

QPhase™ Encoders

QM35 EZ-COMM

DESIGN FEATURES

- Programmable commutation
- Full complement outputs
- Bearingless modular design
- Low profile assembled height of 0.43"
- Resolutions up to 5000 lines per revolution
- 4, 6, 8, 10 or 14 pole commutation3
- Easy lock-n-twist assembly feature
- Through bore sizes up to 0.375" diameter
- Up to 675 kHz frequency response
- High noise immunity
- RoHS construction
- Hub to shaft uses two #3-48 set screws
- Hermetically sealed LED
- Multiple mounting options including resolver size 15



The Quantum Devices EZ-Comm system is the fastest and most economical way to align an optical encoder's commutation channels to a motor. EZ-Comm was designed to reduce assembly cost for high volume manufacturing. By eliminating multiple steps from the typical timing of an encoder and motor, EZ-Comm saves manufacturing time and reduces assembly cost. EZ-Comm is integrated into the high performance, low profile modular design of the QM35. QM35 EZ-Comm is ideal for high volume OEM applications and priced competitively for all sizes of motion control projects. As simple as a push of a button, EZ-Comm is the newest and simplest way to commutate your BLDC motors.



Configuration Options:

Resolution

Please refer to available line count and pole combinations below

Commutation Please refer to available line count and pole combinations below

Output

D = Line Driver with EZ-Comm Line Driver (ABZ)

/ Open Collector (UVW) with

Cover

A = Hole in Cover B = Closed Cover (shaft < 0.512)

C = Closed Cover (shaft < 0.450"

Bore Size C = 5 mm

D = 6 mm E = 8 mm K = 0.1875L = 0.250M = 0.3125

N = 0.375"

Mounting

A = 1.280" B = 1.812"

Index

A = 90° A & B High B = 90° A & B Low

Hardware Please refer

to hardware options on page 7

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Available Line Count and Pole Combinations

Line Count

- 500, 512, 1000, 1024, 2000, 2048, 2500 6
 - 500, 512, 1000, 1024, 2000, 2048, 2500, 4000, 4096
- 8 500, 512, 1000, 1024, 2000, 2048, 2500, 4000, 4096, 5000 10 500, 512, 1000, 1024, 2000, 2048, 2500, 4000, 4096, 5000

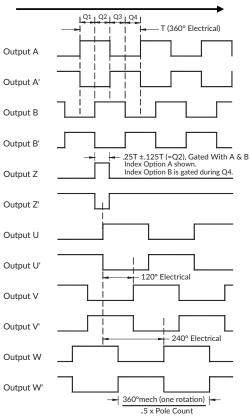
- 1.) 4 poles has four states per revolution (2 pole pair), or two 360° electrical cycles per revolution
- 2.) Mounting option A allows for resolver size 15
- 3.) Consult factory for configurations not shown
- 4.) Line Driver (RS-422) is compatible with Renco options: TTL, PP, VC or LD

Open collector compatible with VO configurations



OUTPUT WAVEFORMS

CCW Shaft Rotation as Viewed Looking at the Encoder Top



 $\begin{array}{l} Q1+Q2=0.5T\pm0.125T \\ Q2+Q3=0.5T\pm0.125T \\ Qn=0.25T\pm0.125T \ (n=1,\,2,\,3,\,4) \end{array}$

ELECTRICAL SPECIFICATIONS			
Input Voltage	5 VDC ± 5%		
Input Current Requirements	65 mA typical, 100 mA max plus interface loads		
Input Ripple	2% peak to peak @ 5 VDC		
Output Circuits	D = 26C31 line driver (RS-422 or single-ended TTL) E = ABZ 26C31 line driver, UVW open collector (no U' V' W')		
Incremental Output Format	Quadrature with A leading B for CCW rotation viewed from the encoder top		
Max Operating Frequency	• < 5000 PPR = 500 kHz or 15,000 RPM • 5000 PPR = 675 kHz • 1000LC-10P, 1024LC-10P, 2000LC-10P, 2048-10P and 2048LC-14P = 7000 RPM		
Commutation Format	Three phase 4, 6, 8, 10 or 14 poles (other pole counts upon request)		
Commutation Accuracy (UVW)	See EZ-Comm Specifications		
Interpolation Factors	1000/1024 PPR = 2x 2000/2048 PPR = 4x 2500 PPR = 5x 4000/4096 PPR = 8x 5000 PPR = 10x		

