggested Mating Connector

Molex 43025-1000

Commutating Encoder (View Facing Front)



Connector Part Number: Molex 43020-1801

Pin	Function	Color
1	B	Green
2	\bar{B}	Grn/Blk
3	A	Blue
4	\bar{A}	Blue/Blk
5	Z	Violet
6	\bar{Z}	Violet/Blk
7	Gnd	Black
8	Thermal Sensor +	Orange
9	Thermal Sensor -	Orange/White
10	Vcc	Red
11	N/C	
12	N/C	
13	N/C	
14	N/C	
15	U	Brown
16	V	Grey
17	W	White
18	Shield	

Shield Is Not Connected at Motor End

Suggested Mating Connector

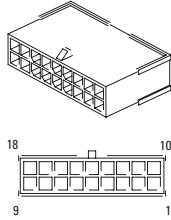
Molex 43025-1800

"M" Connector Options

(AKM 1, 2, 3 & 4 Only) If additional dimensions or connectors are required, contact Kollmorgen Customer Support.

"DA" & "DB" Absolute Encoder (View Facing Front)

"LA" & "LB" Absolute Encoder (View Facing Front)



Connector Part Number: Molex 43020-1801

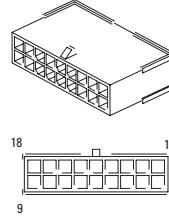
Pin	Function	Color
1	B-	Red/Blk
2	Gnd	Wht/Blk
3	A-	Yel/Blk
4	Vcc (5Vdc)	Brn/Grn
5	Data	Gray
6	N/C	
7	Thermal Sensor+	Green
8	Clock	Violet
9	B+	Blu/Blk
10	Un Sense (Common)	White
11	A+	Grn/Blk
12	Up Sense (VCC)	Blue
13	Data	Pink
14	Thermal Sensor-	Brown
15	Clock	Yellow
16	N/C	
17	N/C	
18	Shield	

Shield is Not Connected at Motor End

Suggested Mating Connector

Molex 43025-1800

"AA" & "AB" Absolute Encoder (View Facing Front)



Connector Part Number: Molex 43020-1801

Pin	Function	Color
1	B-	Red/Blk
2	Gnd	Wht/Blk
3	A-	Yel/Blk
4	Vcc (5Vdc)	Brn/Grn
5	Data	Gray
6	N/C	
7	Thermal Sensor+	Green
8	Clock	Violet
9	B+	Blu/Blk
10	Un Sense (Common)	White
11	A+	Grn/Blk
12	Up Sense (VCC)	Blue
13	Data	Pink
14	Thermal Sensor-	Brown
15	Clock	Yellow
16	N/C	
17	N/C	
18	N/C	

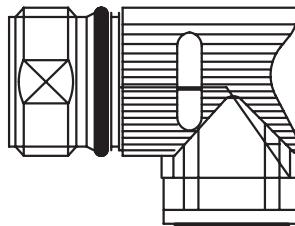
Shield is Not Connected at Motor End

Suggested Mating Connector

Molex 43025-1800

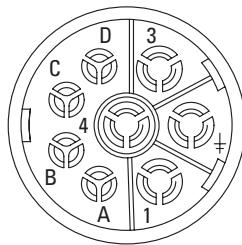
Servomotor Connector Options

"D" Connector Options



Motor Mounted Option (AKM 2, 3 & 4 Only)

Combined Power & SFD Feedback (View Facing Front)



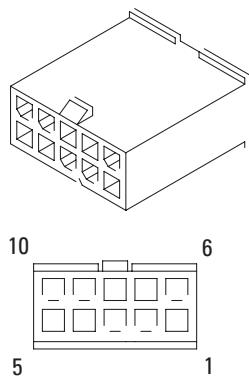
Connector Part Number: BEDC-089-NN-00-00-0005-000

Pin	Function	Color	Suggested Mating Connector
1	U	Blue	
‡	PE	Grn/Yel	
3	W	Violet	
4	V	Brown	
A	SFD +5V	Red	
B	SFD +5V RTN	Black	
C	SFD COM-	Yellow	
D	SFD COM+	Blue	Intercontec BSTA-108-NN-00-08-0036-000

"P" Connector Options

(AKM 1, 2, 3 & 4 Only)

Combined Power & SFD Feedback (Not Available for Brake Motors, View Facing Front)

