

FXM060-10-RM

FlexPro® Series

Product Status: Active

SPECIFICATIONS

Current Peak 20 A
Current Continuous 10 A

DC Supply Voltage
Network Communication

10 – 55 VDC
CANopen



The **FXM060-10-RM** is an Extended Environment single-axis servo drive and integration board assembly for a FXE060-10-RM FlexPro® series servo drive with IMPACTTM architecture. Connections to the controller, motor, power, and feedback are simplified through the standard connectors featured on the board.

The **FXM060-10-RM** offers full tuning control of all servo loops and is designed to drive brushed and brushless servo motors, stepper motors, and AC induction motors. The drive accepts a variety of external command signals, or can use the built-in Motion Engine, an internal motion controller used with Sequencing and Indexing commands. Programmable digital and analog I/O are included to enhance interfacing with external controllers and devices.

The **FXM060-10-RM** utilizes RS485/232 network communication and is configured via USB. All drive and motor parameters are stored in non-volatile memory.

IMPACT™ (Integrated Motion Platform And Control Technology) combines exceptional processing capability and high-current components to create powerful, compact, feature-loaded servo solutions. IMPACT™ is used in all FlexPro® drives and is available in custom products as well.

The **FXM060-10-RM** conforms to the following specifications and is designed to the Environmental Engineering Considerations as defined in MIL-STD-810F.

EXTENDED ENVIRONMENT PERFORMANCE

Ambient Operating Temperature Range -40°C to +95°C (-40°F to +203°F)

Thermal Shock -40°C to +95°C (-40°F to +203°F) within 3 min.

Relative Humidity

Vibration

Altitude

Contaminants

0 to 95%, Non-Condensing
25 Grms for 5 min. in 3 axes
-400m to +25000m
Pollution Degree 2

Comaminani

FEATURES

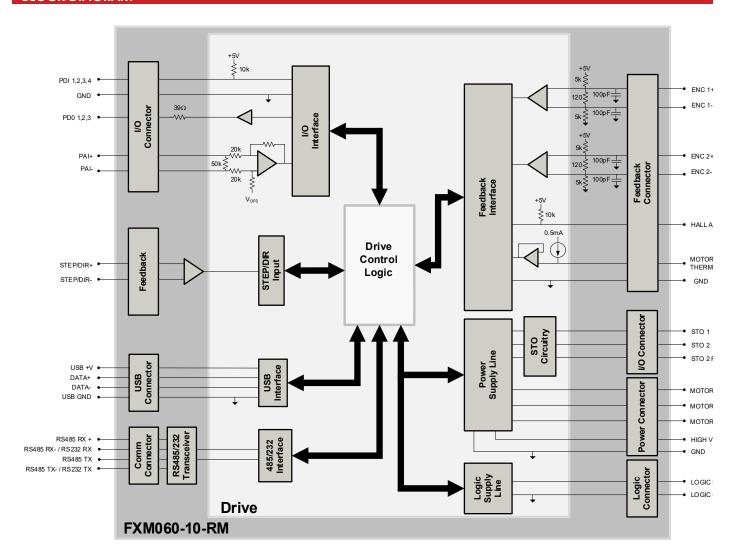
- Standard Connections for Easy Setup
- Four Quadrant Regenerative Operation
- Programmable Gain Settings
- PIDF Velocity Loop

- On-the-Fly Mode Switching
- On-the-Fly Gain Set Switching
- Dedicated Safe Torque Off (STO) Inputs
- Bridge Status, Fault and Network Status LEDs
- I/O Status LEDs

Feedback Supported	o ramagawa/rakon	Motors Supported	Three PhaseSingle PhaseStepperAC Induction	Modes of Operation	CurrentVelocityPosition
Command Sources	- indoxing	Inputs / Outputs	 4 Programmable Digital Inputs 3 Programmable Digital Outputs 1 Programmable Analog Input 	Agency Approvals	 RoHS MIL-STD-810F (as stated) MIL-STD-1275D (optional) MIL-STD-461E (optional) MIL-STD-704F (optional) MIL-HDBK-217 (optional)



BLOCK DIAGRAM



INFORMATION ON APPROVALS AND COMPLIANCES

The RoHS Directive restricts the use of certain substances including lead, mercury, cadmium, hexavalent chromium and halogenated flame retardants PBB and PBDE in electronic equipment.