ENVIRONMENTAL SPECIFICATIONS					
Storage Temperature	-40 to 125°C				
Operating Temperature	-30 to 115°C				
IP Rating	IP40				
Humidity	90% non-condensing				
Vibration	20 g's @ 25 to 2,000 Hz				
Shock	100 g's @ 6 ms duration				

MECHANICAL SPECIFICATIONS					
Bore Minimum Diameter	Bore size +0.0002"				
Recommended Shaft Tolerance	+0.0000/-0.0005"				
Minimum Shaft Engagement	0.400" [10.2 mm]				
Allowable Shaft Runout	0.002" [0.05 mm] TIR (\pm 0.001" shaft radial play from initial shaft position of assembled encoder)				
Allowable Axial Shaft Movement	± 0.010" [± 0.25 mm]				
Mounting	A = 1.280" bolt circle/size 15 resolver, B = 1.812" bolt circle				
Dynamic Commutation Adjustment Range	30° mechanical				
Moment of Inertia	8.0 x 10 ⁻⁶ oz·in·s ²				



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ELECTRICAL PIN FUNCTIONS							
	Electrical Option						
Pin Number	Option D	Option E					
1	A	Α					
2	A'	A'					
3	В	В					
4	B'	B'					
5	Z	Z					
6	Z'	Z'					
7	U	U					
8	U'	NC					
9	V	V					
10	V'	NC					
11	W	W					
12	W'	NC					
13	Vcc	Vcc					
14	GND	GND					
1.5	NC	NC					

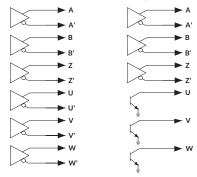
ELECTRICAL OUTPUT CIRCUITS

Output Option D: Output Option E:

ABZ = 26C31 line driver (RS-422)

UVW = 26C31 line driver (RS-422)

UVW = open collector



- 26C31 line driver is TTL compatible (can be wired single-ended)
 26C31 sink/source 20mA max (meets RS-422 at 5 VDC supply)
 Open collector 30 mA sink max
 Open collector pull up voltage 30 VDC max

EZ-COMM SPECIFICATIONS									
Encoder Commutation Accuracy after Alignment Process	, , , , , , , , , , , , , , , , , , , ,								
	U V W edge	UVW edge position error (max), after first Index after Power On:							
	Line Count	4 Pole	6 Pole	8 Pole	10 Pole	14 Pole			
	500	1.0° e	2.4° e	3.4° e	3.8° e				
	512	1.0° e	2.8° e	3.4° e	5.2° e				
	1000	1.0° e	2.4° e	3.4° e	2.8° e				
	1024	1.0° e	2.8° e	3.4° e	3.2° e				
	2000	1.0° e	2.4° e	3.4° e	2.8° e				
	2048	1.0° e	2.8° e	3.4° e	3.2° e	4.5° e			
	2500	1.0° e	2.1° e	3.2° e	3.4° e				
	4000		2.0° e	2.6° e	2.8° e				
	4096		2.0° e	2.6° e	2.7° e				
	5000			2.5° e	2.9° e				
	Note: Accuracy specification does not include motor winding pole pair pos magnetizing inaccuracies.								
Power on Latency	Power on to valid UVW states: 22 ms								