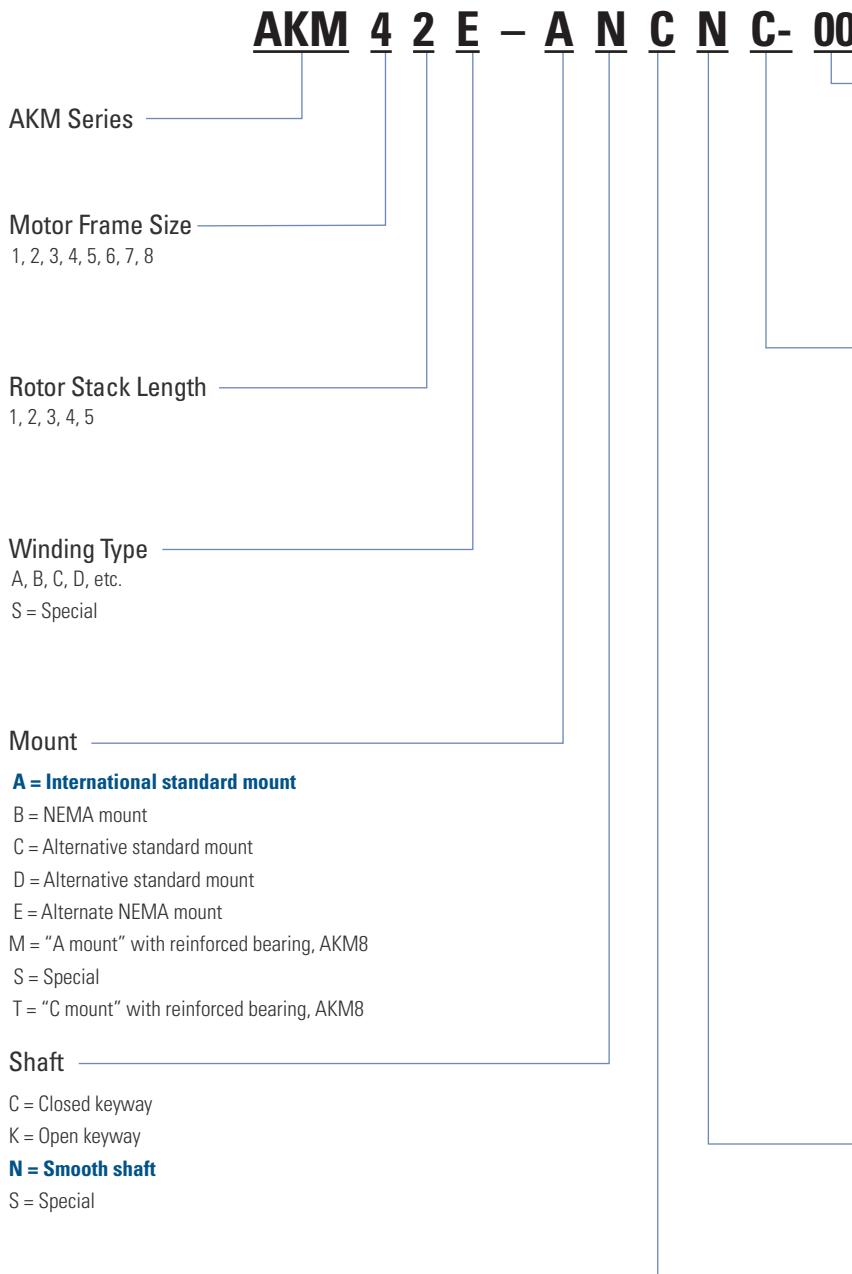


Connector Part Number: Molex 39-01-3103 (Eng No. 5559-10P1)

Pin	Function	Color	
1	SFD +5V	Red	Power Shield Connected to Motor Ground Internal to Motor
‡	SFD +5V RTN	Black	Feedback Shield is Not Connected at Motor End
3	Power Shield		
4	Ground	Grn/Yel	
5	U	Blue	
6	SFD COM-	Yellow	
7	SFD COM+	Blue	
8	SFD COM Shield		
9	V	Brown	
10	W	Violet	

Model Nomenclature

AKM Brushless Servomotor



Customization/Seal

00 = Standard motor without shaft seal

01 = Standard motor with Teflon shaft seal
HG = Standard motor with Viton spring lip shaft seal

OF = Food grade

OW = Washdown

Other numbers will be assigned for special motors.