MIL-STD-810F Environmental Engineering Considerations and Laboratory Tests – (as stated)
MIL-STD-1275D Characteristics of 28 Volt DC Electrical Systems in Military Vehicles – (optional)

MIL-STD-461E Requirements for the Control of Electromagnetic Interference Characteristics of Subsystems and

Equipment – (optional)

MIL-STD-704F

Aircraft Electric Power Characteristics – (optional)

MIL-HDBK-217 Reliability Prediction of Electronic Equipment (MTBF) – (optional)

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SPECIFICATIONS

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	Electric	al Specifications
Description	Units	Value
Nominal DC Supply Input Range	VDC	12 – 48
DC Supply Input Range	VDC	10 – 55
DC Supply Undervoltage	VDC	8
DC Supply Overvoltage	VDC	58
Logic Supply Input Range (optional)	VDC	10 – 55
Safe Torque Off Voltage (Default)	VDC	5
Maximum Peak Current Output ¹	A (Arms)	20 (14.1)
Maximum Continuous Current Output ²	A (Arms)	10 (10)
Bus Capacitance ³	μF	52.8
Efficiency at Rated Power	%	99
Maximum Continuous Output Power	W	545
Maximum Power Dissipation at Continuous Current	W	6
Minimum Load Inductance (line-to-line) ⁴	μН	150 (@ 48VDC supply); 75 (@24VDC supply); 40 (@12VDC supply)
Switching Frequency	kHz	20
Maximum Output PWM Duty Cycle	%	83
Maximom Golport WW Bory Cycle		ol Specifications
Description	Units	Value
Communication Interfaces	-	RS485/232 (USB for configuration)
Commonication interaces	+ -	±10 V Analog, Over the Network, Sequencing, Indexing, Jogging, Step &
Command Sources	-	Direction, Encoder Following
		Absolute Encoder (BiSS C-Mode, EnDat 2.2, Tamagawa/Nikon), Incremental
Feedback Supported	-	Encoder, Hall Sensors, Auxiliary Incremental Encoder, Tachometer (±10V)
Commutation Methods	-	Sinusoidal, Trapezoidal
Modes of Operation	-	Current, Velocity, Position
		Three Phase (Brushless Servo), Single Phase (Brushed Servo, Voice Coil, Inductive
Motors Supported ⁵	-	Load), Stepper (2- or 3-Phase Closed Loop), AC Induction (Closed Loop Vector)
Head and Doctoria		40+ Configurable Functions, Over Current, Over Temperature (Drive & Motor),
Hardware Protection	-	Over Voltage, Short Circuit (Phase-Phase & Phase-Ground), Under Voltage
Programmable Digital Inputs/Outputs	-	4/3
Programmable Analog Inputs/Outputs	-	1/0
Primary I/O Logic Level	-	5 VDC, not isolated
Current Loop Sample Time	μS	50
Velocity Loop Sample Time	μS	100
Position Loop Sample Time	μS	100
Maximum Encoder Frequency	MHz	20 (5 pre-quadrature)
	Mechani	cal Specifications
Description	Units	Value
Size (H x W x D)	mm (in)	50.8 x 25.4 x 22.0 (2.00 x 1.00 x 0.86)
Weight	g (oz)	34 (1.2)
Ambient Operating Temperature Range ⁶	°C (°F)	-40 – 95 (-40 – 203)
Storage Temperature Range	°C (°F)	-50 - 100 (-58 - 212)
Thermal Shock	°C (°F)	-40 – 95 (-40 – 203) within 3 min
Relative Humidity	-	0-95%, non-condensing
Vibration	Grms	25 for 5 minutes in 3 axes
Altitude	m	-400 - 25000
Contaminants	-	Pollution Degree 2
P1 COMMUNICATION CONNECTOR	-	6-pin, 1.0mm spaced single row vertical header
P2 USB CONNECTOR	-	USB Type C, vertical entry
P3 IO and LOGIC CONNECTOR	<u> </u>	20-pin, 1.0mm spaced dual row vertical header
P4 FEEDBACK CONNECTOR	-	30-pin, 1.0mm spaced dual row vertical header
P5 POWER CONNECTOR	+ -	2-port, 3.5mm spaced address vertical entry screw terminal
P6 MOTOR POWER CONNECTOR	+ -	3-port, 3.5mm spaced vertical entry screw terminal
Notes		To posity district operation of the position o