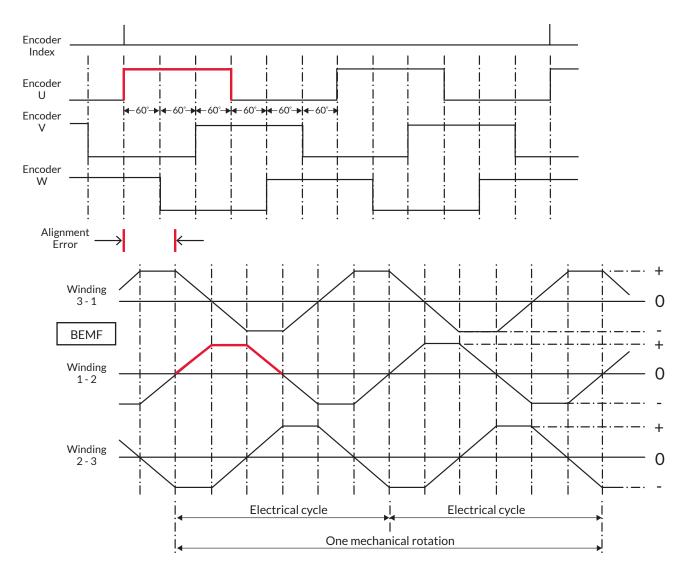




EZ-COMM PROGRAMMABLE COMMUTATION ALIGNMENT

BEFORE ALIGNMENT PROCESS

The waveforms below are the QM35 EZ-Comm encoder Index (Z), U, V, and W phases in relation to the motor back electro motive force (BEMF) phases, prior to any alignment process. The red segments indicate the desired states to be aligned.

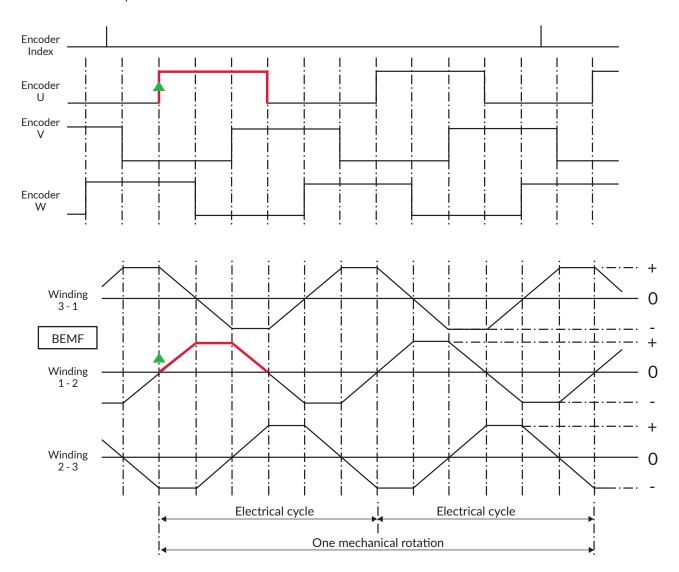




EZ-COMM PROGRAMMABLE COMMUTATION ALIGNMENT

AFTER ALIGNMENT PROCESS

The waveforms below are the QM35 EZ-Comm encoder Index (Z), U, V, and W phases in relation to the motor back electro motive force (BEMF) phases, after the Semi-Automatic Commutator Alignment. The green arrow indicates motor shaft position where the alignment process occurred. The U, V, and W phases are aligned to the BEMF phases of the motor. The index marks are not repositioned.



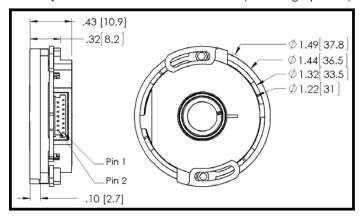
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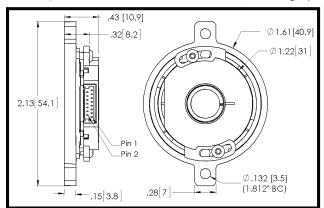
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Model QM35 EZ-Comm - 1.280" Bolt Circle (Mounting Option A)



Model QM35 EZ-Comm - 1.812" Bolt Circle (Mounting Option B)