Feedback Device

1- = 1024 PPR digital encoder with commutation (AKM1-7)

2- = 2048 PPR digital encoder with commutation (AKM1-7)

C- = Smart Feedback Device (SFD) (available across family)

R = Resolver

AA = BiSS single-turn absolute (AKM2-8)

AB = BiSS multi-turn absolute (AKM2-8)

DA = Single-turn absolute sine encoder (EnDat2.2, 01) (AKM2-8)

DB = Multi-turn absolute sine encoder (EnDat2.2, 01) (AKM2-8)

ED = 500 PPR digital encoder w/ commutation (AKM2-7)

EE = 1000 PPR digital encoder w/ commutation (AKM2-7)

EF = 2000 PPR digital encoder w/ commutation (AKM2-7)

EG = 2500 PPR digital encoder w/ commutation (AKM2-7)

EM = 4096 PPR digital encoder w/ commutation (AKM2-7)

EH = 5000 PPR digital encoder w/ commutation (AKM2-7)

EN = 8192 PPR digital encoder w/ commutation (AKM 5, 6, 7 models only)

EJ = 10000 PPR digital encoder w/ commutation (AKM 5, 6, 7 models only)

LA = Inductive single-turn (AKM2-7)

LB = Inductive multi-turn absolute (AKM2-7)

Brake

2 = 24 Vdc brake (AKM2-8)

N = No brake

S = Special

Connectors

B = Dual motor-mounted rotatable IP65 connectors (AKM2 only)

C = 0.5 m shielded cables with IP65 connectors (AKM1, 2), motor-mounted rotatable IP65 connectors (AKM3-7)

D = Single angular connector (AKM2, 3, 4)

G = Straight motor-mounted IP65 connectors (AKM2-7)

H = Motor-mounted IP65 power connector size 1.5 (AKM74Q & AKM82 only)

M = 0.5 m shielded cable w/ IP20 connector (AKM1, 2, 3, 4 models, less than 6 amps)

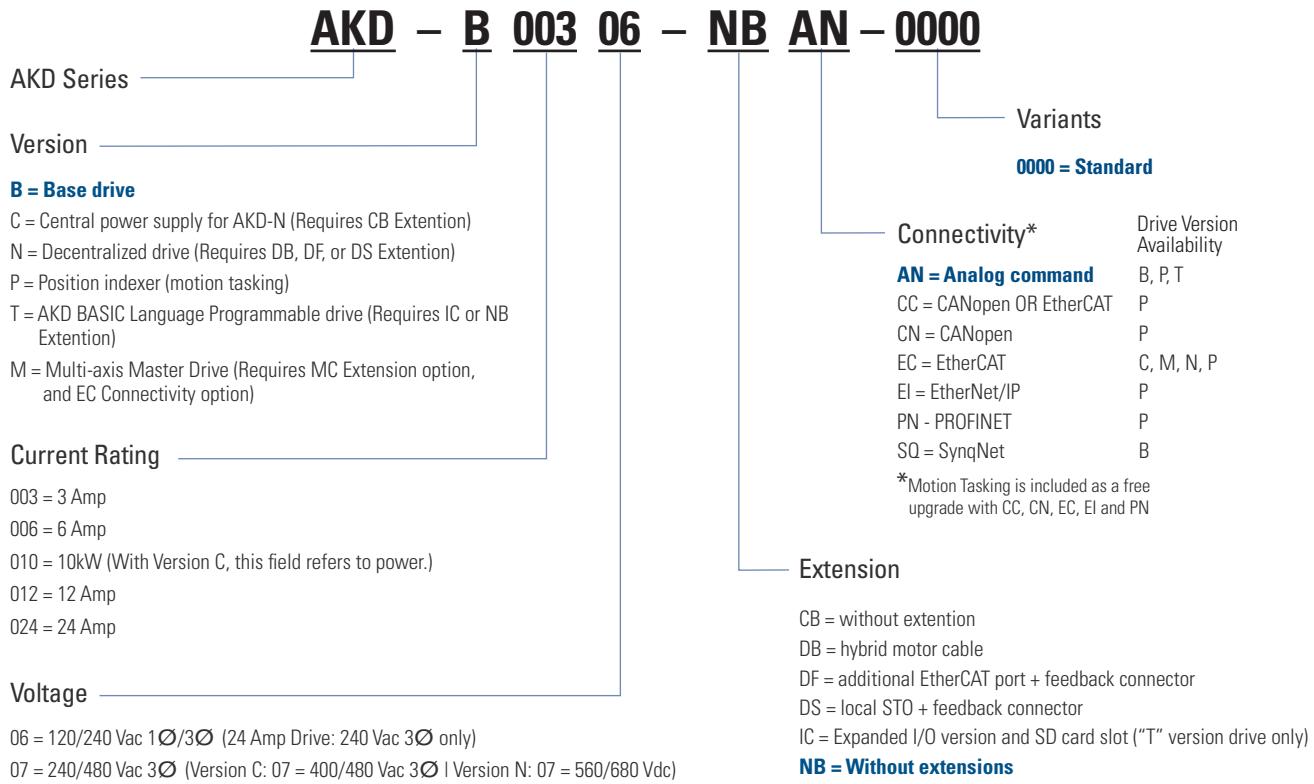
P = 0.5 m shielded cable w/ single IP20 connector (AKM1, 2, 3, 4 models with SFD and no brake, less than 6 amps)