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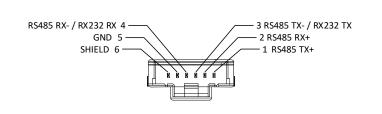
- 1. Capable of supplying drive rated peak current for 2 seconds with 5 second foldback to continuous value. Longer times are possible with lower current limits.
- Continuous A_{rms} value attainable when RMS Charge-Based Limiting is used.
 Applications with a supply voltage higher than 30VDC require a minimum external decoupling capacitance of 470μF / 100V added across HV and POWER GND.
 Lower inductance is acceptable for bus voltages well below maximum. Use external inductance to meet requirements.
- 5. Maximum motor speed for stepper motors is 600 RPM. Consult the hardware installation manual for 2-phase stepper wiring configuration.
- 6. Additional cooling and/or heatsink may be required to achieve rated performance.



PIN FUNCTIONS

P1 – Communication Connector				
Pin	Name	Description / Notes	I/O	
1	RS485 TX+	Transmit Line (RS485)	I/O	
2	RS485 RX+	Receive Line (RS485)		
3	RS485 TX- / RS232 TX	Transmit Line (RS485 or RS232)		
4 RS485 RX- / RS232 RX Receive Line (RS485 or RS232)			I/O	
5	GND	ND Ground		
6	SHIELD	CAN shield	-	
	0111223	o in to head		

Connector Information	6-pin, 1.0mm spaced single row vertical header	
Mating Connector Details	Molex: 5013300600	
Mating Connector Included	No	



	P2 – USB Connector						
Pin No	ame	Description / Notes	I/O				
Connector Information	USB Type C port						
Mating Connector Details	Standard Type C USB connection cable						
Mating Connector Included No							

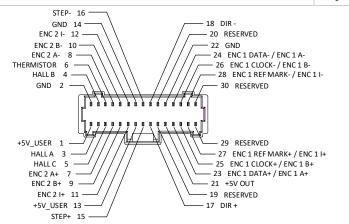
Pin	Nar	me Description / Notes	I/O
1	PDI-1	General Purpose Programmable Digital Input	I
2	PDI-2	General Purpose Programmable Digital Input	1
3	PDI-3	General Purpose Programmable Digital Input	1
4	PDI-4	General Purpose Programmable Digital Input	1
5	PDO-1	General Purpose Programmable Digital Output (TTL/8mA)	0
6	PDO-2	General Purpose Programmable Digital Output (TTL/8mA)	0
7	PDO-3	General Purpose Programmable Digital Output (TTL/8mA)	0
8	GND	Ground.	GND
9	+5V_USER	+5V Supply Output. Short-circuit protected. (300ma total load capacity shared between P3-9, P4-1, P4-13, and P4-21)	0
10	GND	Ground.	GND
11	PAI-1+	General Purpose Differential Programmable Analog Input or Reference Signal Input.	1
12	PAI-1-	±10VDC Range (12-bit Resolution)	I
13	STO-1 INPUT	Safe Torque Off – Input 1	1
14	STO RETURN	Safe Torque Off Return	STORET
15	STO-2 INPUT	Safe Torque Off – Input 2	1
16	STO RETURN	Safe Torque Off Return	STORET
17	RESERVED / NC	Reserved.	-
18	GND	Ground.	GND
19	LOGIC PWR	Logic Supply Input (10 – 55VDC) (optional)	1
20	LOGIC GND	Ground	GND

20 LOGIC GND	Ground	GND
Connector Information	20-pin, 1.0mm spaced dual row vertical header	GND 10 12 PAI-1- GND 8 14 STO RETURN PDO-2 6 16 TO RETURN PDI-4 4 18 GND PDI-2 2 1 LOGIC GND
Mating Connector Details	Molex: 501892010	
Mating Connector Included	No	PDI-1 1