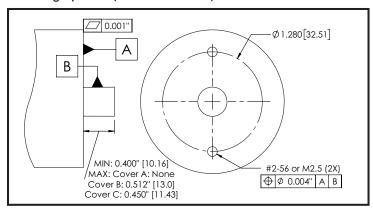


Note:

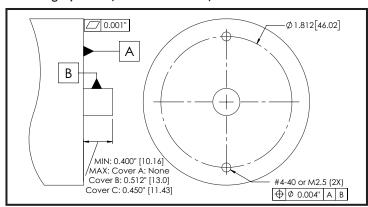
- Shown with Cover option A (hole in cover).
- Cover option B (closed) Maximum shaft length up to 0.512" [13.0 mm]. Overall height increases from 0.43" [10.9 mm] to 0.57" [14.5 mm]. This additional height has a cylinder diameter 0.56" [14.2 mm], centered on the cover top.
- Cover option C (closed) Maximum shaft length up to 0.450" [11.4 mm]. Overall height increases from 0.43" [10.9 mm] to 0.51" [13.0 mm]. This additional height has a cylinder diameter 0.56" [14.2 mm], centered on the cover top.

MOUNTING REQUIREMENTS

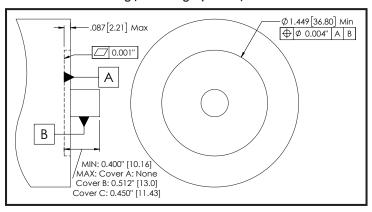
Mounting Option A (1.280" Bolt Circle)



Mounting Option B (1.812" Bolt Circle)



Servo Size 15 Mounting (Mounting Option A)



Patent Protection:

- US Patent 9,857,205
- US Patent 6,563,108

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SELECTION CHARTS

MOUNTING OPTION A (1.280" BOLT CIRCLE)							
1/16	#3-48 x 1/2 set screw req	16" Set Screw uried for 0.375			t screw has o	/32" Set Screv deeper hex po embly tool life	ocket to
Mountir	ng Screws	Mounting Screws with Thread Lock		Mountin	g Screws		Screws with ad Lock
English	Metric	English Metric		English	Metric	English	Metric
Option A	Option B	Option D	Option E	Option F	Option G	Option H	Option J

	MOUNTING OPTION B (1.812" BOLT CIRCLE)								
1/16		16" Set Screw uried for 0.375			#3-48 x 3/ et screw has o improve asse		ocket to		
Mountir	ng Screws	Mounting Screws with Thread Lock		Mountin	g Screws		Screws with ad Lock		
English	Metric	English	Metric	English	Metric	English	Metric		
Option K	Option L	Option M	Option N	Option P	Option Q	Option R	Option S		

- 1.) Bore Size option N (0.375") requires Hardware option A, B, D, E, K, L, M or N. This hardware can optionally be used with all other hub sizes.
- 2.) Hardware options F, G, H, J, P, Q, R and S have longer #3-48 set screws (3/32") and are not compatible with Bore Size option N (0.375").
- 3.) Hardware options D, E, H, J, M, N, R and S contain a thread lock which is applied to the mounting screws only. This preapplied thread locking product contains a microencapsulated epoxy resin that is suspended in a hardener. The force of thread engagement crushes the microscopic $capsules \ of \ epoxy \ resin, \ mixing \ the \ reactant \ components, \ and \ initiating \ a \ chemical \ reaction \ which \ locks \ the \ parts \ together. \ This \ product \ series$ provides consistent and predictable torque values and requires no heat or primers for curing. Product - ND Industries 593S.

