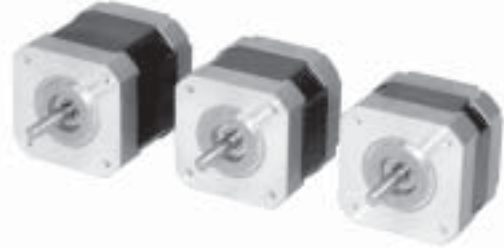
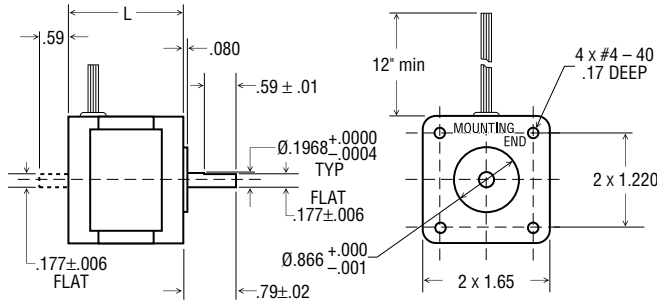


Hybrid Step Motors

SIZE
HT
17



Part #	MOTOR CONNECTION 1 = series 2 = parallel 3 = unipolar	Motor Length (inches)	Minimum Holding Torque (oz-in)	Leads	Step Angle					Rotor Inertia (oz-in ² /G-CM ²)	Motor Weight (Lbs.)
						Volts	Amps	Ohms	mH		
HT17-068	1	1.3	31.4	8	1.8	5.7	.67	8.4	11.2	.190/35.0	.44
	2	↓	31.4	↓	↓	2.8	1.34	2.1	2.8	↓	↓
	3	↓	22.2	↓	↓	4.0	0.95	4.2	2.8	↓	↓
HT17-069	1	↓	31.4	↓	↓	13.6	0.28	48.0	60.0	↓	↓
	2	↓	31.4	↓	↓	6.8	0.57	12.0	15.0	↓	↓
	3	↓	22.2	↓	↓	9.6	0.40	24.0	15.0	↓	↓
HT17-070	1	↓	31.4	↓	↓	17.5	0.22	80.0	88.0	↓	↓
	2	↓	31.4	↓	↓	8.8	0.44	20.0	22.0	↓	↓
	3	↓	22.2	↓	↓	12.4	0.31	40.0	22.0	↓	↓
HT17-071	1	1.54	51.0	↓	↓	5.7	0.85	6.6	14.4	.29/54.0	.57
	2	↓	51.0	↓	↓	2.8	1.70	1.7	3.6	↓	↓
	3	↓	36.1	↓	↓	4.0	1.20	3.3	3.6	↓	↓
HT17-072	1	↓	51.0	↓	↓	9.0	0.57	16.0	30.4	↓	↓
	2	↓	51.0	↓	↓	4.5	1.13	4.0	7.6	↓	↓
	3	↓	36.1	↓	↓	6.4	0.80	8.0	7.6	↓	↓

OTHER LENGTHS AND WINDINGS AVAILABLE UPON REQUEST

- Part numbers listed are for single shaft. To order double shaft add 'D' to the end.
- All HT17 motors are optimized for microstepping.

Sold & Serviced By:



Toll Free Phone (877) SERV098

Toll Free Fax (877) SERV099

www.electromate.com
sales@electromate.com

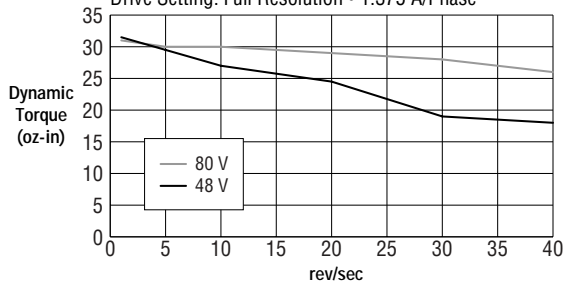
Size HT17 Motor

Typical Speed/Torque Performance*

HT17-068 MOTOR

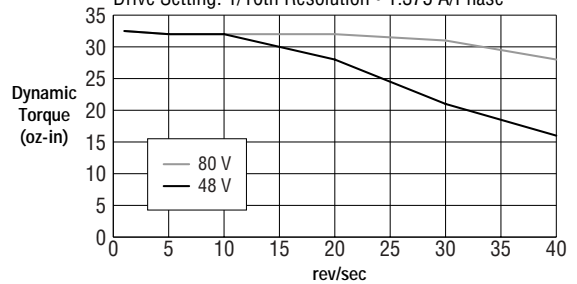
Motor Connection: Parallel

Drive Setting: Full Resolution • 1.375 A/Phase


HT17-068 MOTOR

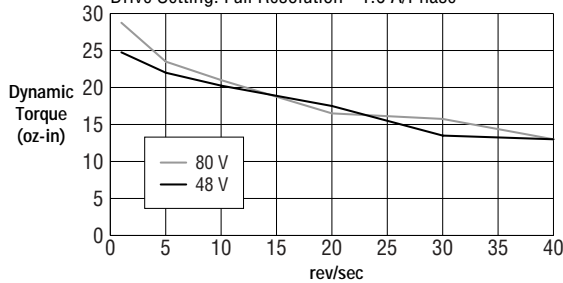
Motor Connection: Parallel

Drive Setting: 1/10th Resolution • 1.375 A/Phase


HT17-071 MOTOR

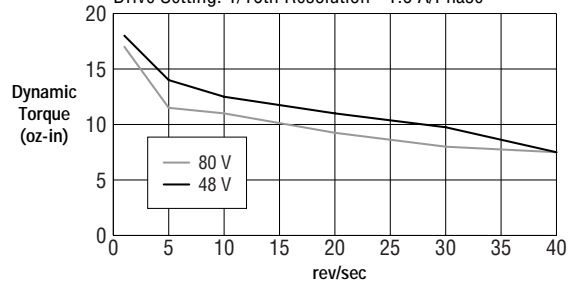
Motor Connection: Parallel

Drive Setting: Full Resolution • 1.0 A/Phase


HT17-071 MOTOR

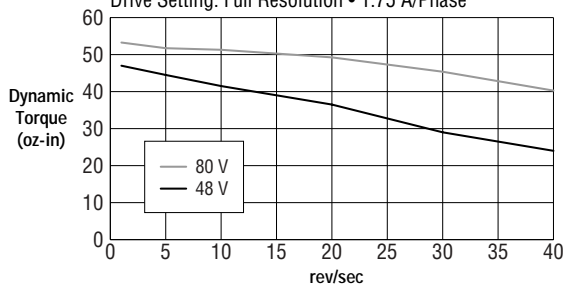
Motor Connection: Parallel

Drive Setting: 1/10th Resolution • 1.0 A/Phase


HT17-075 MOTOR

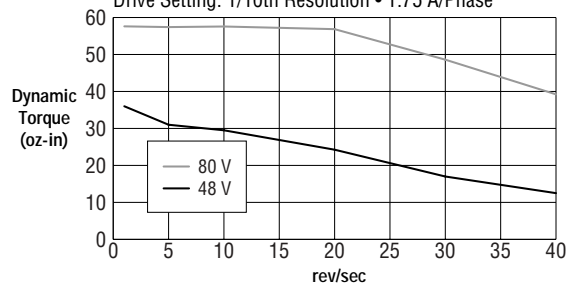
Motor Connection: Parallel

Drive Setting: Full Resolution • 1.75 A/Phase


HT17-075 MOTOR

Motor Connection: Parallel

Drive Setting: 1/10th Resolution • 1.75 A/Phase



Sold & Serviced By:



Toll Free Phone (877) SERV098

Toll Free Fax (877) SERV099

www.electromate.com
sales@electromate.com

*Full steps/rev = Rev/sec x 200.