			P4 – Feedback Connector	
Pin	Absolute Encoder	Incremental Encoder	Description / Notes	I/O
1	+5V_USER	+5V_USER	+5V Supply Output. Short-circuit protected.	0
•			(300ma total load capacity shared between P3-9, P4-1, P4-13, and P4-21)	
2	GND	GND	Ground.	GND
3	HALL A	HALL A		
4	HALL B	HALL B	Single-ended Commutation Sensor Inputs.	<u> </u>
5	HALL C	HALL C		<u> </u>
6	THERMISTOR	THERMISTOR	Motor Thermal Protection.	<u> </u>
7	ENC 2 A+	ENC 2 A+	Differential Incremental Encoder A.	1
8	ENC 2 A-	ENC 2 A-		<u> </u>
9	ENC 2 B+	ENC 2 B+	Differential Incremental Encoder B.	1
10	ENC 2 B-	ENC 2 B-		I
11	ENC 2 I+	ENC 2 I+	Differential Incremental Encoder Index.	1
12	ENC 2 I-	ENC 2 I-	Differential incremental Encoder Index.	I
13	+5V_USER	+5V_USER	+5V Supply Output. Short-circuit protected. (300ma total load capacity shared between P3-9, P4-1, P4-13, and P4-21)	0
14	GND	GND	Ground.	GND
15	STEP +	STEP +	Differential Step Input.	1
16	STEP -	STEP -	billelerilidi step iripot.	1
17	DIR +	DIR +	Differential Direction Input.	
18	DIR -	DIR -	Dillerential Direction inpot.	1
19	RESERVED	RESERVED	Reserved.	-
20	RESERVED	RESERVED		-
21	+5V_USER	+5V_USER	+5V Supply Output. Short-circuit protected. (300ma total load capacity shared between P3-9, P4-1, P4-13, and P4-21)	0
22	GND	GND	Ground.	GND
23	ENC 1 DATA+	ENC 1 A+	Differential Data Line for Absolute Encoders (BiSS: SLO+/-) or Differential Incremental	1
24	ENC 1 DATA-	ENC 1 A-	Encoder A.	
25	ENC 1 CLOCK+	ENC 1 B+	Differential Clock Line for Absolute Encoders (BiSS: MA+/-) or Differential Incremental	
26	ENC 1 CLOCK-	ENC 1 B-	Encoder B.	
27	ENC 1 REF MARK+	ENC 1 I+	Differential Reference Mark for Absolute Encoders (Leave open for BiSS and EnDat 2.2)	
28	ENC 1 REF MARK-	ENC 1 I-	or Differential Incremental Encoder Index.	I
29	RESERVED	RESERVED	Reserved.	
30	RESERVED	RESERVED	Reserved.	-
Con	nnector Information	30-pin, 1.0mm spaced du header	STEP- 16 GND 14 ENC 2 I- 12 ENC 2 B- 10 ENC 2 A- 8 THERMISTOR 6 HALL B 4 GND 2 GND 2 GND 2 A ENC 1 CLOCK- / ENC 1 B- 30 RESERVED 30 RESERVED	3-
Mating Connector Details		Molex: 5011893010		

Mating Connector Included No



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	P5 - Power Connector					
Pin Name				Description / Notes	I/O	
			DC Supply Input. Applications with a supply voltage higher than 30VDC require a minimum external decoupling capacitance of 470µF / 100V added across HV and POWER GND.		I	
2	2 POWER GND Ground.				GND	
Conr	Connector Information 2-port 3.5mm sparterminal		ced vertical entry screw	POWER GROUND 2————————————————————————————————————		
Mating	Mating Connector Details N/A					
Mating	Mating Connector Included N/A					

	P6 — Motor Power Connector					
Pin	No	ame		Description / Notes	I/O	
1	MOTOR A		Motor Phase A.		0	
2	2 MOTOR B		Motor Phase B.		0	
3	MOTOR C		Motor Phase C.		0	
Con	nector Information	3-port 3.5mm spaced vertical entry screw terminal		MOTOR C 3 ——————————————————————————————————		
Matin	g Connector Details	N/A				
Mating	Connector Included	N/A				

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BOARD CONFIGURATION

Status LED Functions

LED	Description
STAT	Indicates drive power bridge status. GREEN when DC bus power is applied and the drive is enabled. RED when the drive is in a fault state.
LOGIC PWR	Indicates that +5V logic power is available to the drive. GREEN when +5V logic power is available.

Switch Settings

The RS485/232 drive address and baud rate are set using DIP Switch SW1. Switch settings are given in the below table.