HARDWARE SELECTION BREAKOUT

	Option A	Option B	Option D	Option E	Option F	Option G	Option H	Option J
Set Screws (Qty. 2 each)	Black Ox #3-48 x 1/16" 0.050" Hex (Torque = 18 - 22 oz-in) Part Number 1829ZG014	Black Ox #3-48 x 1/16" 0.050" Hex (Torque = 18 - 22 oz·in) Part Number 1829ZG014	Black Ox #3-48 x 1/16" 0.050" Hex (Torque = 18 - 22 oz-in) Part Number 1829ZG014	Black Ox #3-48 x 1/16" 0.050" Hex (Torque = 18 - 22 oz-in) Part Number 1829ZG014	Black Ox #3-48 x 3/32" 0.050" Hex (Torque = 28 - 32 oz·in) Part Number 1829ZG015	Black Ox #3-48 x 3/32" 0.050" Hex (Torque = 28 - 32 oz-in) Part Number 1829ZG015	Black Ox #3-48 x 3/32" 0.050" Hex (Torque = 28 - 32 oz·in) Part Number 1829ZG015	Black Ox #3-48 x 3/32" 0.050" Hex (Torque = 28 - 32 oz·in) Part Number 1829ZG015
Mounting Screws (Qty. 2 each)	#2-56 x 1/4" Button Head, 0.050" Hex (Torque = 45 - 51 oz·in) Part Number 1834ZG002	M 2.5 x 6 mm Button Head (max dia. 4.5 mm) 1.5 mm Hex (Torque = 45 to 51 oz·in) Part Number 1834ZG050	#2-56 x 1/4" Button Head, 0.050" Hex w ith thread lock (Torque = 45 - 51 oz-in) Part Number 1834A G102	M 2.5 x 6 mm Button Head (max dia. 4.5 mm) 1.5 mm Hex w ith thread lock (Torque = 45 - 51 oz·in) Part Number 1834AG150	#2-56 x 1/4" Button Head, 0.050" Hex (Torque = 45 - 51 oz·in) Part Number 1834ZG002	M 2.5 x 6 mm Button Head (max dia. 4.5 mm) 1.5 mm Hex (Torque = 45 - 51 oz·in) Part Number 1834ZG050	#2-56 x 1/4" Button Head, 0.050" Hex w ith thread lock (Torque = 45 - 51 oz·in) Part Number 1834AG102	M 2.5 x 6 mm Button Head (max dia. 4.5 mm) 1.5 mm Hex w ith thread lock (Torque = 45 - 51 oz-in) Part Number 1834AG150
Cover Screws (Qty. 2 each)	Plastite 48-2, thread 2-28, length 1/4", Torx Plus IP7 (Torque = 37 - 43 oz·in) Part Number 1826ZG002	Plastite 48-2, thread 2-28, length 1/4", Torx Plus IP7 (Torque = 37 - 43 oz-in) Part Number 1826ZG002	Plastite 48-2, thread 2-28, length 1/4", Torx Plus IP7 (Torque = 37 - 43 oz·in) Part Number 1826ZG002	Plastite 48-2, thread 2-28, length 1/4", Torx Plus IP7 (Torque = 37 - 43 oz·in) Part Number 1826ZG002	Plastite 48-2, thread 2-28, length 1/4", Torx Plus IP7 (Torque = 37 - 43 oz-in) Part Number 1826ZG002	Plastite 48-2, thread 2-28, length 1/4", Torx Plus IP7 (Torque = 37 - 43 oz-in) Part Number 1826ZG002	Plastite 48-2, thread 2-28, length 1/4", Torx Plus IP7 (Torque = 37 - 43 oz-in) Part Number 1826ZG002	Plastite 48-2, thread 2-28, length 1/4", Torx Plus IP7 (Torque = 37 - 43 oz·in) Part Number 1826ZG002
ĺ	Option K	Option L	Option M	Option N	Option P	Option Q	Option R	Option S