S = Special

T = Terminal box for power and feedback connector size 1.0 (AKM8 only)

Model Nomenclature

AKD Servo Drive



Note: Options shown in bold blue text are considered standard.

S700 Servo Drive**S7 48 0 2 – NA – NA – NA**

S700 Series

Current Rating

- 01 = 1.5 Arms
- 03 = 3 Arms
- 06 = 6 Arms
- 12 = 12 Arms
- 24 = 24 Arms
- 48 = 48 Arms
- 72 = 72 Arms

Voltage Rating

0 = 208...480 Vac

6 = 110...230 Vac (with 1.5 to 24 Arms only)

Electrical Options

2 = Standard

Expansion Card Slot 3

**NA = No Expansion card in Slot 3
EtherCAT and CANopen on board**

F2 = Fan controller
 PM = Post/O
 PA = Post/O-Monitor
 S1 = Safety card SIL 3
 S2 = Safety card SIL 2

Expansion Card Slot 2

**NA = No Expansion card in Slot 2
EtherCAT and CANopen on board**

F2 = Fan controller
 PM = Post/O
 PA = Post/O-Monitor

Expansion card F2 in Slot 2 can be used combined with a card in Slot 1.

Expansion Card Slot 1

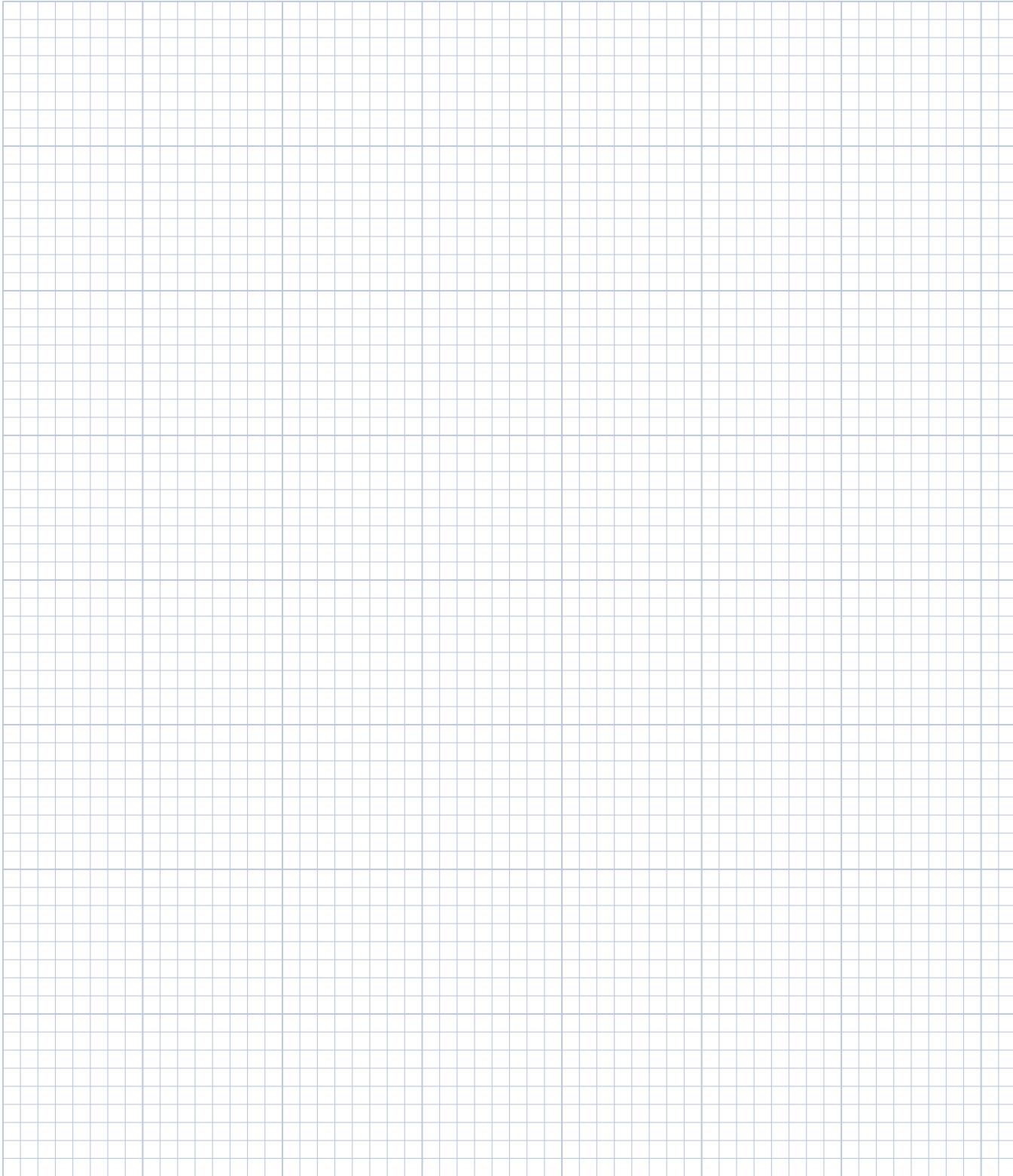
**NA = No expansion card in Slot 1,
EtherCAT and CANopen on board**