SW1	Description	On	Off			
1	Bit 0 of binary RS485/232 address.					
2	Bit 1 of binary RS485/232 address.	the address stored in NVM. Default setting is NVM address.				
3	Bit 2 of binary RS485/232 address.					
4	RS485/RS232 Select	RS485	RS232 (default)			
5	Baud Rate	115.2k	Set via software (default)			
6	RS485 2-wire / 4-wire Select					
7	RS485 2-wire / 4-wire Select	2-wire 4-wire (default)				
8	Network Termination	Terminated	Not Terminated (default)			

Safe Torque Off (STO) Inputs

The Safe Torque Off (STO) inputs are dedicated +5VDC sinking single-ended inputs. For applications not using STO functionality, disabling of the STO feature is required for proper drive operation. STO may be disabled by following the STO Disable wiring instructions as given in the hardware installation manual.

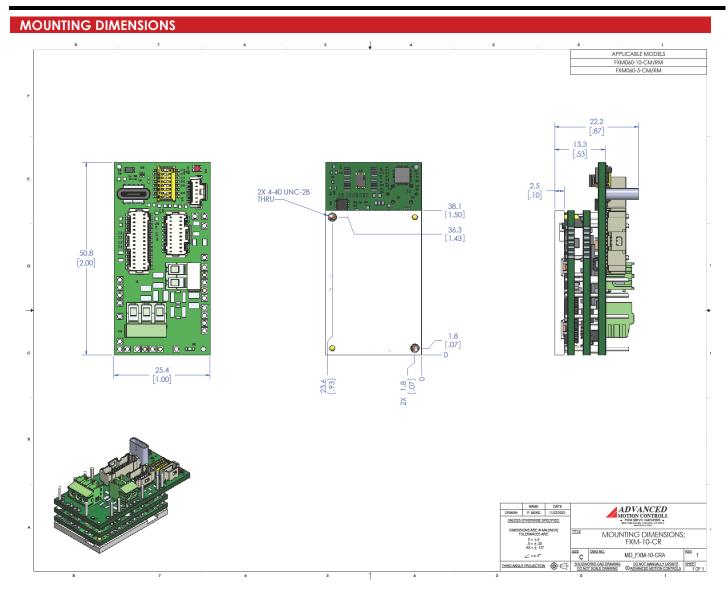
Mating Connector Kit

Mating connector housing and crimp contacts can be ordered as a kit using ADVANCED Motion Controls' part number KC-MC1XFMCR01. This includes mating connector housing and crimp style contacts for the Communication, I/O and Logic, and Feedback connectors. The recommended tool for crimping the contacts is Molex PN: 63819-1500 (not included with the kit). Pre-crimped leads (Molex PN: 797581018) are also available for purchase from many inline component vendors.

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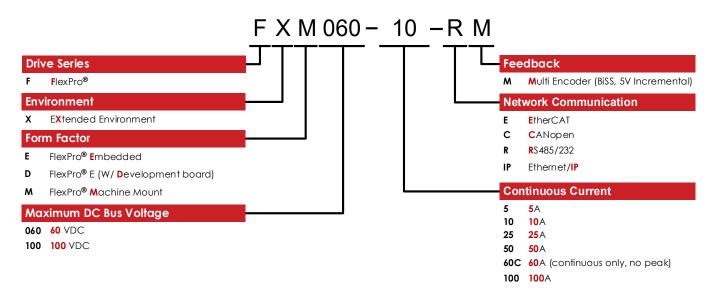


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PART NUMBERING AND CUSTOMIZATION INFORMATION



ADVANCED Motion Controls also has the capability to promptly develop and deliver specified products for OEMs with volume requests. Our Applications and Engineering Departments will work closely with your design team through all stages of development in order to provide the best servo drive solution for your system. Equipped with on-site manufacturing for quick-turn customs capabilities, ADVANCED Motion Controls utilizes our years of engineering and manufacturing expertise to decrease your costs and time-to-market while increasing system quality and reliability.

Examples of Customized Products

- Optimized Footprint
- OEM Specified Connectors
- No Outer Case
- ▲ Increased Current Resolution
- ▲ Increased Temperature Range
- Custom Control Interface
- Integrated System I/O

- Tailored Project File
- Silkscreen Branding
- Optimized Base Plate
- ▲ Increased Current Limits
- ▲ Increased Voltage Range
- Conformal Coating
- ▲ Multi-Axis Configurations
- Reduced Profile Size and Weight

Feel free to contact us for further information and details!

Available Accessories

ADVANCED Motion Controls offers a variety of accessories designed to facilitate drive integration into a servo system. Visit www.a-m-c.com to see which accessories will assist with your application design and implementation.

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