	Option K	Option L	Option M	Option N	Option P	Option Q	Option R	Option S
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Mounting Screws (Qty. 2 each)	#4-40 x 5/16" Button Head, 0.062" Hex (Torque = 45 - 51 oz·in) Part Number 1835ZG004	M 2.5 x 8 mm Button Head, 1.5 mm Hex (Torque = 45 - 51 oz·in) Part Number 1834ZG051	#4-40 x 5/16" Button Head, 0.062" Hex w ith thread lock (Torque = 45 - 51 oz·in) Part Number 1835ZG104		#4-40 x 5/16" Button Head, 0.062" Hex (Torque = 45 - 51 oz·in) Part Number 1835ZG004	M 2.5 x 8 mm Button Head, 1.5 mm Hex (Torque = 45 - 51 oz·in) Part Number 1834ZG051	#4-40 x 5/16" Button Head, 0.062" Hex w ith thread lock (Torque = 45 - 51 oz·in) Part Number 1835ZG104	M 2.5 x 8 mm Button Head, 1.5 mm Hex w ith thread lock (Torque = 45 - 51 oz·in) Part Number 1834AG151
Cover Screws (Qty. 2 each)	Plastite 48-2, thread 2-28, length 1/4", Torx Plus IP7 (Torque = 37 - 43 oz-in) Part Number 1826ZG002	Plastite 48-2, thread 2-28, length 1/4", Torx Plus IP7 (Torque = 37 - 43 oz-in) Part Number 1826ZG002	Plastite 48-2, thread 2-28, length 1/4", Torx Plus IP7 (Torque = 37 - 43 oz-in) Part Number 1826ZG002	Plastite 48-2, thread 2-28, length 1/4", Torx Plus IP7 (Torque = 37 - 43 oz·in) Part Number 1826ZG002	Plastite 48-2, thread 2-28, length 1/4", Torx Plus IP7 (Torque = 37 - 43 oz-in) Part Number 1826ZG002	Plastite 48-2, thread 2-28, length 1/4", Torx Plus IP7 (Torque = 37 - 43 oz-in) Part Number 1826ZG002	Plastite 48-2, thread 2-28, length 1/4", Torx Plus IP7 (Torque = 37 - 43 oz-in) Part Number 1826ZG002	Plastite 48-2, thread 2-28, length 1/4", Torx Plus IP7 (Torque = 37 - 43 oz·in) Part Number 1826ZG002

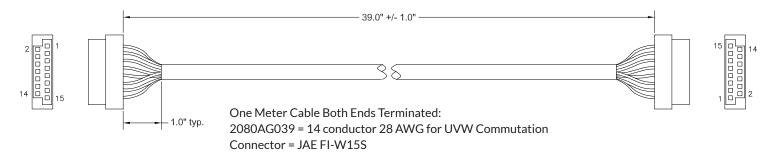
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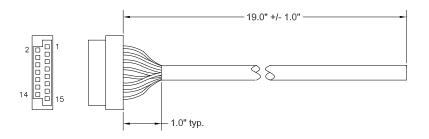


CABLE ACCESSORIES

(2080AG039, 2081AG019)

Consult Factory for Custom Lengths





Half Meter Cable One End Terminated: 2081AG019 = 114 conductor 28 AWG for UVW Commutation Connector = JAE FI-W15S

Pin Number	Encoder Pin Function	2080AG039 2081AG019 Wire Color
1	Α	Brown
2	A'	White
3	В	Blue
4	B'	Green
5	Z	Orange
6	Z'	Yellow
7	U	Violet
8	U'	Gray
9	V	White/Brown
10	V'	White/Red
11	W	White/Orange
12	W'	White/Yellow
13	Vcc	Red
14	GND	Black
15	No Connect	-

- Note:
 1. Cable has internal foil shield with 28 AWG drain wire trimmed to jacket edge
- 2. Unused wires to be locally isolated from adjacent signal wires, Vcc and GND to prevent damage to encoder signals





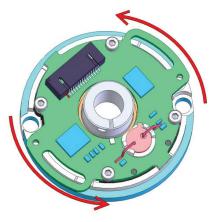
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INSTALLATION INSTRUCTIONS FOR 1.280" BOLT CIRCLE

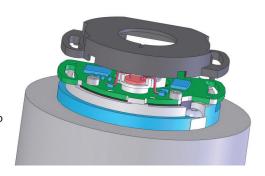
STEP 1

Rotate printed circuit board (PCB) to expose the mounting holes. This is the Lock position. Mounting/ motor surface must be clean and flat.



STEP 5

Place cover on encoder. Observe the cover dowel pins positioned into mating PCB holes.