DN = DEVICENET
 PB = PROFIBUS
 SE = SERCOS
 SN = SYNQNET
 EI = I/O extension

Expansion card F2 in Slot 2 can be used combined with a card in Slot 1.

Note: Options shown in bold blue text are considered standard.

Notes



MOTIONEERING® Application Engine

To help select and size Kollmorgen components, this Windows®-based motor-sizing program takes a systems approach to the selection of brushless DC servomotors, stepper motors and drives. MOTIONEERING application engine, available at www.kollmorgen.com, uses a project concept for the collection and saving of rotary and linear multi-axis load information. This provides the user the flexibility to sum the effects of multiple axes of motion for power supply and shunt regeneration sizing.

A wide variety of linear and rotary mechanisms are provided including lead screw, rack and pinion, conveyor, nip rolls, cylinder, rotary, and direct data-entry using unique sizing algorithms and product databases criteria.

The searchable database consists of hundreds of systems on product combinations including rotary housed and frameless brushless servomotors, direct drive rotary and linear brushless servomotors, linear actuators (electric cylinders, rodless actuators, and precision tables) and stepper systems.

The MOTIONEERING application engine also provides versatile units-of-measure selection options for mechanism and motion profile data-entry, with the ability to convert data into other available units. Online Help explains program functions and the definition of terms and equations used in the program.

Features

- Group multiple mechanisms within a “project” – organize and combine data for power supply and regeneration sizing
- Types of mechanisms for analysis include lead screw, rack and pinion, conveyor, nip rolls, rotary and direct drive linear motor
- Motion profile options include simple triangle, 1/3-1/3-1/3 trapezoidal, variable traverse trapezoidal, and more
- Search results display shows color highlighted solution set of options for easy evaluation of system specifications and selection

Supported Operating Systems

- Microsoft® Windows 2000, XP, Vista, Windows 7

MOTIONEERING 6.4.0 includes

- **NEW** AKMH series Stainless Steel Motors and AKD systems at 120, 240, 400 and 480 V
- Designed to meet IP69K, EHEDG, 3A, and built with FDA approved food grade materials
- 19 frame/stack length combinations
- Continuous torque to 22 Nm
- Peak torque to 92 Nm
- Corrected length dimensions of some AKM servomotor & gearmotor models
- Corrected CH132 thermal resistance
- Added HIPERFACE DSL sine encoder to search field

Note: Performance curves included for all servomotor systems