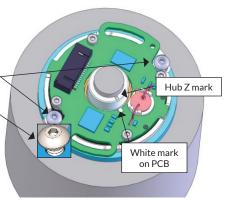


STEP 2

A. Install mounting screws through encoder into mounting/motor surface. Insert 1-2 turns.

DO NOT tighten screws.

Note: Alignment of Z mark on hub to white mark on PCB is NOT required.

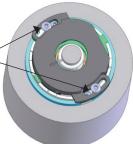


STEP 6

A. Twist cover/ PCB to expose screw holes for cover screws.



B. Install cover screws and tighten to 37-43 oz·in.



C. Install cable to complete installation.



STEP 3

A. Press down on the hub with a force between $150 \, \mathrm{g}$ (0.33 lb) and $700 \, \mathrm{g}$ (1.5 lb). This will center the encoder assembly to the motor shaft.

B. Using slight forefinger and thumb force, verify no radial (side-to-side) movement of the encoder occurs.

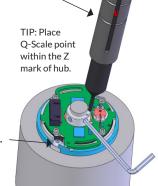
Illustrated is accessory Q-Scale p/n 2160AG276. Proper downward force is indicated when pin is between the force lines.



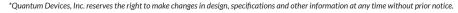
A. Tighten hub set screws to motor shaft. #3-48 x 1/16" screw = 18-22 oz·in #3-48 x 3/32" screw = 28-32 oz·in

B. The downward force on the hub can be removed.

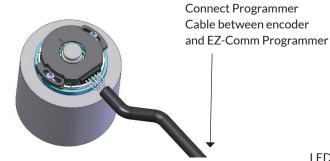
C. Tighten mounting screws to 45-51 oz·in.



Note: Refer to Hardware Selection Breakout chart for driver sizes.



QM35 EZ-COMM SET UP:



Includes:

- EZ-Comm Programmer
- 19" Programmer Cable p/n: 2174AG002
- 9VDC, 6W Power Supply

Switch Power ON

EZ-COMM PROGRAMMER INDICATORS

LED1 Flashing: Rotate Shaft to Align Commutation. **LED1 Steady:** Commutation Alignment Complete.

LED2 Flashing: Rotate Shaft to Verify Installation. **LED2 Steady:** Encoder Installation is Good.

LED3 Flashing: Error (repeat installation).

LED4 Steady: Encoder has Power.



Plug power supply cube into 110 VAC supply. Connect +9v DC power plug into socket.

EZ-COMM ALIGNMENT PROCEDURE

- A. Energize appropriate motor windings to align shaft to U rise position.
- B. Press button to Start Alignment process.
 - LED 1 will flash.
 - LED 4 will illuminate, indicating power applied to encoder.
- C. Remove power from motor windings applied in step A.
- D. Rotate motor shaft (~one rotation) to align commutation.
 - LED 1 will light steady when align is complete.
 - LED 2 will flash.
- E. Rotate motor shaft (~one rotation) to verify installation.
 - LED 2 will light steady when installation verification is complete.
 - LED 4 will extinguish removing power from encoder.

For multiple alignments, the power switch on the box side can remain in the ON position.

Rotational speed limited to 350RPM.

PROGRAMMER PINOUT

- Pin 1 = Encoder power
- Pin 2 = Ground
- Pin 3 = Chan U
- Pin 4 = Chan V
- Pin 5 = Chan W

REMOTE/AUTOMATED CONNECTION

- Pin 7 = Input Open Collector ground and release to Start Alignment process, alignment procedure step B.
- Pin 8 = Output TTL logic High during alignment procedure steps B, C and D.
- Pin 15 = Output TTL logic High during alignment procedure step E.
- Pin 14 = Output TTL logic High upon complete of step E to signal the installation was verified (passing).
- Pin 13 = Output TTL High if an installation error occurs.

Repeat next assembly: First ground and release of Pin 7 to clear Pass or Fail from the previous alignment.

Sold & Serviced By:



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